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Supplement of

The role of snow cover affecting boreal-arctic soil freeze–thaw and carbon dynamics

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- 1 Table S1 The 20 FLUXNET eddy-covariance (EC) tower sites within the pan-Arctic basin and
- 2 Alaska domain used for model validation.

¹ Site	Lat, Lon	² Biome type	Observation period
US-Bn1	63.92°N, 145.38°W	ENF	2003-2003
CA-NS1	55.88°N, 98.48°W	ENF	2003-2004
CA-NS2	55.91°N, 98.52°W	ENF	2002-2004
CA-NS3	55.91°N, 98.38°W	ENF	2002-2004
CA-NS5	55.86°N, 98.48°W	ENF	2002-2004
CA-Ojp	53.92°N, 104.69°W	ENF	2000-2005
CA-SF1	54.49°N, 105.82°W	ENF	2004-2005
CA-SF2	54.25°N, 105.88°W	ENF	2003-2004
CA-Man	55.88°N, 98.48°W	ENF	2000-2003
CA-Obs	53.99°N, 105.12°W	ENF	2000-2005
CA-Qfo	49.69°N, 74.34°W	ENF	2004-2006
RU-Zot	60.80°N, 89.35°W	ENF	2002-2003
US-Bn2	63.92°N, 145.38°W	DBF	2003-2003
CA-Oas	53.63°N, 106.20°W	DBF	2000-2005
CA-WP1	54.95°N, 112.47°W	MXF	2004-2005
CA-Gro	48.22°N, 82.15°W	MXF	2004-2005
RU-Che	68.61°N, 161.34°W	MXF	2003-2003
CA-Let	49.71°N, 112.94°W	GRS	2003-2005
FI-Kaa	69.14°N, 27.30°W	WET	2000-2006
US-Ivo	68.49°N, 155.75°W	Tundra	2004-2006

- 3 ¹FLUXNET Site Identifier;
- 4 ²Dominant biome type within the tower footprint: ENF: evergreen needle-leaf forest; DBF:
- 5 deciduous broadleaf forest; MXF: mixed forest; GRS: grassland; WET: wetland.

- 1 Table S2 The model prescribed fraction (percentage) of leaf, fine root and woody components of
- 2 litterfall for each model biome type based on White et al. (2000).

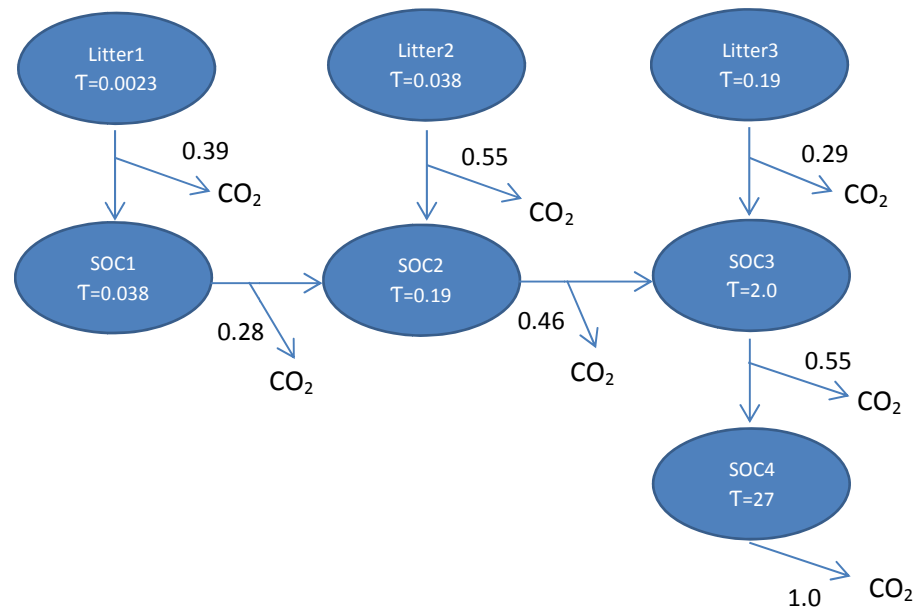
Biome type	Leaf (%)	Fine roots (%)	Wood (%)
Tundra	32	48	20
Forest-tundra	28	42	30
Taiga-boreal	24	36	40
Grasslands/steppe/Shrubland	28	42	30
Wetland	36	54	10
Deciduous/mixed forest	24	36	40

1 Table S3 Prescribed labile, cellulose and lignin fractions (percentage) of leaf, fine root and
2 woody litterfall (White et al. 2000), used to partition model litterfall and relative
3 decomposability in the soil decomposition model.

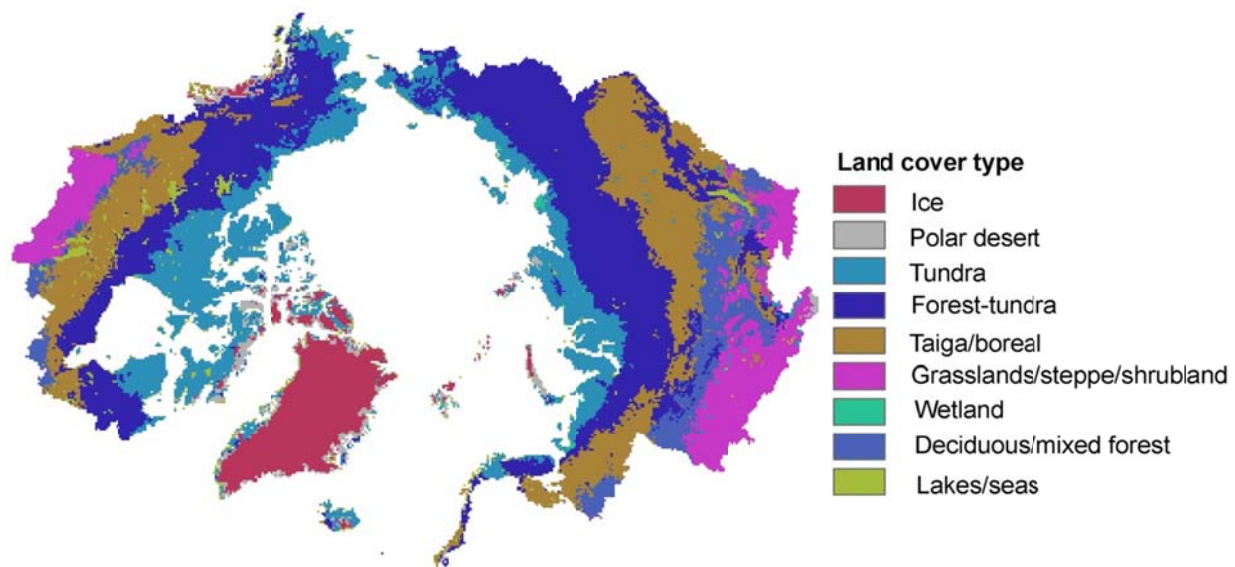
	Labile (%)	Cellulose (%)	Lignin (%)
Leaf	55	31	14
Fine roots	34	44	22
Wood	0	71	29

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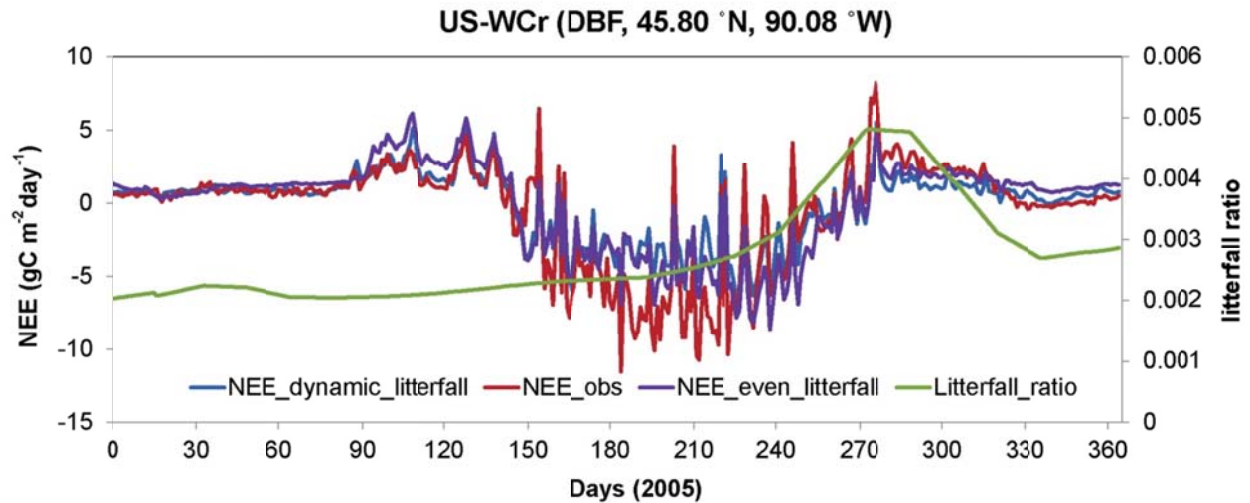
11 Figure S1. The pool structure, transitions, respired fractions (numbers on the arrows) and
12 turnover rates for the soil organic carbon (SOC) decomposition model (numbers in the ellipses,
13 yr⁻¹). The SOC pools include 3 litterfall pools, 3 SOC pools with relatively fast turnover rates
14 (SOC1-3) and a deep SOC pool (SOC4) with relatively slow turnover.



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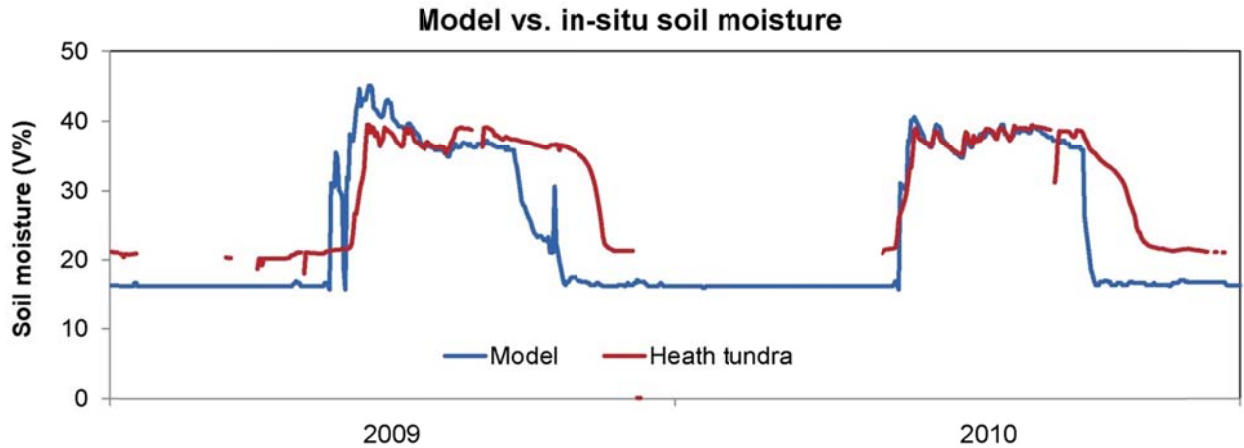
3 Figure S2. The merged land cover map based on the MODIS Collection 5 IGBP land cover and
 4 CAVM classifications. Tundra, forest-tundra and taiga/boreal biomes account for 18.1%, 31.4%
 5 and 20.0% of the pan-Arctic basin and Alaska study area, respectively.



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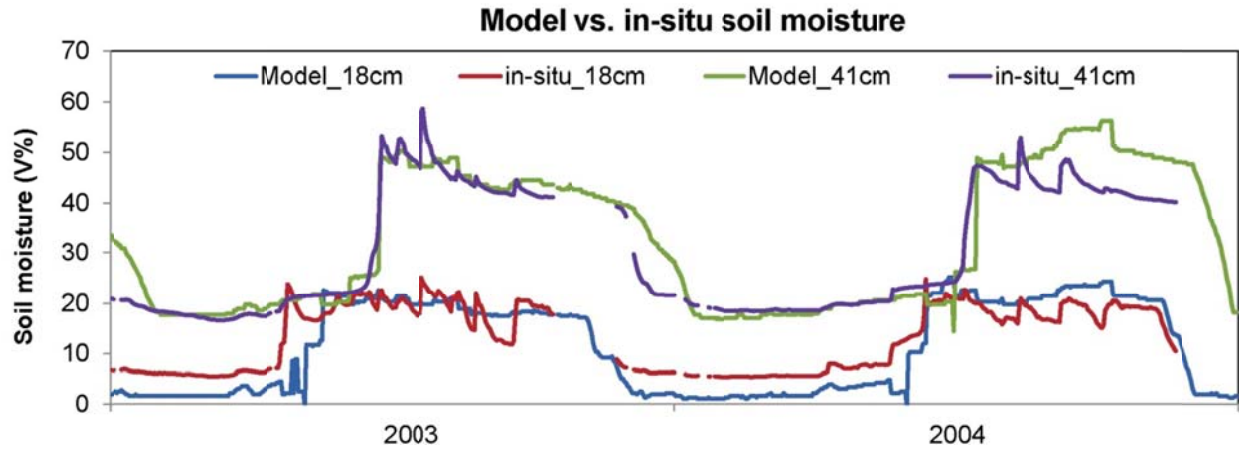
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3 Figure S3. Comparisons of simulated NEE fluxes using dynamical litterfall allocation and evenly
 4 distributed litterfall schemes at a deciduous broadleaf forest (DBF) tower site. The dynamic
 5 litterfall allocation scheme was based on satellite NDVI time series (Appendix A2), and the daily
 6 proportion of annual total litterfall is shown as Litterfall_ratio. NEE_obs indicates the tower EC
 7 observed NEE fluxes, NEE_dynamic_litterfall and NEE_even_litterfall represent model
 8 simulated NEE fluxes using the dynamic litterfall allocation and evenly distributed litterfall
 9 schemes, respectively.



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3 Figure S4. Comparisons of model simulated surface soil moisture (~ 5 cm depth) and in situ
 4 measurements at the Imnavait Creek, AK tundra tower validation site. Only the measurements at
 5 the dry heath tundra site were included due to paucity of soil moisture data at the other two
 6 tundra sites. The year 2008 was not included due to relatively few measurements available at the
 7 dry heath tundra site. Generally, different soil moisture datasets are not directly comparable due
 8 to different statistical moments and systematic bias. Therefore, the modeled and in situ soil
 9 moisture records were scaled to a consistent mean and standard deviation before comparisons
 10 following Koster et al. (2009). Note that the simulated soil moisture during the winter was much
 11 lower than the tower measurements prior to the scaling.



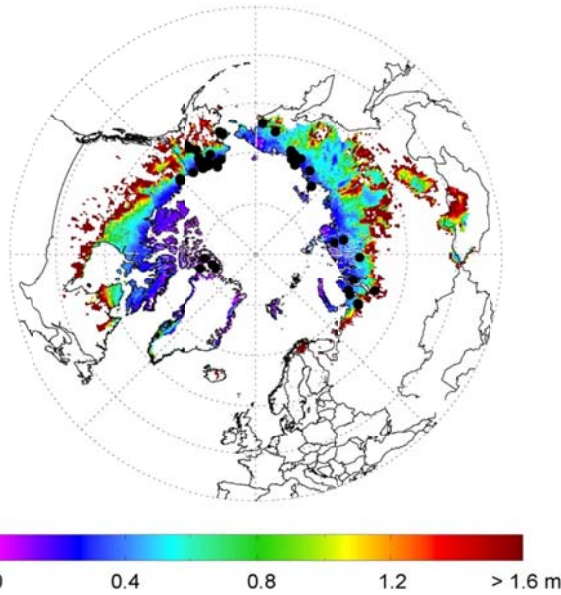
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3 Figure S5. Comparisons of model simulated soil moisture at different depths (18, 41cm) and in
 4 situ measurements at a mature boreal forest site in Manitoba, CAN. The year 2002 was not
 5 included due to relatively few measurements available for that year. Similar as Fig. S4, the
 6 simulated soil moisture was rescaled to match the mean and standard deviation of the in situ soil
 7 moisture data prior to the comparison.

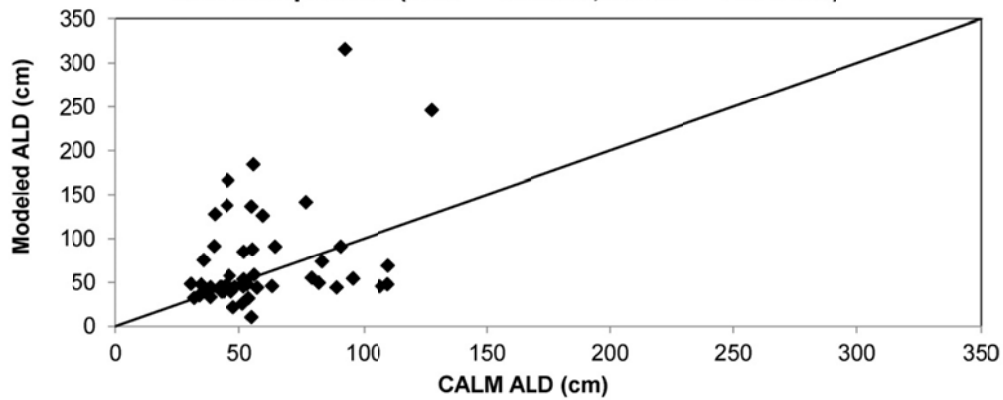
(a)

Distribution of CALM site for validation



(b)

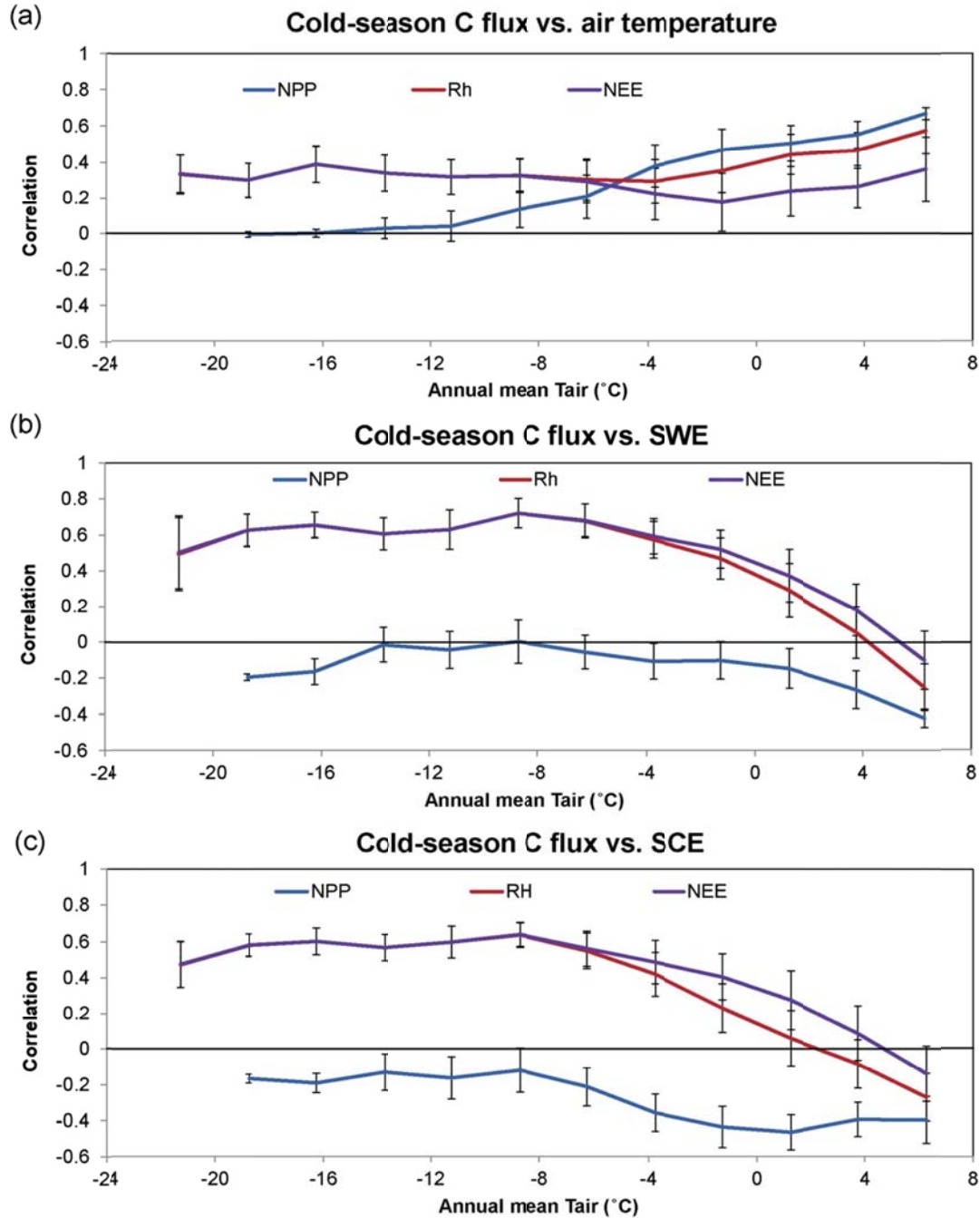
ALD comparison (bias = -9.48cm, RMSE = 44.70 cm)



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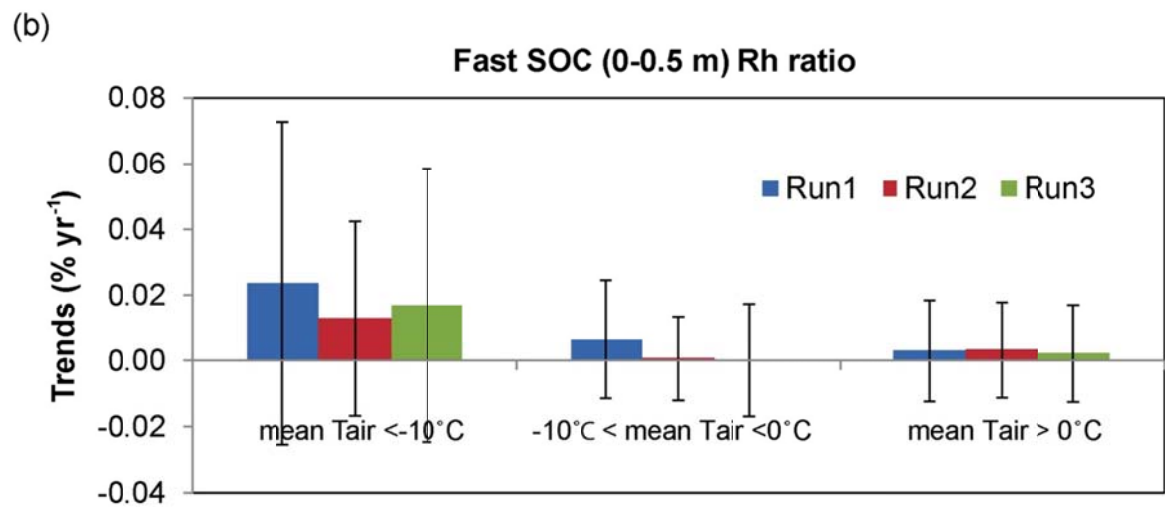
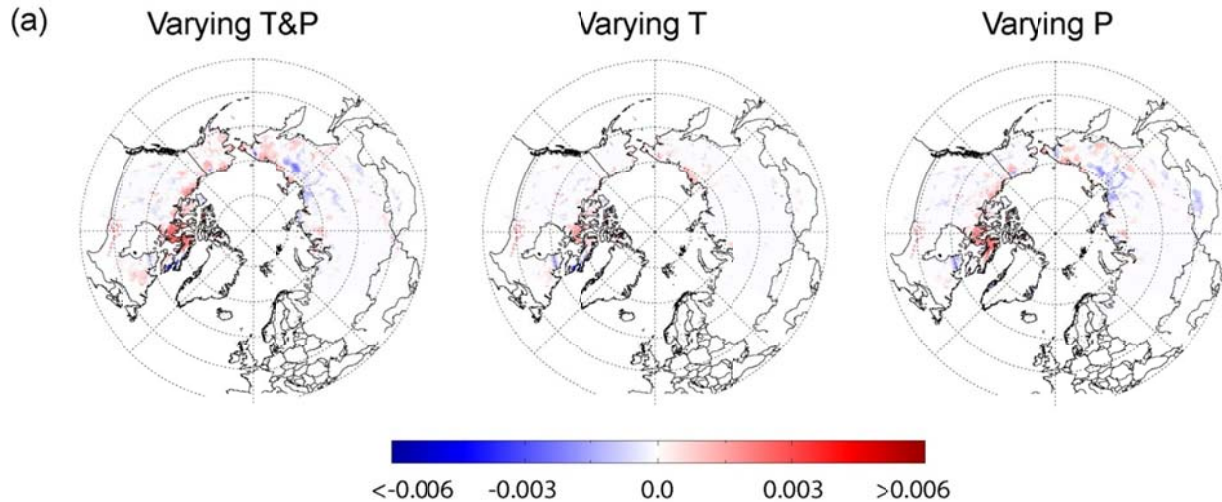
3 Figure S6. (a) Distribution of 53 Circumpolar Active Layer Monitoring (CALM) tundra sites (as
4 indicated by black dots) used for model ALD validation; (b) Comparisons of model simulated
5 ALD versus the CALM observations. The distribution of CALM sites was shown over the model
6 simulated mean (1982-2010) ALD map. The comparisons were made at different periods from
7 1982 to 2010 since CALM observations span different periods.



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3 Figure S7. Correlations between cold-season (from November to April) carbon fluxes and
 4 climate variables (including cold-season air temperature Tair, SWE and SCE). The correlations
 5 were binned into 2.5 °C intervals of annual mean Tair. The standard deviation of correlations
 6 across each climate zone is shown through the error bars.



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3 Figure S8. (a) Simulated temporal trends (unit: yr^{-1}) in the ratio of the warm-season (MJJASO)
 4 Rh contribution from the upper soil ($\leq 0.5\text{m}$) organic carbon (SOC) pool to total Rh for the model
 5 sensitivity analysis runs from 1982 to 2010. The zonal-averages of Rh ratio trends for the
 6 sensitivity analysis are shown in (b). For the sensitivity analysis, the model was driven using
 7 different surface meteorology datasets. Run1 indicates model simulations based on varying T
 8 and P inputs; Run2 indicates model simulations based on varying T inputs alone; and Run3
 9 indicates the model simulations based on varying P inputs alone.

1 **References**

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