



Predicting carbon dioxide and energy fluxes across global FLUXNET sites with regression algorithms

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Abstract. Spatio-temporal fields of land–atmosphere fluxes derived from data-driven models can complement simulations by process-based land surface models. While a number of strategies for empirical models with eddy-covariance flux data have been applied, a systematic intercomparison of these methods has been missing so far. In this study, we performed a cross-validation experiment for predicting carbon dioxide, latent heat, sensible heat and net radiation fluxes across different ecosystem types with 11 machine learning (ML) methods from four different classes (kernel methods, neural networks, tree methods, and regression splines). We applied two complementary setups: (1) 8-day average fluxes based on remotely sensed data and (2) daily mean fluxes based on meteorological data and a mean seasonal cycle of remotely sensed variables. The patterns of predictions from different ML and experimental setups were highly consistent.

There were systematic differences in performance among the fluxes, with the following ascending order: net ecosystem exchange ($R^2 < 0.5$), ecosystem respiration ($R^2 > 0.6$), gross primary production ($R^2 > 0.7$), latent heat ($R^2 > 0.7$), sensible heat ($R^2 > 0.7$), and net radiation ($R^2 > 0.8$). The ML methods predicted the across-site variability and the mean seasonal cycle of the observed fluxes very well ($R^2 > 0.7$), while the 8-day deviations from the mean seasonal cycle were not well predicted ($R^2 < 0.5$). Fluxes were better predicted at forested and temperate climate sites than at sites in extreme climates or less represented by training data (e.g., the tropics). The evaluated large ensemble of ML-based models will be the basis of new global flux products.

1 Introduction

Improving our knowledge of the carbon, water, and energy exchanges between terrestrial ecosystems and the atmosphere is essential to better understand and model the Earth's climate system (IPCC, 2007; Reich, 2010). In situ continuous observations can be obtained with the eddy-covariance technique, which estimates the net exchanges of carbon dioxide (CO₂), water vapor and energy between land ecosystems and the atmosphere (Aubinet et al., 2012; Baldocchi, 2014).

The large-scale measurement network, FLUXNET, integrates site observations of these fluxes globally and provides detailed time series of carbon and energy fluxes across biomes and climates (Baldocchi, 2008). However, eddy-covariance measurements are site-level observations (at < 1 km² scale), and spatial upscaling is required to estimate these fluxes at regional to global scales.

The increasing number of eddy-covariance sites across the globe has encouraged the application of data-driven models by machine learning (ML) methods such as artificial neural networks (ANNs, Papale and Valentini, 2003), random forest (RF, Tramontana et al., 2015), model trees ensemble (MTE, Jung et al., 2009; Xiao et al., 2008, 2010) or support vector regression (SVR, Yang et al., 2006, 2007) to estimate land surface–atmosphere fluxes from site level to regional or global scales (e.g., Beer et al., 2010, Jung et al., 2010, 2011; Kondo et al., 2015; Schwalm et al., 2010, 2012; Yang et al., 2007; Xiao et al., 2008, 2010). The ML upscaled outputs are also increasingly used to evaluate process-based land surface models (e.g., Anav et al., 2013; Bonan et al., 2011; Ichii et al., 2009; Piao et al., 2013).

The key characteristics of data-driven models compared to process-based ones are the former's intrinsic observational nature and the fact that functional relationships are not prescribed, but rather emerge from patterns found in the measurements. In this context, data-driven models extract multivariate functional relationships between the in situ measured fluxes of the network and explanatory variables. These variables are derived from satellite remote sensing, providing useful (although partial) information on vegetation state (e.g., vegetation indices) and other land surface properties (e.g., surface temperature), along with continuous measurements of meteorological variables at flux towers.

While ML-based upscaling provides a systematic approach to move from point-based flux estimates to spatially explicit gridded fields, various sources of uncertainty exist. For example, individual ML methods can have different responses, especially when these models are applied beyond the conditions represented in the training data set (Jung et al., 2009; Papale et al., 2015). The information content of the driving input variables may not be sufficient to capture the variability of the fluxes in all conditions (Tramontana et al., 2015). Moreover, remotely sensed and meteorological gridded data sets are affected by uncertainties themselves. Remote sensing data contain noise, biases and gaps, and can

be perturbed by atmospheric effects or by the presence of snow. Meteorological gridded data sets are known to contain product-specific biases as well (Garnaud et al., 2014; Tramontana et al., 2015; Zhao et al., 2012).

Thorough experiments using multiple data-driven models and explanatory variables are an essential step to identify and assess limitations and sources of uncertainty in the empirical upscaling approach. For this reason several experts in the field gathered together and formed the collaborative FLUXCOM initiative. FLUXCOM aims to better understand the multiple sources and facets of uncertainties in empirical upscaling and, ultimately, to provide an ensemble of machine learning-based global flux products to the scientific community. In FLUXCOM we selected machine learning-based regression tools that span the full range of commonly applied algorithms: from model tree ensembles, multiple adaptive regression splines, artificial neural networks, to kernel methods, with several representatives of each family. We defined common protocols for two complementary upscaling strategies (setups) based on (1) 8-day averaged fluxes based on exclusively remotely sensed data, and (2) daily mean fluxes based on remotely sensed and meteorological data. Different ML approaches were then applied to both setups using the same sets of predictor variables, and a thorough “leave-towers-out” cross-validation was conducted. This study presents the FLUXCOM results obtained from the cross-validation. Our overarching aim was to understand how well fluxes of CO₂ (gross primary production (GPP), terrestrial ecosystem respiration (TER) and net ecosystem exchange (NEE)), and energy (latent heat (LE), sensible heat (*H*) and net radiation (Rn)), as estimated by the eddy-covariance technique, are predicted by an ensemble of ML methods. We focused in particular on the ensemble median prediction because the ensemble median global product will likely be used extensively. At first we looked at the consistency of the patterns between the two experimental setups to understand whether satellite remote sensing is sufficient for mapping carbon and energy fluxes or whether instantaneous meteorological conditions need to be considered explicitly. Second, we investigated which characteristics of the predicted fluxes were robust, analyzing how well the median estimates were able to predict the across-site variability, the mean seasonal cycle by site and interannual variation, i.e., time-dependent deviations from the mean seasonal cycle. Thirdly, we investigated how the ML performance varies among climate zones or ecosystem types.

Table 1. Distribution of flux tower sites across plant functional types (PFTs) and climate zones.

PFT	No. of sites	Climate zone	No. of sites
Evergreen needleleaf forest	66	Temperate	111
Grassland	38	Subtropical–Mediterranean	47
Cropland	27	Boreal	34
Deciduous broadleaf forest	24	Tropical	14
Evergreen broadleaf forest	19	Dry	13
Wetland	17	Arctic	5
Shrubland	12		
Mixed forest	11		
Savannah	10		

2 Material and methods

2.1 Data

2.1.1 Eddy-covariance study sites

We used eddy-covariance data from 224 flux-tower sites (Supplement Sect. S1), which originate from the FLUXNET La Thuile synthesis data set and CarboAfrica network (Valentini et al., 2014). The study sites were distributed globally and cover most plant functional types (PFTs) and biomes over the globe (Table 1).

2.1.2 Observation-based CO₂ and energy fluxes

All flux measurements were post-processed using standardized procedures of quality control (Papale et al., 2006) and gap-filled following Reichstein et al. (2005). Estimates of GPP and TER were derived from half-hourly NEE measurements using two independent flux partitioning methods: (1) according to Reichstein et al. (2005), where the temperature sensitivity of ecosystem respiration was initially estimated from nighttime NEE data and then extrapolated to daytime to estimate TER and GPP. This was done by subtracting NEE (negatively signed for the CO₂ uptake) from TER; and (2) according to Lasslop et al. (2010), where daytime NEE data were used to constrain an hyperbolic light response curve to directly estimate GPP and TER. In the following we refer to GPP and TER as derived by Reichstein et al. (2005) as GPP_R and TER_R, whereas estimates based on the Lasslop et al. (2010) method are referred to as GPP_L and TER_L.

Half-hourly data were aggregated to daily values and screened according to multiple quality criteria, as follows.

1. We excluded data when more than 20 % of the data were based on gap-filling with low confidence (Reichstein et al., 2005).

2. We identified and removed obviously erroneous periods due to non-flagged instruments or flux partitioning failures based on visual interpretation.
3. We excluded data points where the two flux-partitioning methods provided extremely different patterns. Specifically, we computed for each site a robust linear regression between (a) TER_R – GPP_L and NEE – and (b) GPP_R and GPP_L. Data points with a residual outside the range of ± 3 times the inter-quartile range were removed. This criterion removed only the extreme residuals; systematic differences between methods were not removed.
4. We removed the 5 % of data points with the largest friction velocity (u^*) uncertainty, defined as data points above the 95th percentile of daily u^* uncertainty, measured as the inter-quartile range of 100 bootstrap samples (Papale et al., 2006).

We applied the same criteria (1) and (2) above for the energy fluxes as we did for the CO₂ fluxes. Additionally, we removed data with inconsistent energy fluxes, i.e., when the residual of a robust linear regression between LE + H and Rn for each site was outside 3 times the inter-quartile range of the residuals.

2.1.3 Remote sensing data

We collected data from the Moderate Resolution Imaging Spectroradiometer (MODIS) that provided data at a spatial resolution of 1 km or better (Justice et al., 2002). We used MODIS cutouts of 3 × 3 km pixels centered on each tower to reduce the effect of geolocation error and to better represent the eddy-covariance footprint area (Xiao et al., 2008). We used the following products: MOD11A2 Land Surface Temperature (LST; Wan et al., 2002); the MOD13A2 Vegetation Index (Normalized Difference Vegetation Index (NDVI) and Enhanced Vegetation Index (EVI) (Huete et al., 2002); the MOD15A2 Leaf Area Index (LAI) and fraction of absorbed photosynthetic active radiation (fPAR; Myneni et al., 2002); and MCD43A2 and MCD43A4 Bidirectional Reflectance Distribution Function (BRDF)-corrected surface reflectances (Schaaf et al., 2002). The BRDF-corrected surface reflectance data were further processed to calculate the Normalized Difference Water Index (NDWI; Gao, 1996) and the Land Surface Water Index (LSWI; Xiao et al., 2002). These data were obtained from <http://daac.ornl.gov/MODIS/>.

The remote sensing data were further processed to improve data quality and data gaps were filled to create continuous time-series data and to minimize non-land surface signals. In particular, we identified good-quality pixels by using the quality assurance/quality control (QA/QC) included in the MODIS product. If more than 25 % of the pixels had good quality at the time of the snapshot, the average of good-quality pixels was assigned as the actual value. Otherwise,

the data at the time snapshot were marked as blank (no data). Then, we created the mean seasonal variations from 2000 to 2012 using only good pixel data, and the data gaps in the processed data were filled using the mean seasonal variation. Only MOD13 was provided with 16-day composites, and 8-day data were created by assigning the 16-day composite value to the corresponding two 8-day periods.

2.1.4 Meteorological data

The air temperature (T_{air}), global radiation (R_g), vapor pressure deficit (VPD), and precipitation (in situ measured at the flux towers' locations) were used after data screening according to criteria (1) and (2) as applied for the measured fluxes (see Sect. 2.1.2). We also used long-term time series of these variables from the ERA-Interim data set (Dee et al., 2011) for the period 1989–2010, which were bias-corrected for each site based on the period of overlap with the in situ measurements (see <http://www.bgc-jena.mpg.de/~MDIwork/meteo/>). These long-term meteorological data were primarily used to calculate consistent metrics of climatological variables (e.g., mean annual temperature) for all sites given the temporal coverage of data of the different sites. In addition, we used a composite of these ERA-Interim data and in situ measured data to obtain a gap-free time series for calculating a soil water availability index (WAI; see Sects. 2.3.2 and S3).

2.2 Applied ML methods

For our purpose, 11 ML algorithms for regression from four broad families were chosen: tree-based methods, regression splines, neural networks and kernel methods. Moreover, a comprehensive review of ML algorithms in biophysical parameter estimation can be found in Verrelst et al. (2015). A brief description of the characteristics of each family follows.

2.2.1 Tree-based methods

These methods construct hierarchical binary decision trees. The inner nodes of the tree hold decision rules according to explanatory variables (e.g., less/greater than X_1), recursively splitting the data into subspaces. The leaf nodes at the end of the decision tree contain models for the response variable. Because a single tree is generally not effective enough to cope with strong nonlinear multivariate relationships, ensembles of trees are often used. We applied two different tree ensemble methods: (1) random forests (RF), which combines regression trees grown from different bootstrap samples and randomly selected features at each split node (Breiman, 2001; Ho, 1998), and (2) model tree ensembles (MTE), which combine model trees (Jung et al., 2009). The main difference between regression and model trees is the prediction model in the leaf node: a simple mean of the target values from the training in regression trees and a parametric function (here a multiple linear regression) in model

trees. In this study, we used three different variants of MTE, which differ mainly with respect to different cost functions for determining the splits, and the technique to create the ensemble of model trees. Further details are described in the Supplement (Sect. S2).

2.2.2 Regression splines

Multivariate regression splines (MARS) are an extension of simple linear regression adapted to nonlinear response surfaces using piecewise (local) functions. The target variable is predicted as the sum of regression splines and a constant value (Alonso Fernández et al., 2013; Friedman, 1991).

2.2.3 Neural networks

Neural networks are based on nonlinear and nonparametric regressions. Their base unit is the neuron, where nonlinear regression functions are applied. The neurons are interconnected and organized in layers. The outputs of m neurons in the current layer are the inputs for n neurons of the next layer. We used two types of neural network: the artificial neural network (ANN) and the group method of data handling (GMDH). In an ANN, each neuron performs a linear regression followed by a nonlinear function. Neurons of different layers are interconnected by weights that are adjusted during the training (Haykin, 1999; Papale and Valentini, 2003). The GMDH is a self-organizing inductive method (Ungaro et al., 2005) building polynomials of polynomials; the neurons are pairwise connected through a quadratic polynomial to produce new neurons in the next layer (Shirmohammadi et al., 2015).

2.2.4 Kernel methods

Kernel methods (Shawe-Taylor and Cristianini, 2004; Camps-Valls and Bruzzone, 2009) owe their name to the use of kernel functions, which measure similarities between input data examples. Among the available kernel methods we used are (1) support vector regression (SVR; Vapnik et al., 1997), (2) kernel ridge regression (KRR; Shawe-Taylor and Cristianini, 2004), and (3) Gaussian process regression (GPR; Rasmussen and Williams, 2006). The SVR defines a linear prediction model over mapped samples to a much higher dimensional space, which is nonlinearly related to the original input (Yang et al., 2007). The KRR is considered to be the kernel version of the regularized least squares linear regression (Shawe-Taylor and Cristianini, 2004). The GPR is a probabilistic approximation to nonparametric kernel-based regression, and both a predictive mean (point-wise estimates) and predictive variance (error bars for the predictions) can be derived. We also used a hybrid approach combining RF with simple decision stumps in the inner nodes and GPR for prediction in the leaf nodes (Fröhlich et al., 2012).

2.3 Experimental design

2.3.1 Experiment setups

We defined two complementary experimental setups, which differ in the choice of explanatory variables, and the temporal resolution of the target fluxes: (1) at 8-day temporal resolution using exclusively remote sensing data (hereafter RS); and (2) at daily temporal resolution using meteorological data together with the mean seasonal cycle (MSC) of the remote sensing data (hereafter RS + METEO). In the latter case, the MSC of remote sensing data was smoothed and interpolated to a daily time step. Each setup represents a trade-off between spatial and temporal resolution. While RS provides products with high spatial resolution for global upscaling (e.g., 1 km), the temporal resolution is coarse (8-day vs. daily) and temporal coverage is limited to the period when satellite observation is available (e.g., 2000–present in the case of MODIS). The uncertainties of remote sensing data at tower locations, due to finer-scale spatial heterogeneity, also degraded the performance of the ML methods. In contrast, RS + METEO takes advantage of information from meteorological variables and was resistant to the noise of remote sensing time series because only the mean seasonal cycle of data from satellite RS was used. RS + METEO also allowed for upscaled products over a longer time period (because not constrained by the availability of MODIS data) and finer timescale (daily). Furthermore, the use of meteorological gridded data sets introduced uncertainty due to data-set-specific biases and the coarser spatial resolution ($>0.5^\circ$ or coarser).

2.3.2 Variable selection

Combining remote sensing and meteorological data (see Sects. 2.1.2 and 2.1.3), we created additional explanatory variables. In the case of the RS + METEO setup, we derived the Water Availability Index (WAI) based on a soil water balance model (for more details, see Sect. S3) to represent water stress conditions appropriately. For both setups we derived proxies for absorbed radiation as the product between vegetation greenness (e.g., EVI, NDVI, fPAR) and drivers related to the useful energy for photosynthesis (e.g., daytime LST, R_g , and potential radiation). Other derived variables included the MSC of dynamic variables (e.g., LST, fPAR, R_g , air temperature) and associated metrics (minimum, maximum, amplitude, and mean). For remote sensing predictors, the MSC and associated metrics were based on the period 2001–2012, while for climate variables they were based on the bias-corrected daily long-term ERA-Interim data reference period (1989–2010). In total, 216 potential explanatory variables were created for RS and 231 for RS + METEO (see Sect. S4 for details).

For each of the two experimental setups we selected a small subset of variables optimally suitable for predicting

target fluxes using a variable selection search algorithm. Variable selection was an important component in the spatial upscaling since it improved the accuracy of predictions, while the computational costs of the global predictions were minimized. We used the Guided Hybrid Genetic Algorithm (GHGA; Jung and Zscheischler, 2013), which was designed for variable selection problems with many candidate predictor variables and computationally expensive cost functions. The GHGA required the training of a regression algorithm (here RF) to estimate the cost associated with selected variable subsets. We executed GHGA selection runs for the RS and RS + METEO setups and separately for CO₂ and energy fluxes (see S5 for details). All ML used exactly the same selected drivers (listed in Table 2) to make predictions. This procedure had the advantage that the resulting global products will have originated from a consistent set of predictor variables.

2.3.3 Algorithm training

The capability of ML methods to spatially extrapolate CO₂ and energy fluxes was evaluated using a 10-fold cross-validation strategy. The training data sets were stratified into 10 folds, each containing ca. 10% of the data. Entire sites were assigned to each fold (Jung et al., 2011). The training of each ML method was done using data from nine folds, while predictions were made for the remaining one. This was repeated 10 times and each fold was used exactly once as a validation set, thus ensuring that the validation data were completely independent of the training data. Due to the computational expense of the RS + METEO setup, only one method representing each “family” – RF, MARS, ANN and KRR – was trained. ML method hyperparameters (that account for regularization in order to avoid overfitting as well as for the shape and smoothness constraints) (see Sect. S6 for details) were estimated in each fold.

2.3.4 Model evaluation

To highlight the differences between the RS and RS + METEO setups, the daily output from RS + METEO was aggregated to 8-day time steps; predictions from the same periods and sites were used for the comparison. Besides the statistical analysis of the individual ML cross-validation results, we focused on the ensemble median estimate, here defined as the median predicted value across all ML for a given setup and time step. We used a suite of metrics to evaluate the ML performance: the Nash and Sutcliffe model efficiency (MEF; Nash and Sutcliffe, 1970); the root mean square error (RMSE); the empirical BIAS; Pearson’s linear correlation coefficient (ρ); the coefficient of determination (R^2); and the ratio of variance (ROV).

MEF is a measure of the capability of a model to estimate a target variable better than a reference, generally the mean value of the observations. In our study MEF was calculated

Table 2. Selected predictors for both setups for CO₂ fluxes (GPP, TER and NEE) and energy fluxes (*H*, LE and Rn). List of acronyms: Enhanced Vegetation Index (EVI), fraction of absorbed photosynthetically active radiation (fAPAR), leaf area index (LAI), daytime land surface temperature (LST_{Day}) and nighttime land surface temperature (LST_{Night}), middle infrared reflectance (band 7; MIR¹), Normalized Difference Vegetation Index (NDVI), Normalized Difference Water Index (NDWI), plant functional type (PFT), incoming global radiation (*R_g*), top of atmosphere potential radiation (Rpot), Index of Water Availability (IWA), relative humidity (Rh), Water Availability Index lower (WAI_L), and upper (WAI_U) (for details, see Sect. S3), and mean seasonal cycle (MSC). The product between A and B (*A* × *B*) is shown as (*A*, *B*).

Setup	Type of variability	CO ₂ fluxes	Energy fluxes
RS	Spatial	PFT Amplitude of MSC of EVI Amplitude of MSC of MIR ¹ Maximum of MSC of LST _{Day}	PFT Maximum of MSC of (fAPAR, <i>R_g</i>) Minimum of MSC of <i>R_g</i>
	Spatial and seasonal	MSC LAI	MSC of (EVI, LST _{Day}) Rpot
	Spatial, seasonal and interannual	NDWI LST _{Day} LST _{Night} (NDVI, <i>R_g</i>)	<i>R_g</i> LST _{Day} Anomalies of LST _{Night} Anomalies of (EVI, LST _{Day})
RS + METEO	Spatial	PFT Amplitude of MSC of NDVI Amplitude of MSC of band 4 BRDF reflectance ² Minimum of MSC of NDWI Amplitude of MSC of WAI _L	PFT Maximum of MSC of WAI _U Mean of MSC of band 6 BRDF reflectance ² Max of MSC of (fPAR, <i>R_g</i>)
	Spatial and seasonal	MSC of LST _{Night} MSC of (fPAR, LST _{Day}) MSC of (EVI, Rpot)	Rpot MSC of NDWI MSC of LST _{Night} MSC of (EVI, <i>R_g</i>)
	Spatial and seasonal and interannual	<i>T_{air}</i> (<i>R_g</i> , MSC of NDVI) WAI _L	Rain <i>R_g</i> Rh (MSC of NDVI, <i>R_g</i> , IWA)

¹ Derived from the MOD13 product. ² Derived from the MCD43 product.

as

$$\text{MEF} = 1 - \frac{\sum_{i=1}^n (x_i - y_i)^2}{\sum_{i=1}^n (y_i - \bar{y})^2}, \quad (1)$$

where x_i and y_i were the predicted and observed values, respectively, and \bar{y} is the mean value of the observations. MEF varied between -inf and 1; in the case of $\text{MEF} > 0$, the predictive capacity of the model was better than the mean ($\text{MEF} = 1$ for the ideal model); instead, if $\text{MEF} = 0$, the predictive capacity of the model was equivalent to the mean; finally, if $\text{MEF} < 0$, the predictive capacity of the mean value of the target was better than the model.

The RMSE was estimated as the square root of the mean value of the squared residuals:

$$\text{RMSE} = \sqrt{\frac{\sum_{i=1}^n (x_i - y_i)^2}{n}}. \quad (2)$$

The BIAS was evaluated as the mean value of the model's residuals:

$$\text{BIAS} = \frac{\sum_{i=1}^n (x_i - y_i)}{n}. \quad (3)$$

Following Gupta et al. (2009) the importance of bias in the overall uncertainty was evaluated as the ratio between the square of BIAS and the mean square error, the latter estimated as the square value of RMSE.

Pearson's linear correlation coefficient (ρ) was the ratio between the covariance between the modeled and observed values (σ_{xy}) and the product of the standard deviation of modeled (σ_x) and observed (σ_y) values:

$$\rho = \frac{\sigma_{xy}}{\sigma_x \sigma_y}. \quad (4)$$

R^2 was estimated as the squared value of ρ ; finally, ROV was evaluated as the ratio between predicted and observed standard deviation.

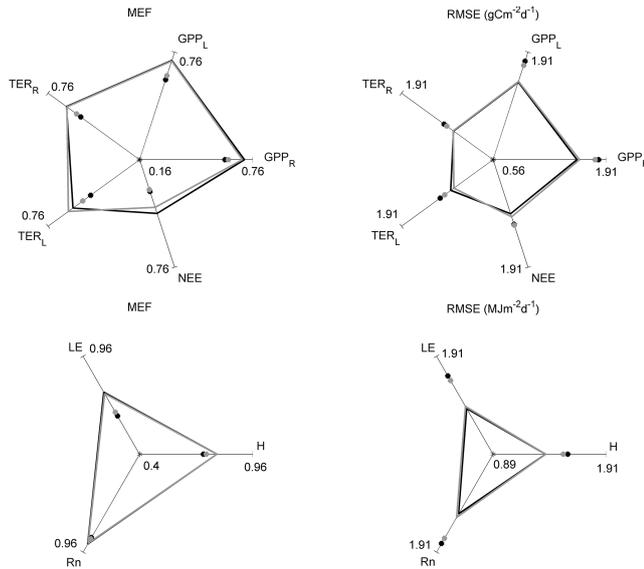


Figure 1. Spider plot of MEF (first column) and RMSE (second column) for CO₂ (first row) and energy fluxes (second row) showing the consistency of prediction made by the RS (black line) and RS + METEO (grey lines) setups. The lines were the ensemble median estimate of ML; we also showed the performance of multiple regressions trained with RS (black point) and RS + METEO (grey points). GPP_R and GPP_L were, respectively, the gross primary production estimated following Reichstein et al. (2005) and Lasslop et al. (2010), TER_R and TER_L the total ecosystem respiration estimated following Reichstein et al. (2005) and Lasslop et al. (2010), NEE net ecosystem exchange, *H* the sensible heat, LE the latent heat, and Rn the net radiation.

We evaluated the overall predictive capacity and consistency of ML approaches – including the ML median estimate – by flux, by experimental setup and by site as well as grouped by Köppen climate zone and International Geosphere-Biosphere Programme (IGBP) plant functional types. In our evaluation we focused on site-specific means, the mean seasonal cycle (MSC), and anomalies (Jung et al., 2011). The MSC per site was calculated using the averaged values for each 8-day period across the years, but only when at least two values (i.e., years) for each 8-day period were available. To assess the mean values of the study sites, we calculated the mean of the MSC if at least 50 % of the 46 8-day values were present, whereas the 8-day anomalies were calculated as the deviation of a flux value from the MSC. Finally, the mean site values were removed from the MSC to disentangle the seasonal variation from the mean site values, making them complementary.

3 Results

3.1 Machine learning performance across fluxes

Prediction capability of the ensemble median estimate clustered into tiers whereby energy fluxes were better predicted than CO₂ fluxes: Rn > H/LE/GPP > TER > NEE (Tables 3 and A1 in Appendix A). The highest predictive capacity levels as exhibited by net radiation showed near-perfect agreement; Rn displayed a model efficiency (MEF) of 0.91–0.92 and a correlation of 0.96. The decline in predictive capacity for the second tier fluxes was ca. 15 to 20 %; MEF for *H*, LE, and GPP is 0.79, 0.75–0.76, and 0.71, respectively. The lowest two tiers exhibited 20 and 40 % declines in MEF (0.57–0.64 and 0.43–0.46 for TER and NEE, respectively). These relative rankings, consistent with previous studies (Jung et al., 2011; Yuan et al., 2010), were unchanged regardless of the metric of the predictive capacity used in cross-validation – apart from RMSE, where the difference in flux units and magnitude confounded a direct comparison (Table 3).

There were only minor performance differences between the two CO₂ flux-partitioning methods (Table 3), although for the RS setup, the performance of TER_L was slightly lower than TER_R (lower MEF, ρ and ROV). However, a similar pattern was not found in the RS + METEO setup.

Accuracy metrics of median ensembles were similar, by flux, for both the RS and RS + METEO approaches, showing that the spatiotemporal variability of remotely sensed land surface properties is appropriate for predicting the top-tier fluxes (Rn, *H*, LE, and GPP; Jung et al., 2008; Tramontana et al., 2015; Xiao et al., 2010; Yang et al., 2007). We found some minor differences for those fluxes that showed lower overall predictive capacity levels, in particular the NEE and TER_L (Fig. 1, Table 3). MEF and correlation values were slightly larger for RS than RS + METEO, but the differences in performances might be due to a different ensemble size, with the RS median ensemble composed of 11 MLs, whereas RS + METEO was based on only four. However, the output provided by ML methods showed high overall consistency among them that increased when predictions were obtained by different MLs trained with the same experimental setup (RS, else RS + METEO; for more details, see Appendix B and Table B1).

3.2 Capability to predict the across-site variability, the mean seasonal cycle and the deviations from it

Decomposing FLUXNET data into across-site variability, mean seasonal cycle, and interannual variability components (Sect. 2.3.4) revealed clear gradients in predictive capacity (Table 4 and Figs. 2, 3a and b). Across-site variability was in general well captured by the ML (R^2 range: 0.61 to 0.81, except for NEE), suggesting that the ML methods are suitable for reproducing the spatial pattern of the mean annual fluxes. The variability in the mean seasonal cycle (on an 8-

Table 3. Statistics of the accuracy of predictions of CO₂ and energy fluxes made by the ensemble median estimate based on RS and RS + METEO. For RMSE and BIAS, the reference units were gCm⁻²d⁻¹ and MJm⁻²d⁻¹ for CO₂ fluxes (GPP, TER and NEE) and energy fluxes (*H*, LE and Rn), respectively.

Flux	RS					RS + METEO				
	MEF	RMSE	ρ	ROV	BIAS	MEF	RMSE	ρ	ROV	BIAS
GPP _R	0.71	1.56	0.85	0.69	-0.02	0.70	1.59	0.84	0.73	0.09
GPP _L	0.71	1.53	0.84	0.68	-0.02	0.71	1.54	0.84	0.74	0.09
TER _R	0.64	1.14	0.80	0.61	-0.01	0.64	1.15	0.80	0.69	0.09
TER _L	0.60	1.18	0.77	0.56	-0.01	0.63	1.14	0.79	0.66	0.08
NEE	0.46	1.24	0.68	0.39	0.04	0.43	1.28	0.65	0.40	-0.02
<i>H</i>	0.79	1.36	0.89	0.71	-0.02	0.79	1.37	0.89	0.75	0.02
LE	0.76	1.37	0.87	0.71	-0.07	0.75	1.39	0.87	0.73	-0.01
Rn	0.92	1.51	0.96	0.90	-0.01	0.91	1.55	0.96	0.93	0.08

day timescale) was also uniformly well predicted, in particular for LE and Rn (R^2 between 0.67 and 0.77 for GPP and TER, and between 0.86 and 0.98 for the energy fluxes). In contrast, the 8-day anomalies' variability was generally poorly captured by all the ML approaches, with only *H* and Rn showing an R^2 greater than 0.4. This low predictive skill was regardless of whether 8-day, monthly (Jung et al., 2011), or annual time steps were used (data not shown), and predicting interannual variability remains one of the largest challenges in the context of the empirical upscaling. NEE was confirmed to be the poorest predicted flux (Table 3). ML showed considerably lower predictive capability for NEE, by comparison with the other fluxes for across-site variability ($R^2 = 0.46$), the mean seasonal cycle ($R^2 = 0.59$), and interannual variability ($R^2 = 0.13$; TER_L was the lowest at 0.10).

3.3 Model performance for different climate zones and ecosystem types

Climate zone and plant functional type (PFT) are important discriminating factors for ML predictive capacity for CO₂ fluxes. In general, the mixed forest (MF), the deciduous broadleaved forest (DBF) and the boreal sites (Bor) showed higher accuracy of prediction for the median ensembles (Fig. 4, Tables C1–C6 in Appendix C), even for NEE ($R^2 > 0.6$). In contrast, relatively poor prediction capability was found in evergreen broadleaved forest (EBF), in the tropics (Trop), in the extreme environments for reduced water resources (Dry) or low temperature (Cold), and in managed sites such as croplands (Crop). This gradient largely reflects the mismatch between the seasonal dynamics of predicted fluxes and the models' drivers. The absence of a clear seasonal cycle in evergreen broadleaf forest and in the tropical sites likely contributed to the low ML performance (in general) in these ecosystems (Sims et al., 2008; Yebra et al., 2015; Yuan et al., 2010). Similarly, cold and dry sites are characterized by both low magnitude and low variance of fluxes, making it difficult to explain the flux variability in these ecosystem types using empirical methods. For

the intensively managed croplands, the seasonal dynamics of fluxes were highly constrained by management practices (e.g., irrigation, fertilization, tillage), which is not directly reflected in the explanatory variables used in training.

The gradient of prediction capability in different PFTs and climate zones was less evident in the case of energy fluxes (not significant in the case of Rn) and the performances of ML were generally good. In fact, the median R^2 between simulations and observations was greater than 0.7 for more than 85 % of the PFTs and climate zones (at all sites for Rn). For comparison in the case of GPP and TER, the median R^2 between simulations and observations was greater than 0.6 for more than 75 % of the PFTs and climate zones.

4 Discussion

4.1 Comparison between experimental setups

In general the performance metrics across the two experimental setups were highly similar. Very few differences were found decomposing the flux variability into across-site variability, mean seasonal cycle, and interannual variability components. This suggests that CO₂ and energy fluxes can be mapped exclusively with remotely sensed inputs, allowing for high-spatial-resolution products without additional uncertainty introduced by gridded meteorological data products (Tramontana et al., 2015). However, differences between the two experimental setups are apparent at PFT and climate zone scales, particularly in the EBF PFT and in the tropics, where RS + METEO performs better than RS in predicting CO₂ fluxes (e.g., in RS + METEO the decrease in RMSE was 0.10–0.68 gCm⁻²d⁻¹ in comparison to RS). This might be due on the one hand to the pattern of CO₂ fluxes that do not follow the seasonal pattern of the vegetation indices, and on the other hand to the increasing importance of meteorological drivers, in particular the ones accounting for the water stress/limitation (e.g., VPD or WAI). In addition, the larger sample size due to the daily resolution of the RS + METEO

Table 4. R^2 and RMSE for the comparison across sites, mean seasonal cycle and anomalies. The last two columns showed the consistency between the median estimates of the two setups. For RMSE, the reference units were $\text{g Cm}^{-2} \text{d}^{-1}$ and $\text{MJm}^{-2} \text{d}^{-1}$ for CO_2 fluxes (GPP, TER and NEE) and energy fluxes (H , LE and Rn), respectively.

Fluxes	RS vs. OBS		RS + METEO vs. OBS		RS vs. RS + METEO	
	R^2	RMSE	R^2	RMSE	R^2	RMSE
Across-site variability						
GPP _R	0.78	0.80	0.77	0.82	0.95	0.34
GPP _L	0.78	0.77	0.79	0.75	0.94	0.36
TER _R	0.68	0.73	0.61	0.81	0.92	0.32
TER _L	0.72	0.60	0.71	0.61	0.92	0.27
NEE	0.48	0.61	0.46	0.61	0.83	0.22
H	0.81	0.68	0.81	0.68	0.97	0.25
LE	0.79	0.74	0.75	0.80	0.93	0.33
Rn	0.80	0.93	0.79	0.96	0.96	0.38
Mean seasonal cycle						
GPP _R	0.76	1.03	0.77	1.02	0.93	0.48
GPP _L	0.77	1.00	0.77	0.99	0.93	0.50
TER _R	0.71	0.62	0.71	0.62	0.92	0.29
TER _L	0.67	0.64	0.68	0.63	0.92	0.29
NEE	0.61	0.83	0.59	0.84	0.93	0.24
H	0.86	0.89	0.86	0.87	0.97	0.36
LE	0.87	0.79	0.87	0.79	0.95	0.45
Rn	0.98	0.74	0.98	0.74	0.99	0.43
Anomalies						
GPP _R	0.18	0.67	0.12	0.68	0.38	0.32
GPP _L	0.16	0.67	0.11	0.68	0.37	0.31
TER _R	0.14	0.48	0.15	0.48	0.36	0.17
TER _L	0.10	0.58	0.13	0.57	0.35	0.18
NEE	0.13	0.56	0.13	0.55	0.43	0.20
H	0.43	0.81	0.41	0.81	0.77	0.34
LE	0.21	0.78	0.21	0.77	0.46	0.32
Rn	0.57	0.81	0.54	0.83	0.84	0.41

setup might have been beneficial. The RS setup might also suffer from poorer quality of remote sensing data in the tropics due to frequent cloud coverage. At cropland sites the RS has better predictive capacity than RS + METEO (for predicting CO_2 fluxes, RMSE of RS + METEO increases of $0.02\text{--}0.67 \text{gCm}^{-2} \text{d}^{-1}$ in comparison to RS). This could be related to management (e.g., sowing and harvesting dates) that is partly captured by RS but not by RS + METEO, which uses only the mean seasonal cycle of VI, reflecting also the better performance of RS for predicting anomalies in the case of CRO, (although in general, results for anomalies were not good; data not shown).

Another distinguishing element between RS and RS + METEO is the degree of uncertainty of the drivers. At the site level, meteorological drivers (used only in RS + METEO) are generally measured with good quality, while remote sensing data are generally affected by additional uncertainties. Scale mismatch between FLUXNET

eddy-covariance towers and satellite sensor footprints as well as satellite sensor limitations are important sources of uncertainty not present in the in situ measured meteorological drivers. Furthermore, the quality of remote sensing data is affected by external factors such as the atmospheric condition, cloud cover and ground surface state. These issues were minimized in RS + METEO by using only the smoothed mean seasonal cycle of satellite data that contains much less noise. We had expected that this would improve the performance of predicting anomalies (in general) with the RS + METEO setup, because anomalies are comparatively small signals that could be readily distorted by the comparatively large noise in remote sensing data. However, we found no clear indication of that in the cross-validation results.

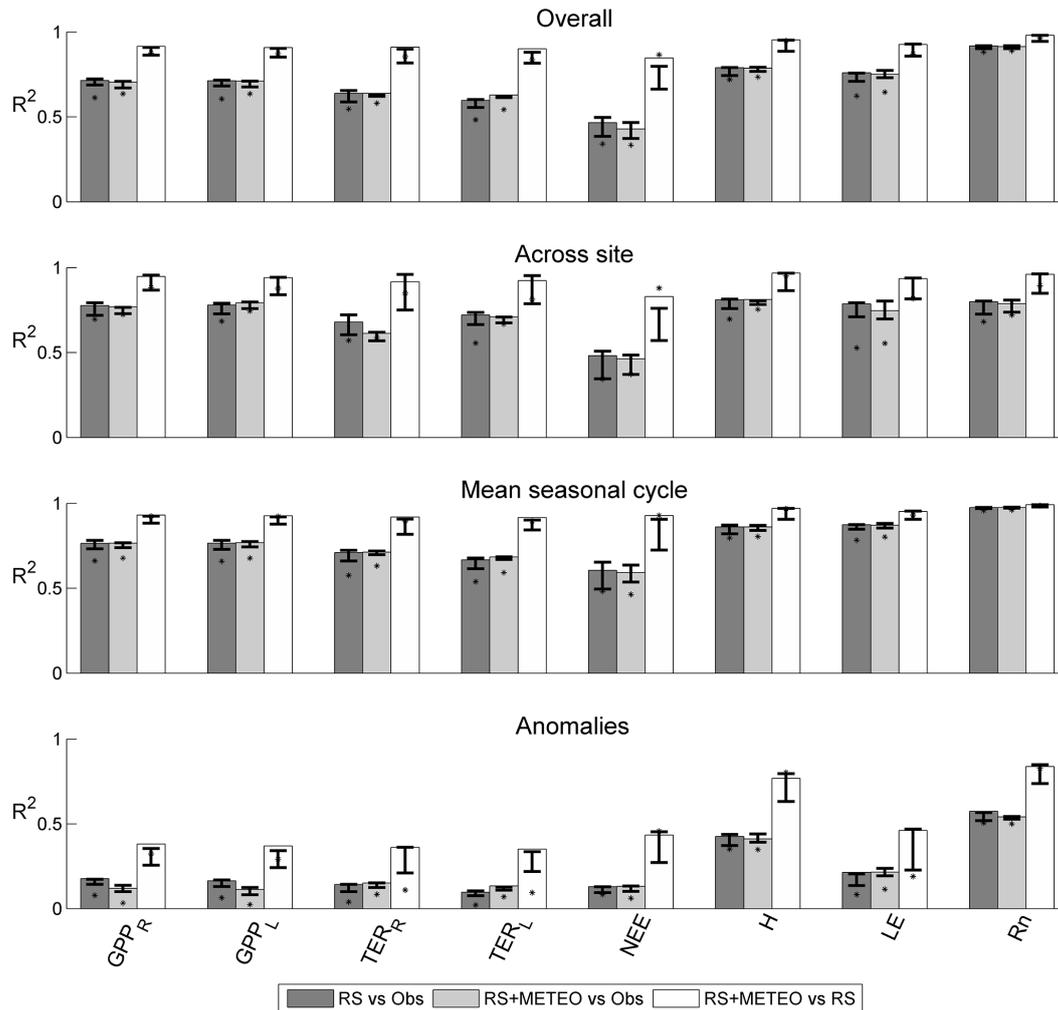


Figure 2. Coefficients of determination (R^2) from the comparison of overall time series, across-sites, mean seasonal cycle, and the anomalies, in particular the determination coefficients between predictions by the ensemble median estimate of RS setup and observation (dark grey bars), between predictions by the ensemble median estimate of RS + METEO setup and observation (light grey bars), and between the two ensembles' median estimate (white bars). Whiskers were the higher and lower R^2 when the comparisons were made among the singular ML. The comparison of output by the multiple regressions was also shown (black points). GPP_R and GPP_L were, respectively, the gross primary production estimated following Reichstein et al. (2005) and Lasslop et al. (2010), TER_R and TER_L the total ecosystem respiration estimated following Reichstein et al. (2005) and Lasslop et al. (2010), NEE net ecosystem exchange, H the sensible heat, LE the latent heat and R_n the net radiation.

4.2 Completeness of predictors

Certainly, the predictor variables used for the ML approaches do not capture all drivers of flux variability, both across sites and temporally. For example, in managed sites, external factors such as management practices and disturbances (Amiro et al., 2010; Thornton et al., 2002) are likely crucial. In addition, direct estimates of soil moisture would improve the prediction capability in dry environments. The absence of important drivers of flux variability in the predictor sets likely explains why NEE and TER are less well predicted compared to GPP . First-order constraints of GPP such as radiation, temperature, and canopy properties are accounted for

in the predictors. For TER some important factors like soil properties and carbon pools (Amiro et al., 2010) are not well presented in the predictor variables. For NEE , several studies have shown its dependence on long-term lag and memory effects (Bell et al., 2012; Frank et al., 2015; Papale et al., 2015; Paruelo et al., 2005) that are not accounted for by the drivers used in this study. Adding targeted variables (e.g., soil carbon stock, turnover of the soil organic matter, lagged drivers) among the candidate predictors, and carrying out the driver selection for each CO_2 flux specifically, could improve the ML performance for each flux. At the same time it could be a detriment to the spatial upscaling of CO_2 fluxes, generating less consistent global products with plausible bad effects

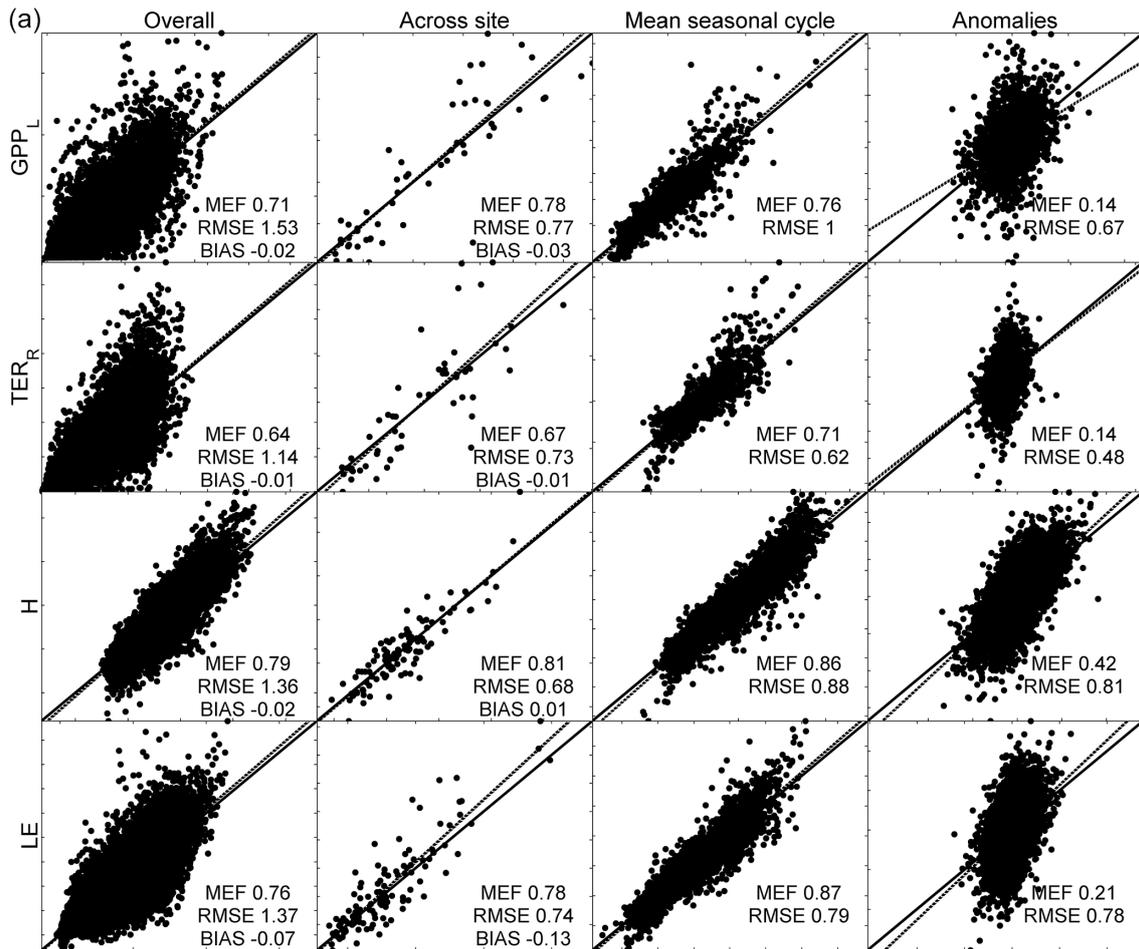


Figure 3.

on CO₂ uptake/release balance closure over the land ecosystems. Moreover, the choice of predictor variables for the ML approaches is limited in practical terms by the availability of consistent observations across all sites on the one hand, and by the availability of a corresponding consistent global gridded product for upscaling. Therefore, continued efforts of metadata collection at the sites in conjunction with large-scale inventories and new Earth observations are needed to improve the ML approach in the future.

4.3 Quality of the response variable

The predictive capacity of ML approaches also depends on the uncertainties in the flux variables themselves. Clearly, there is some variability in the target flux variables that is due to noise and measurement problems, and this portion of variability cannot (and should not) be reproduced by the ML approaches. Interestingly, we obtained the best results for Rn and *H*, which have lower measurement uncertainties than all other target fluxes. For example, for *H* only one sensor, the sonic anemometer, is used, while other measured fluxes (LE and NEE), two sensors, a sonic anemometer and a CO₂/H₂O

trace gas analyzer are needed. GPP and TER estimates are additionally subject to uncertainties in the flux partitioning methods, and this might explain why LE as a direct measurement was better predicted than GPP. Random uncertainties in the fluxes are likely not a big issue because averaging at daily and 8-day time steps (as in this study) greatly reduces the random error (Hollinger and Richardson, 2005). Instead we hypothesize that site-specific systematic uncertainties in the eddy-covariance estimations (e.g., due to the presence of strong advection not corrected by the standard methods) could play an important role because ML methods were trained across sites, distributing uncertainties among them. Systematic uncertainties could also reduce the sensitivity of the models to the small signal, explaining the comparatively poor predictive skill of ML for anomalies of eddy-covariance fluxes. We also hypothesize that the general tendency of better predictability of energy fluxes compared to carbon fluxes is at least partly related to their differences in data quality. To test these hypotheses, improved ways of detecting and characterizing systematic uncertainties in eddy-covariance data are needed.

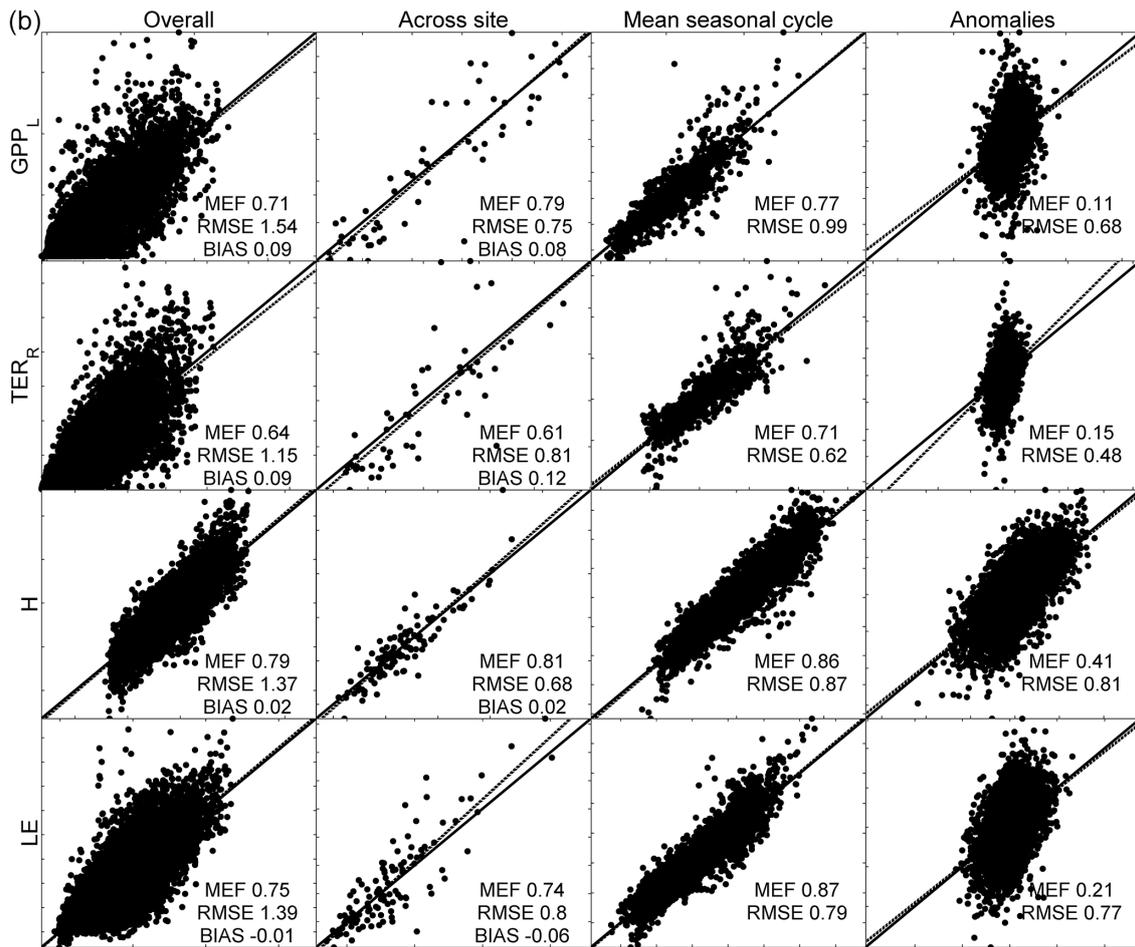


Figure 3. (a) Scatterplots of observed data by eddy-covariance (y axis) and the median ensemble of modeled fluxes by RS setup (x axis). The panels from left to right were the 8-day predictions, the across-site variability, the mean seasonal cycle and the 8-day anomalies. The fluxes considered here were the gross primary production estimated following Lasslop et al. (2010), GPP_L (first row); the total ecosystem respiration estimated following Reichstein et al. (2005), TER_R (second row); the sensible heat, H (third row); and the latent heat, LE (fourth row). The reference units were $\text{g Cm}^{-2} \text{d}^{-1}$ and $\text{MJ m}^{-2} \text{d}^{-1}$ for CO₂ fluxes (GPP_L and TER_R) and energy fluxes (H and LE), respectively. (b) As in Fig. 3a, but the predictions (x axis) were obtained by the RS + METEO setup.

Another common issue with eddy-covariance data is the gaps generated by the data exclusion rules. Data exclusion strikes strongly the nighttime period (primarily for the low turbulence condition), affecting the representativeness of the diurnal cycle, and hence the quality of the averaged daily/8-day eddy-covariance fluxes, in particular CO₂. To reduce the risk of biased estimates, half-hourly data gaps are filled by models. In our study NEE data were gap filled using site-specific empirical relationships between meteorological data and net CO₂ ecosystem exchange (the MDS method, Reichstein et al., 2005) that produce small biases when short gaps were encountered (Moffat et al., 2007). This has a limited effect in this study as only a very small percentage of high-quality gap-filled data is used. We also minimize the bias in estimates of gross CO₂ fluxes (GPP and TER) by using two different partitioning methods that yield very consistent results.

4.4 Data quantity and representativeness

The mismatch between prediction and eddy-covariance estimation was also influenced by data representativeness. FLUXNET sites are not uniformly distributed over the globe and not all climates and PFTs are well represented. Very few sites are currently distributed in tropical forest, and data availability over the record is fragmented. Similarly, very few sites are located in the poorly predicted extreme environments, e.g., cold and dry climates. There was a clear pattern in our cross-validation results where more accurate predictions were obtained for the better represented vegetation types and climates (e.g., temperate and boreal forests). Therefore, increasing the number of study sites in less represented environments (e.g., the tropics and in the extreme climates) could improve the prediction by ML and models in general (Papale et al., 2015).

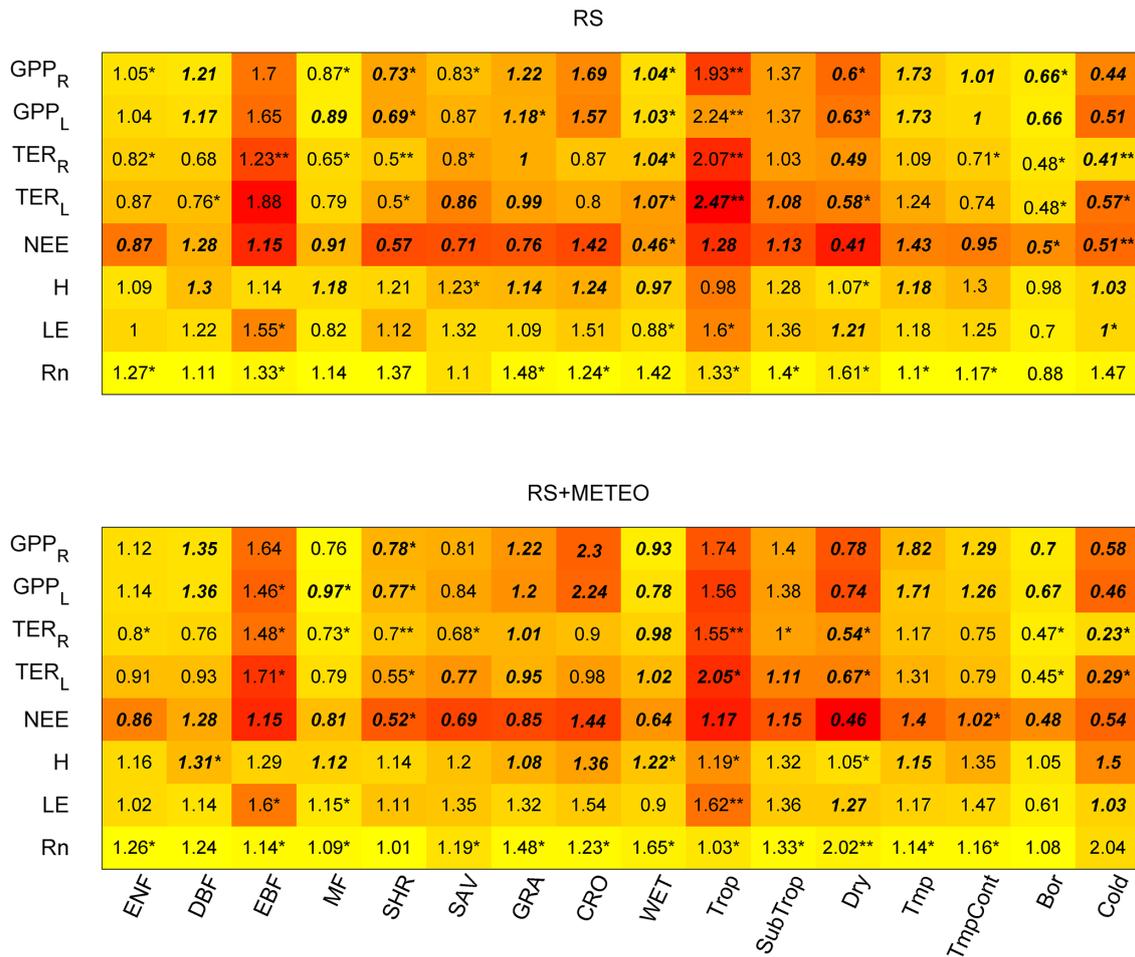


Figure 4. Performance of FLUXCOM median estimates per climate zone and plant functional type (PFT). The colored matrices show the median values of R^2 (red pixels for low R^2 , yellow pixels for high R^2). Numbers indicate the RMSE (units of CO₂ fluxes are g Cm⁻² d⁻¹ and MJm⁻² d⁻¹ in the case of energy fluxes). Oblique and bold fonts are used when the relative RMSE (normalized for the mean observed fluxes per PFT and climate zone) was greater than 0.5. The symbols “***” after RMSE were used when the weight of bias (estimated as the ratio between the square of the median absolute bias and the MSE) was greater than 0.5; instead, “**” symbols were used if the weight of bias was between 0.25 and 0.5. No symbols were used if the weight of bias is less than 0.25. List of acronyms: ENF, evergreen needleleaf forest; DBF, deciduous broadleaf forest; EBF, evergreen broadleaf forest; MF, mixed forest; SHR, shrubland; SAV, savannah; GRA, grassland; CRO, cropland; WET, wetland; Trop, tropical; SubTrop, subtropical; Dry, dry and arid land; Tmp, temperate; TmpCont, temperate–continental; Bor, boreal; Cold, cold and polar environment or covered by ice; GPP_R and GPP_L were, respectively, the gross primary production estimated following Reichstein et al. (2005) and Lasslop et al. (2010); TER_R and TER_L the total ecosystem respiration estimated following Reichstein et al. (2005) and Lasslop et al. (2010); NEE, net ecosystem exchange; H, sensible heat; LE, latent heat; and Rn, net radiation.

Data representativeness also has a temporal aspect. For example, remote sensing data discarded due to low quality occur preferentially in the cold or wet season – due to snow, ice or cloud cover – by comparison with other seasonal periods.

5 Conclusions

The ML methods presented and evaluated in this study have shown a high capability to predict CO₂ and energy fluxes, in particular the across-site variability and the mean seasonal cycle, with a general tendency towards increasing per-

formance in the following order: NEE, TER, GPP, LE, H, and Rn. The relatively poor performance for NEE likely resulted from factors that cannot be easily accounted for in ML-based approaches, such as legacies of site history (e.g., disturbances, management, age, and stocks). Future progress in this direction requires the reconstruction of the relevant management and disturbance history and the integration of information from forest inventories, high-resolution satellites such as LANDSAT, and high-resolution biomass data from radar and lidar. We found no substantial bias in the predictions of the ML approaches for most vegetation types or biomes. However, there is less consistency with observations

for evergreen broadleaf forests, croplands, the tropics, and extreme climates. The growing number of eddy-covariance sites, in particular new sites in poorly represented regions, will improve the predictive capacity of ML methods in the future. This is particularly so for the tropics, which account for a disproportionate share of global terrestrial water and carbon fluxes (Beer et al., 2010).

The predictions for ecosystem fluxes across FLUXNET by different explanatory variable sets (RS vs. RS + METEO) were highly consistent, indicating that the extracted patterns by the trained models were robust, realistic and not subject to overfitting. We recommend using the ensemble median estimate for generating global flux products as extrapolation beyond the FLUXNET-sampled conditions may generate large differences among methods.

The ML-based models presented and extensively evaluated here form the basis of an extensive archive of global gridded flux products, which is currently under development. The thorough cross-validation experiment presented in this paper helps users understand the products' strengths and weaknesses. The overall high skill of the ML methods, the planned archive of their ensemble median, and the detailed analysis of their uncertainties will make this product a sought-after data stream to study the global land–atmosphere exchange of CO₂, water and energy.

6 Data availability

Fluxes and in situ measured meteorological data are obtained from the La Thuile data set, and they are freely available at the FLUXNET website (<http://fluxnet.fluxdata.org/data/la-thuile-dataset/>). Reanalyzed ERA-Interim meteorological data are produced by the European Centre for Medium-Range Weather Forecasts (ECMWF), and they are freely available at the ERA-Interim ECMWF website (<http://apps.ecmwf.int/datasets/>). Satellite MODIS subset products are freely available at the MODIS subset website (https://daac.ornl.gov/cgi-bin/MODIS/GR_col5_1/mod_viz.html). The data used for the cross-validation analysis (e.g., machine learning output and/or their median ensemble) are available on request from the first (and second) author.

Appendix A: Median performance of the methods

In Table A1 we reported, for both setups, the median value of predictive capacity metrics (MEF, RMSE, and absolute value of BIAS) realized across singular ML and their standard deviation estimated as reported in Jung et al. (2009).

Table A1. Accuracy of CO₂ and energy fluxes predicted by the machine learning method based on the RS and RS + METEO setup. The median value and the standard deviation across methods (in parentheses and estimated as reported in Jung et al., 2009) are shown. Reference units for RMSE and absolute BIAS, were gCm⁻² d⁻¹ and MJm⁻² d⁻¹ for CO₂ fluxes (GPP, TER and NEE) and energy fluxes (H, LE and Rn), respectively.

FLUXES	RS			RS + METEO		
	MEF	RMSE	Abs BIAS	MEF	RMSE	Abs BIAS
GPP	0.698 (±0.012)	1.604 (±0.033)	0.022 (±0.019)	0.694 (±0.012)	1.614 (±0.032)	0.073 (±0.011)
GPP _{HB}	0.700 (±0.009)	1.564 (±0.024)	0.023 (±0.024)	0.701 (±0.008)	1.561 (±0.020)	0.083 (±0.011)
TER	0.612 (±0.022)	1.183 (±0.033)	0.026 (±0.025)	0.623 (±0.005)	1.166 (±0.008)	0.089 (±0.033)
TER _{HB}	0.571 (±0.016)	1.218 (±0.023)	0.019 (±0.017)	0.609 (±0.001)	1.163 (±0.002)	0.079 (±0.017)
NEE	0.433 (±0.017)	1.270 (±0.019)	0.024 (±0.021)	0.407 (±0.029)	1.298 (±0.032)	0.014 (±0.003)
H	0.767 (±0.015)	1.426 (±0.047)	0.014 (±0.005)	0.776 (±0.008)	1.397 (±0.025)	0.022 (±0.009)
LE	0.739 (±0.015)	1.418 (±0.042)	0.052 (±0.046)	0.734 (±0.003)	1.434 (±0.009)	0.023 (±0.008)
Rn	0.909 (±0.009)	1.589 (±0.082)	0.030 (±0.025)	0.908 (±0.008)	1.600 (±0.070)	0.073 (±0.015)

Appendix B: Consistency among ML algorithms

Pairwise R^2 values among model outputs (Table B1) were close to unity ($R^2 \geq 0.90$), regardless of experimental setup, with NEE showing a slightly lower value ($R^2 = 0.84$). Among corresponding model residuals (Table B1), R^2 values ranged from 0.79 (Rn) to 0.89 (TER_L). Comparing the same ML technique but using different experimental setups (Table B1, RS vs. RS + METEO) showed a similarly high albeit somewhat diminished level of consistency (R^2 ranged from 0.71 to 0.80 for model residuals). These results highlighted the fact that the ML methods were mapping between explanatory variables and target fluxes both reliably and robustly. Across all three consistency checks there was also a tendency for better predicted fluxes (e.g., H) to exhibit higher pairwise R^2 values than poorly predicted fluxes (e.g., NEE).

Table B1. Mean values of the determination coefficient (R^2) by the pairwise comparison of the models' output and their residuals. We compared different MLs and the same drivers (RS and RS + METEO, respectively) or the same ML and different drivers (RS vs. RS + METEO). Numbers in parentheses were the standard deviation of R^2 . All correlations were statistically significant ($p < 0.001$).

Fluxes	Correlation among model output			Correlation among model residuals		
	RS	RS + METEO	RS vs. RS + METEO	RS	RS + METEO	RS vs. RS + METEO
GPP _R	0.95 (0.02)	0.95 (0.02)	0.89 (0.02)	0.88 (0.04)	0.87 (0.04)	0.74 (0.04)
GPP _L	0.95 (0.02)	0.94 (0.02)	0.88 (0.02)	0.88 (0.04)	0.86 (0.04)	0.72 (0.04)
TER _R	0.91 (0.03)	0.94 (0.03)	0.86 (0.04)	0.86 (0.05)	0.88 (0.05)	0.75 (0.06)
TER _L	0.92 (0.03)	0.93 (0.03)	0.85 (0.03)	0.89 (0.04)	0.88 (0.05)	0.77 (0.05)
NEE	0.84 (0.06)	0.84 (0.07)	0.75 (0.08)	0.88 (0.05)	0.87 (0.06)	0.80 (0.06)
H	0.94 (0.02)	0.96 (0.02)	0.93 (0.03)	0.80 (0.06)	0.87 (0.05)	0.76 (0.08)
LE	0.94 (0.02)	0.96 (0.01)	0.90 (0.02)	0.83 (0.05)	0.88 (0.04)	0.73 (0.04)
Rn	0.98 (0.01)	0.99 (0.00)	0.97 (0.01)	0.79 (0.08)	0.86 (0.03)	0.71 (0.12)

Appendix C: Median values of site-by-site performance per vegetation and climate type

Table C1. Median site-by-site R^2 and its standard deviation (in parentheses and estimated as reported in Jung et al., 2009) for the CO_2 fluxes, per PFT and climate zones. List of acronyms: ENF, was evergreen needleleaf forest; DBF, deciduous broadleaf forest; EBF, evergreen broadleaf forest; MF, mixed forest; SHR, shrubland; SAV, savannah; GRA, grassland; CRO, cropland; WET, wetland; Trop, tropical; SubTrop, subtropical; Dry, dry and arid land; Tmp, temperate; TmpCont, temperate–continental; Bor, boreal; Cold, cold and polar environment or covered by ice.

CAT	GPP _R		GPP _L		TER _R		TER _L		NEE	
	RS	RS + METEO	RS	RS + METEO						
ENF	0.87 (0.10)	0.86 (0.10)	0.85 (0.12)	0.86 (0.12)	0.81 (0.15)	0.85 (0.11)	0.75 (0.24)	0.76 (0.20)	0.50 (0.34)	0.55 (0.30)
DBF	0.89 (0.07)	0.87 (0.09)	0.87 (0.07)	0.88 (0.08)	0.81 (0.12)	0.83 (0.13)	0.76 (0.14)	0.76 (0.14)	0.72 (0.16)	0.68 (0.17)
EBF	0.50 (0.29)	0.48 (0.20)	0.48 (0.29)	0.44 (0.28)	0.34 (0.34)	0.49 (0.35)	0.15 (0.18)	0.29 (0.20)	0.26 (0.23)	0.24 (0.26)
MF	0.91 (0.06)	0.95 (0.02)	0.91 (0.03)	0.95 (0.04)	0.85 (0.10)	0.90 (0.07)	0.84 (0.10)	0.86 (0.15)	0.73 (0.10)	0.75 (0.09)
SHR	0.67 (0.30)	0.71 (0.28)	0.67 (0.36)	0.72 (0.23)	0.80 (0.13)	0.78 (0.24)	0.68 (0.18)	0.66 (0.38)	0.37 (0.38)	0.41 (0.31)
SAV	0.75 (0.13)	0.70 (0.13)	0.72 (0.05)	0.67 (0.17)	0.65 (0.07)	0.72 (0.11)	0.55 (0.16)	0.61 (0.10)	0.38 (0.20)	0.34 (0.29)
GRA	0.69 (0.27)	0.62 (0.33)	0.69 (0.25)	0.60 (0.32)	0.70 (0.25)	0.73 (0.25)	0.66 (0.20)	0.72 (0.21)	0.40 (0.29)	0.36 (0.30)
CRO	0.58 (0.41)	0.44 (0.36)	0.56 (0.41)	0.45 (0.31)	0.78 (0.17)	0.76 (0.15)	0.68 (0.22)	0.65 (0.23)	0.35 (0.46)	0.33 (0.43)
WET	0.87 (0.11)	0.91 (0.07)	0.85 (0.12)	0.87 (0.09)	0.78 (0.19)	0.83 (0.14)	0.65 (0.17)	0.74 (0.20)	0.64 (0.16)	0.61 (0.24)
Trop	0.32 (0.46)	0.40 (0.39)	0.63 (0.23)	0.31 (0.32)	0.25 (0.23)	0.34 (0.47)	0.11 (0.13)	0.26 (0.14)	0.28 (0.35)	0.21 (0.30)
SubTrop	0.64 (0.26)	0.66 (0.28)	0.65 (0.26)	0.65 (0.24)	0.64 (0.25)	0.66 (0.26)	0.52 (0.24)	0.55 (0.28)	0.39 (0.37)	0.39 (0.26)
Dry	0.47 (0.27)	0.40 (0.33)	0.50 (0.25)	0.38 (0.30)	0.62 (0.25)	0.62 (0.38)	0.55 (0.19)	0.55 (0.39)	0.21 (0.29)	0.11 (0.14)
Tmp	0.81 (0.19)	0.74 (0.24)	0.83 (0.14)	0.78 (0.22)	0.78 (0.13)	0.77 (0.18)	0.68 (0.20)	0.72 (0.17)	0.56 (0.28)	0.47 (0.34)
TmpCont	0.86 (0.09)	0.82 (0.16)	0.84 (0.11)	0.80 (0.17)	0.81 (0.12)	0.78 (0.14)	0.75 (0.17)	0.76 (0.15)	0.54 (0.42)	0.53 (0.36)
Bor	0.90 (0.07)	0.90 (0.07)	0.92 (0.06)	0.89 (0.07)	0.90 (0.05)	0.91 (0.04)	0.86 (0.08)	0.89 (0.06)	0.59 (0.31)	0.59 (0.25)
Cold	0.56 (0.57)	0.50 (0.56)	0.49 (0.62)	0.46 (0.59)	0.84 (0.20)	0.86 (0.13)	0.50 (0.38)	0.55 (0.23)	0.47 (0.56)	0.45 (0.57)

Table C2. Median site-by-site RMSE and its standard deviation (in parentheses and estimated as reported in Jung et al., 2009) for the CO_2 fluxes per PFT and climate zones. List of acronyms: ENF, was evergreen needleleaf forest; DBF, deciduous broadleaf forest; EBF, evergreen broadleaf forest; MF, mixed forest; SHR, shrubland; SAV, savannah; GRA, grassland; CRO, cropland; WET, wetland; Trop, tropical; SubTrop, subtropical; Dry, dry and arid land; Tmp, temperate; TmpCont, temperate–continental; Bor, boreal; Cold, cold and polar environment or covered by ice.

CAT	GPP _R ($\text{gCm}^{-2} \text{d}^{-1}$)		GPP _L ($\text{gCm}^{-2} \text{d}^{-1}$)		TER _R ($\text{gCm}^{-2} \text{d}^{-1}$)		TER _L ($\text{gCm}^{-2} \text{d}^{-1}$)		NEE ($\text{gCm}^{-2} \text{d}^{-1}$)	
	RS	RS + METEO	RS	RS + METEO						
ENF	1.05 (0.60)	1.12 (0.60)	1.04 (0.59)	1.14 (0.66)	0.82 (0.50)	0.80 (0.52)	0.87 (0.60)	0.91 (0.68)	0.87 (0.51)	0.86 (0.53)
DBF	1.21 (0.78)	1.35 (0.59)	1.17 (0.68)	1.36 (0.62)	0.68 (0.26)	0.76 (0.33)	0.76 (0.33)	0.93 (0.44)	1.28 (0.39)	1.28 (0.39)
EBF	1.70 (0.55)	1.64 (0.85)	1.65 (0.70)	1.46 (0.51)	1.23 (0.69)	1.48 (0.85)	1.88 (1.23)	1.71 (0.73)	1.15 (0.48)	1.15 (0.45)
MF	0.87 (0.17)	0.76 (0.45)	0.89 (0.27)	0.97 (0.56)	0.65 (0.18)	0.73 (0.42)	0.79 (0.14)	0.79 (0.18)	0.91 (0.47)	0.81 (0.29)
SHR	0.73 (0.47)	0.78 (0.46)	0.69 (0.44)	0.77 (0.37)	0.50 (0.33)	0.70 (0.41)	0.50 (0.34)	0.55 (0.36)	0.57 (0.31)	0.52 (0.15)
SAV	0.83 (0.44)	0.81 (0.18)	0.87 (0.45)	0.84 (0.18)	0.80 (0.53)	0.68 (0.41)	0.86 (0.55)	0.77 (0.38)	0.71 (0.36)	0.69 (0.31)
GRA	1.22 (0.64)	1.22 (0.60)	1.18 (0.68)	1.20 (0.62)	1.00 (0.48)	1.01 (0.54)	0.99 (0.58)	0.95 (0.52)	0.76 (0.61)	0.85 (0.49)
CRO	1.69 (1.38)	2.30 (1.02)	1.57 (1.42)	2.24 (1.10)	0.87 (0.46)	0.90 (0.57)	0.80 (0.51)	0.98 (0.57)	1.42 (0.90)	1.44 (0.70)
WET	1.04 (0.95)	0.93 (0.77)	1.03 (0.96)	0.78 (0.53)	1.04 (0.87)	0.98 (0.82)	1.07 (0.51)	1.02 (0.51)	0.46 (0.19)	0.64 (0.26)
Trop	1.93 (0.46)	1.74 (1.01)	2.24 (0.62)	1.56 (0.78)	2.07 (0.69)	1.55 (0.87)	2.47 (0.74)	2.05 (0.43)	1.28 (0.29)	1.17 (0.46)
SubTrop	1.37 (0.55)	1.40 (0.61)	1.37 (0.56)	1.38 (0.57)	1.03 (0.46)	1.00 (0.41)	1.08 (0.36)	1.11 (0.40)	1.13 (0.63)	1.15 (0.62)
Dry	0.60 (0.24)	0.78 (0.36)	0.63 (0.16)	0.74 (0.30)	0.49 (0.10)	0.54 (0.20)	0.58 (0.26)	0.67 (0.32)	0.41 (0.13)	0.46 (0.15)
Tmp	1.73 (1.02)	1.82 (0.99)	1.73 (0.98)	1.71 (1.03)	1.09 (0.54)	1.17 (0.67)	1.24 (0.57)	1.31 (0.59)	1.43 (0.59)	1.40 (0.61)
TmpCont	1.01 (0.42)	1.29 (0.59)	1.00 (0.45)	1.26 (0.57)	0.71 (0.30)	0.75 (0.38)	0.74 (0.31)	0.79 (0.34)	0.95 (0.39)	1.02 (0.43)
Bor	0.66 (0.27)	0.70 (0.36)	0.66 (0.27)	0.67 (0.33)	0.48 (0.27)	0.47 (0.27)	0.48 (0.16)	0.45 (0.21)	0.50 (0.32)	0.48 (0.22)
Cold	0.44 (0.04)	0.58 (0.42)	0.51 (0.24)	0.46 (0.32)	0.41 (0.06)	0.23 (0.06)	0.57 (0.16)	0.29 (0.12)	0.51 (0.21)	0.54 (0.35)

Table C3. Median site-by-site absolute bias and its standard deviation (in parentheses and estimated as reported in Jung et al., 2009) for the CO₂ fluxes per PFT and climate zone. List of acronyms: ENF, was evergreen needleleaf forest; DBF, deciduous broadleaf forest; EBF, evergreen broadleaf forest; MF, mixed forest; SHR, shrubland; SAV, savannah; GRA, grassland; CRO, cropland; WET, wetland; Trop, tropical; SubTrop, subtropical; Dry, dry and arid land; Tmp, temperate; TmpCont, temperate–continental; Bor, boreal; Cold, cold and polar environment or covered by ice.

CAT	GPP _R (gCm ⁻² d ⁻¹)		GPP _L (gCm ⁻² d ⁻¹)		TER _R (gCm ⁻² d ⁻¹)		TER _L (gCm ⁻² d ⁻¹)		NEE (gCm ⁻² d ⁻¹)	
	RS	RS + METEO	RS	RS + METEO						
ENF	0.53 (0.46)	0.54 (0.56)	0.45 (0.42)	0.48 (0.50)	0.47 (0.47)	0.50 (0.54)	0.42 (0.40)	0.41 (0.43)	0.39 (0.44)	0.32 (0.36)
DBF	0.43 (0.38)	0.56 (0.59)	0.42 (0.36)	0.50 (0.52)	0.29 (0.32)	0.35 (0.35)	0.39 (0.33)	0.42 (0.34)	0.60 (0.28)	0.55 (0.30)
EBF	0.82 (0.91)	0.77 (0.50)	0.75 (0.81)	0.76 (0.48)	0.88 (0.98)	0.84 (0.72)	0.76 (0.81)	0.93 (0.65)	0.36 (0.45)	0.46 (0.44)
MF	0.47 (0.20)	0.34 (0.38)	0.38 (0.29)	0.57 (0.29)	0.39 (0.28)	0.41 (0.13)	0.37 (0.15)	0.30 (0.35)	0.34 (0.49)	0.32 (0.36)
SHR	0.38 (0.37)	0.54 (0.49)	0.38 (0.44)	0.39 (0.47)	0.36 (0.38)	0.50 (0.43)	0.31 (0.40)	0.32 (0.23)	0.27 (0.27)	0.28 (0.24)
SAV	0.42 (0.40)	0.36 (0.21)	0.35 (0.40)	0.23 (0.15)	0.43 (0.41)	0.35 (0.23)	0.42 (0.37)	0.31 (0.10)	0.23 (0.21)	0.19 (0.10)
GRA	0.60 (0.59)	0.48 (0.49)	0.60 (0.56)	0.52 (0.55)	0.38 (0.29)	0.36 (0.37)	0.44 (0.39)	0.38 (0.38)	0.17 (0.20)	0.31 (0.31)
CRO	0.47 (0.37)	0.66 (0.44)	0.36 (0.33)	0.56 (0.47)	0.29 (0.32)	0.25 (0.22)	0.29 (0.32)	0.30 (0.29)	0.41 (0.31)	0.56 (0.55)
WET	0.54 (0.64)	0.28 (0.41)	0.55 (0.62)	0.29 (0.25)	0.72 (0.35)	0.48 (0.52)	0.69 (0.29)	0.50 (0.51)	0.24 (0.19)	0.30 (0.25)
Trop	1.66 (1.31)	0.67 (0.79)	1.71 (1.23)	0.77 (0.86)	1.73 (0.88)	1.16 (1.19)	1.94 (0.81)	1.21 (0.67)	0.52 (0.57)	0.38 (0.55)
SubTrop	0.54 (0.45)	0.55 (0.43)	0.50 (0.38)	0.52 (0.55)	0.46 (0.44)	0.53 (0.47)	0.47 (0.35)	0.42 (0.37)	0.34 (0.44)	0.37 (0.34)
Dry	0.31 (0.20)	0.33 (0.26)	0.33 (0.38)	0.36 (0.29)	0.24 (0.21)	0.32 (0.35)	0.34 (0.21)	0.43 (0.26)	0.14 (0.08)	0.22 (0.14)
Tmp	0.72 (0.55)	0.77 (0.71)	0.66 (0.59)	0.63 (0.56)	0.50 (0.46)	0.47 (0.50)	0.51 (0.55)	0.41 (0.45)	0.46 (0.43)	0.51 (0.41)
TmpCont	0.45 (0.35)	0.60 (0.52)	0.39 (0.35)	0.57 (0.47)	0.37 (0.28)	0.29 (0.25)	0.37 (0.33)	0.38 (0.37)	0.35 (0.40)	0.55 (0.55)
Bor	0.36 (0.30)	0.32 (0.34)	0.32 (0.24)	0.27 (0.31)	0.32 (0.40)	0.32 (0.33)	0.31 (0.35)	0.26 (0.32)	0.27 (0.26)	0.23 (0.26)
Cold	0.07 (0.00)	0.08 (0.09)	0.08 (0.12)	0.15 (0.06)	0.34 (0.04)	0.12 (0.06)	0.34 (0.06)	0.15 (0.01)	0.37 (0.15)	0.27 (0.27)

Table C4. Median site-by-site R^2 and its standard deviation (in parentheses and estimated as reported in Jung et al., 2009) for the energy fluxes per PFT and climate zones. List of acronyms: ENF, was evergreen needleleaf forest; DBF, deciduous broadleaf forest; EBF, evergreen broadleaf forest; MF, mixed forest; SHR, shrubland; SAV, savannah; GRA, grassland; CRO, cropland; WET, wetland; Trop, tropical; SubTrop, subtropical; Dry, dry and arid land; Tmp, temperate; TmpCont, temperate–continental; Bor, boreal; Cold, cold and polar environment or covered by ice.

CAT	H		LE		Rn	
	RS	RS + METEO	RS	RS + METEO	RS	RS + METEO
ENF	0.87 (0.10)	0.86 (0.10)	0.83 (0.10)	0.84 (0.11)	0.97 (0.02)	0.97 (0.02)
DBF	0.76 (0.18)	0.74 (0.12)	0.87 (0.05)	0.87 (0.07)	0.97 (0.01)	0.97 (0.02)
EBF	0.85 (0.13)	0.82 (0.17)	0.56 (0.30)	0.52 (0.42)	0.95 (0.05)	0.96 (0.03)
MF	0.85 (0.06)	0.82 (0.10)	0.91 (0.07)	0.89 (0.06)	0.97 (0.02)	0.96 (0.02)
SHR	0.83 (0.15)	0.83 (0.17)	0.73 (0.29)	0.77 (0.23)	0.98 (0.01)	0.97 (0.01)
SAV	0.74 (0.25)	0.77 (0.26)	0.85 (0.06)	0.78 (0.11)	0.86 (0.05)	0.88 (0.10)
GRA	0.72 (0.22)	0.71 (0.22)	0.85 (0.11)	0.83 (0.16)	0.96 (0.02)	0.96 (0.02)
CRO	0.70 (0.16)	0.66 (0.18)	0.79 (0.14)	0.80 (0.14)	0.97 (0.02)	0.96 (0.02)
WET	0.81 (0.06)	0.78 (0.14)	0.86 (0.10)	0.84 (0.06)	0.94 (0.02)	0.92 (0.06)
Trop	0.52 (0.18)	0.60 (0.32)	0.56 (0.38)	0.50 (0.44)	0.86 (0.14)	0.89 (0.13)
SubTrop	0.81 (0.18)	0.82 (0.18)	0.78 (0.13)	0.80 (0.13)	0.96 (0.03)	0.96 (0.02)
Dry	0.87 (0.07)	0.86 (0.13)	0.80 (0.07)	0.79 (0.14)	0.90 (0.06)	0.93 (0.05)
Tmp	0.78 (0.14)	0.78 (0.13)	0.86 (0.11)	0.83 (0.13)	0.97 (0.02)	0.96 (0.02)
TmpCont	0.72 (0.18)	0.69 (0.18)	0.83 (0.08)	0.84 (0.09)	0.97 (0.02)	0.96 (0.02)
Bor	0.90 (0.07)	0.89 (0.08)	0.92 (0.05)	0.92 (0.03)	0.98 (0.01)	0.97 (0.02)
Cold	0.83 (0.12)	0.57 (0.19)	0.83 (0.08)	0.82 (0.07)	0.94 (0.03)	0.85 (0.13)

Table C5. Median site-by-site RMSE and its standard deviation (in parentheses and estimated as reported in Jung et al., 2009) for the energy fluxes per PFT and climate zone. List of acronyms: ENF, was evergreen needleleaf forest; DBF, deciduous broadleaf forest; EBF, evergreen broadleaf forest; MF, mixed forest; SHR, shrubland; SAV, savannah; GRA, grassland; CRO, cropland; WET, wetland; Trop, tropical; SubTrop, subtropical; Dry, dry and arid land; Tmp, temperate; TmpCont, temperate–continental; Bor, boreal; Cold, cold and polar environment or covered by ice.

CAT	H ($\text{MJm}^{-2} \text{d}^{-1}$)		LE ($\text{MJm}^{-2} \text{d}^{-1}$)		Rn ($\text{MJm}^{-2} \text{d}^{-1}$)	
	RS	RS + METEO	RS	RS + METEO	RS	RS + METEO
ENF	1.09 (0.25)	1.16 (0.25)	1.00 (0.56)	1.02 (0.55)	1.27 (0.68)	1.26 (0.57)
DBF	1.30 (0.43)	1.31 (0.38)	1.22 (0.26)	1.14 (0.46)	1.11 (0.42)	1.24 (0.41)
EBF	1.14 (0.60)	1.29 (0.76)	1.55 (0.39)	1.60 (0.46)	1.33 (0.43)	1.14 (0.56)
MF	1.18 (0.44)	1.12 (0.42)	0.82 (0.37)	1.15 (0.54)	1.14 (0.45)	1.09 (0.43)
SHR	1.21 (0.46)	1.14 (0.28)	1.12 (0.41)	1.11 (0.56)	1.37 (0.80)	1.01 (0.43)
SAV	1.23 (0.25)	1.20 (0.22)	1.32 (0.56)	1.35 (0.30)	1.10 (0.33)	1.19 (0.60)
GRA	1.14 (0.35)	1.08 (0.47)	1.09 (0.34)	1.32 (0.54)	1.48 (0.83)	1.48 (0.90)
CRO	1.24 (0.45)	1.36 (0.33)	1.51 (0.61)	1.54 (0.35)	1.24 (0.52)	1.23 (0.26)
WET	0.97 (0.36)	1.22 (0.60)	0.88 (0.13)	0.90 (0.18)	1.42 (0.51)	1.65 (0.71)
Trop	0.98 (0.51)	1.19 (0.63)	1.60 (0.52)	1.62 (0.41)	1.33 (0.73)	1.03 (0.48)
SubTrop	1.28 (0.38)	1.32 (0.46)	1.36 (0.62)	1.36 (0.53)	1.40 (0.40)	1.33 (0.49)
Dry	1.07 (0.24)	1.05 (0.50)	1.21 (0.33)	1.27 (0.52)	1.61 (0.75)	2.02 (0.93)
Tmp	1.18 (0.23)	1.15 (0.33)	1.18 (0.43)	1.17 (0.49)	1.10 (0.36)	1.14 (0.47)
TmpCont	1.30 (0.42)	1.35 (0.37)	1.25 (0.41)	1.47 (0.37)	1.17 (0.65)	1.16 (0.54)
Bor	0.98 (0.23)	1.05 (0.26)	0.70 (0.26)	0.61 (0.20)	0.88 (0.31)	1.08 (0.50)
Cold	1.03 (0.36)	1.50 (0.55)	1.00 (0.23)	1.03 (0.45)	1.47 (0.18)	2.04 (0.19)

Table C6. Median site-by-site absolute bias and its standard deviation (in parentheses and estimated as reported in Jung et al., 2009) for the energy fluxes. List of acronyms: ENF, was evergreen needleleaf forest; DBF, deciduous broadleaf forest; EBF, evergreen broadleaf forest; MF, mixed forest; SHR, shrubland; SAV, savannah; GRA, grassland; CRO, cropland; WET, wetland; Trop, tropical; SubTrop, subtropical; Dry, dry and arid land; Tmp, temperate; TmpCont, temperate–continental; Bor, boreal; Cold, cold and polar environment or covered by ice.

CAT	H ($\text{MJm}^{-2} \text{d}^{-1}$)		LE ($\text{MJm}^{-2} \text{d}^{-1}$)		Rn ($\text{MJm}^{-2} \text{d}^{-1}$)	
	RS	RS + METEO	RS	RS + METEO	RS	RS + METEO
ENF	0.44 (0.40)	0.40 (0.33)	0.42 (0.41)	0.44 (0.49)	0.78 (0.63)	0.64 (0.61)
DBF	0.60 (0.35)	0.66 (0.35)	0.57 (0.56)	0.49 (0.50)	0.38 (0.28)	0.61 (0.49)
EBF	0.38 (0.48)	0.55 (0.46)	0.97 (0.79)	0.88 (0.70)	0.88 (0.51)	0.62 (0.43)
MF	0.48 (0.40)	0.26 (0.31)	0.34 (0.40)	0.64 (0.52)	0.56 (0.45)	0.56 (0.57)
SHR	0.34 (0.43)	0.47 (0.52)	0.41 (0.41)	0.50 (0.43)	0.62 (0.76)	0.44 (0.52)
SAV	0.68 (0.35)	0.56 (0.15)	0.63 (0.80)	0.40 (0.15)	0.27 (0.22)	0.63 (0.55)
GRA	0.51 (0.39)	0.40 (0.24)	0.38 (0.38)	0.57 (0.50)	0.97 (0.81)	0.81 (1.03)
CRO	0.23 (0.21)	0.24 (0.24)	0.36 (0.38)	0.41 (0.50)	0.66 (0.58)	0.68 (0.39)
WET	0.47 (0.51)	0.67 (0.37)	0.54 (0.41)	0.38 (0.21)	0.34 (0.34)	0.83 (0.78)
Trop	0.37 (0.51)	0.67 (0.47)	0.97 (0.79)	1.24 (0.82)	0.94 (1.10)	0.63 (0.60)
SubTrop	0.58 (0.59)	0.50 (0.39)	0.62 (0.58)	0.58 (0.56)	0.83 (0.71)	0.70 (0.55)
Dry	0.68 (0.62)	0.55 (0.56)	0.21 (0.14)	0.30 (0.26)	1.06 (0.55)	1.61 (0.91)
Tmp	0.38 (0.23)	0.34 (0.31)	0.49 (0.46)	0.56 (0.54)	0.65 (0.49)	0.68 (0.58)
TmpCont	0.49 (0.41)	0.40 (0.46)	0.44 (0.51)	0.53 (0.50)	0.69 (0.72)	0.61 (0.58)
Bor	0.33 (0.32)	0.38 (0.24)	0.22 (0.16)	0.23 (0.24)	0.38 (0.27)	0.50 (0.47)
Cold	0.43 (0.46)	0.71 (0.11)	0.56 (0.31)	0.39 (0.18)	0.30 (0.29)	0.86 (0.58)

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