Supplement of

## Climate change will cause non-analog vegetation states in Africa and commit vegetation to long-term change

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## SUPPLEMENT S1

Supplementary table and figures referenced in the publication.

Table S1. Criteria used to define biome boundaries based on grid-cell level values of key variables

| Biome type | Grass <br> biomass [t/ha] <br> $[\mathrm{t} / \mathrm{ha}]$ | $\mathrm{C}_{3}: \mathrm{C}_{4}$ <br> grass <br> ratio | Total tree [\%] <br> cover <br> $[\%]$ | Forest:Savanna <br> tree cover <br> ratio |
| :--- | :---: | :---: | :---: | :---: |
| Desert | $\leq 0.5$ | - | $\leq 10$ | - |
| $\mathrm{C}_{3}$ grassland | $>0.5$ | $>0.5$ | $\leq 10$ | - |
| $\mathrm{C}_{4}$ grassland | $>0.5$ | $<=0.5$ | $\leq 10$ | - |
| $\mathrm{C}_{3}$ savanna | - | $>0.5$ | $10-80$ | $\leq 0.5$ |
| $\mathrm{C}_{3}$ savanna | - | $\leq 0.5$ | $10-80$ | $\leq 0.5$ |
| Woodland | - | - | $10-80$ | $>0.5$ |
| Forest | - | - | $>80$ | - |



Figure S1. Time series of continental-scale spatial averages of variables for RCP4.5, calculated from decadal averages of grid cells.


Figure S2. Spatial patterns of Euclidean distance between same-decade partners (SDPs) in RCP4.5 for three selected decades (2010-2019, 2050-2059, 2090-2099). Panels (a), (c), and (e) represent distance between SDPs in simulations including fire, panels (b), (d) and (f) are for SDPs from simulations excluding fire.


Figure S3. Decay of influence on full Euclidean distance between same-decade partners (SDPs) according to variable rank, and separated by variable identity. The second-most influential variable had substantially less influence on full Euclidean distance than the dominant variable, and influence of higher-ranked variables rapidly declined.


Figure S4. Spatial pattern of dominant variables with respect to Euclidean distance between same-decade partners (SDPs) for RCP8.5 for the three reference decades. Panels (a), (c), and (e) show the spatial pattern for RCP8.5 with fire, panels (b), (d) and (f) the pattern for RCP8.5 without fire.


Figure S5. Spatial pattern of dominant variables with respect to Euclidean distance between same-decade partners (SDPs) for RCP4.5 for the three reference decades. Panels (a), (c), and (e) show the spatial pattern for RCP4.5 with fire, panels (b), (d) and (f) the pattern for RCP4.5 without fire.


Figure S6. Percent deviance from the full Euclidean distance caused by the dominant variable, for same-decade partners (SDPs), by identity of most influential variable (colored boxes) and across all variables irrespective of identity (grey box). ST: savanna tree cover; FT: forest tree cover; TB: aboveground tree biomass; $\mathrm{C}_{3}: \mathrm{C}_{4}: \mathrm{C}_{3}$ to $\mathrm{C}_{4}$ grass ratio; MH : mean tree height; MaH : maximum tree height; IndT: number of tree individuals; GB: aboveground grass biomass; TC: total tree cover; ALL: all variables combined; Boxes indicate first and third quartiles, the black line the median, the black star the mean value, and whiskers extend to 1.5 times the interquartile range. Percentage values of dominant variables were combined across all decades.


Figure S7. Spatial pattern of percent deviance from full Euclidean distance caused by the dominant variable for RCP8.5, for same-decade partners (SDPs). Panels (a), (c), and (e) are for SDPs from simulations including fire, panels (b), (d) and (f) for SDPs from simulations without fire.


Figure S8. Spatial pattern of percent deviance from full Euclidean distance caused by the dominant variable for RCP4.5, for same-decapde partners (SDPs). Panels (a), (c), and (e) are for SDPs from simulations including fire, panels (b), (d) and (f) for SDPs from simulations without fire.


Figure S9. Spatial patterns of lag time between closest-decade partners (CDPs) for RCP8.5 without fire (panels (a), (c), and (e)), and residual Euclidean distance between CDPs (panels (b), (d) and (f)), for three selected decades (2010-2019, 2050-2059, 2090-2099).


Figure S10. Spatial patterns of lag time between closest-decade partners (CDPs) for RCP4.5 with fire (panels (a), (c), and (e)), and residual Euclidean distance between CDPs (panels (b), (d) and (f)), for three selected decades (2010-2019, 2050-2059, 2090-2099).


Figure S11. Spatial patterns of lag time between closest-decade partners (CDPs) for RCP4.5 without fire (panels (a), (c), and (e)), and residual Euclidean distance between CDPs (panels (b), (d) and (f)), for three selected decades (2010-2019, 2050-2059, 2090-2099).


Figure S12. Residual distance between closest-decade partners (CDPs) shown against lag time, irrespective of the transient decade in which these pairs occur. Boxes indicate first and third quartiles, the black line the median, and whiskers extend to 1.5 times the interquartile range.


Figure S13. Decay of influence on full Euclidean distance between closest-decade partners (CDPs) according to variable rank, and separated by variable identity. The second-most influential variable had substantially less influence on full Euclidean distance than the dominant variable, and influence of higher-ranked variables rapidly declined.


Figure S14. Spatial pattern of dominant variables with respect to Euclidean distance between closest-decade partners (CDPs) for RCP8.5 for the three reference decades. Panels (a), (c), and (e) show the spatial pattern for RCP8.5 with fire, panels (b), (d) and (f) the pattern for RCP8.5 without fire.


Figure S15. Spatial pattern of dominant variables with respect to Euclidean distance between closest-decade partners (CDPs) for RCP4.5 for the three reference decades. Panels (a), (c), and (e) show the spatial pattern for RCP4.5 with fire, panels (b), (d) and (f) the pattern for RCP4.5 without fire.


Figure S16. Percent deviance from the full Euclidean distance caused by the dominant variable, for closest-decade partners (CDPs), by identity of most influential variable (colored boxes) and across all variables irrespective of identity (grey box). ST: savanna tree cover; FT: forest tree cover; TB: aboveground tree biomass; $\mathrm{C}_{3}: \mathrm{C}_{4}: \mathrm{C}_{3}$ to $\mathrm{C}_{4}$ grass ratio; MH: mean tree height; MaH: maximum tree height; IndT: number of tree individuals; GB : aboveground grass biomass; TC: total tree cover; ALL: all variables combined; Boxes indicate first and third quartiles, the black line the median, the black star the mean value, and whiskers extend to 1.5 times the interquartile range. Percentage values of dominant variables were combined across all decades.


Figure S17. Spatial pattern of percent deviance from full Euclidean distance caused by the dominant variable for RCP8.5, for closest-decade partners (CDPs). Panels (a), (c), and (e) refer to CDPs from simulations including fire, panels (b), (d) and (f) to CDPs from simulations without fire.


Figure S18. Spatial pattern of percent deviance from full Euclidean distance caused by the dominant variable for RCP4.5, for closest-decade partners (CDPs). Panels (a), (c), and (e) refer to CDPs from simulations including fire, panels (b), (d) and (f) to CDPs from simulations without fire.


Figure S19. Fractions of African area covered by specific biome types, as time series stacks. Panels (a-d) show biome cover fractions for simulations with fire, panels (e-h) show biome cover fractions for simulations without fire. Biome color scheme is identical to the one used in Fig. 8, and as specified in panel a. Green: C3 savanna; Yellow: C3 grassland.


Figure S20. Overview showing the number of biome types assumed by a given grid cell (left column), the number of biome changes experienced by a given grid cell over the course of 13 decades (central column), and the ratio between number of biome changes experienced by a given grid cell and the number of biome types assumed by that grid cell (right column), for RCP8.5 simulation scenarios. A large ratio between number of biome changes and number of biome types assumed indicates a grid cell is flickering back and forth between two or more biome types, i.e., the transition is less definite than at a low ratio.


Figure S21. Overview showing the number of biome types assumed by a given grid cell (left column), the number of biome changes experienced by a given grid cell over the course of 13 decades (central column), and the ratio between number of biome changes experienced by a given grid cell and the number of biome types assumed by that grid cell (right column), for RCP4.5 simulation scenarios. A large ratio between number of biome changes and number of biome types assumed indicates a grid cell is flickering back and forth between two or more biome types, i.e., the transition is less definite than at a low ratio.

## SUPPLEMENT S2

Additional supplementary figures illustrating temporal changes of biome states, as well as differences between biome states of 5 different scenarios.

## I. Time series comparison

Figure series of Sankey diagrams that show biome change between the 2010s and 2050s, and between 2050s and 2090s, within a given scenario.


Figure S2.1. Sankey diagrams showing the change of biomes between the three decades of interest, for both RCP scenarios with fire. "T_" denotes transient scenarios, "E_" denotes equilibrium scenarios.


Figure S2.2. Sankey diagrams showing the change of biomes between the three decades of interest, for both RCP scenarios without fire. "T_" denotes transient scenarios, "E_" denotes equilibrium scenarios.

## II. Comparison between scenarios - Fire against no fire

10 Sankey diagrams showing difference in biome type between scenarios with fire and scenarios without fire for the three decades of interest (2010s, 2050s, 2090s).


Figure S2.3. Sankey diagrams showing the difference in biome type between scenarios with fire and scenarios without fire for RCP8.5, for the three decades of interest (2010s, 2050s, 2090s). "T_" denotes transient scenarios, "E_" denotes equilibrium scenarios.


Figure S2.4. Sankey diagrams showing the difference in biome type between scenarios with fire and scenarios without fire for RCP4.5, for the three decades of interest (2010s, 2050s, 2090s). "T_" denotes transient scenarios, "E_" denotes equilibrium scenarios.

## III. Comparison between scenarios - Transient against equilibrium

Sankey diagrams showing difference in biome type between transient and equilibrium scenarios for the three decades of interest (2010s, 2050s, 2090s).


Figure S2.5. Sankey diagrams showing the difference in biome type between transient and equilibrium scenarios for RCP8.5, for the three decades of interest (2010s, 2050s, 2090s). "wifi" denotes scenarios with fire, "nofi" denotes scenarios without fire.


Figure S2.6. Sankey diagrams showing the difference in biome type between transient and equilibrium scenarios for RCP4.5, for the three decades of interest (2010s, 2050s, 2090s). "wifi" denotes scenarios with fire, "nofi" denotes scenarios without fire.

Sankey diagrams showing difference in biome type between RCP8.5 and RCP4.5 for the three decades of interest (2010s, 2050s, 2090s).


Figure S2.7. Sankey diagrams showing the difference in biome type between RCP8.5 and RCP4.5 with fire, for the three decades of interest (2010s, 2050s, 2090s). "T_" denotes transient scenarios, "E_" denotes equilibrium scenarios.


Figure S2.8. Sankey diagrams showing the difference in biome type between RCP8.5 and RCP4.5 without fire, for the three decades of interest (2010s, 2050s, 2090s). "T_" denotes transient scenarios, "E_" denotes equilibrium scenarios.

## SUPPLEMENT S3

Additional video material supplementing this publication is available and can be downloaded here:

The videos show decadal time series of results in form of maps and allow detailed visual comparison of scenarios.

## SUPPLEMENT S4

In order to test whether the Euclidean distance between transient and equilibrium decade vegetation states is significantly different from zero, one would need to have another reference for comparison in order to determine a typical threshold value. A way to obtain such a reference could be to conduct several equilibrium simulations per decade and scenario, as well as several transient simulations per scenario, each with different initializations and, in the case of the equilibrium runs, differently randomized climate year sequences. This would allow determining the Euclidean distances among the decadal replicates, which then could be compared to the mean Euclidean distance between transient and equilibrium decadal replicates. If the mean Euclidean distance among decadal replicates is statistically significantly smaller than the mean Euclidean distance between transient and equilibrium decadal replicates, then one could quantitatively say the transient-equilibrium distance is different from zero. However, due to the large number of simulations required for this study, we did not conduct replicate simulations that would allow us making a direct quantitative statement. Yet, based on experience we know that the between-replicate variability of the state variables used to calculate the Euclidean distance in this study is usually a few percent at best, due to stochasticity between differently initialized runs. Therefore, as a best estimate, we altered our original simulation values, letting them randomly range between $\pm 5 \%$ difference from the actual simulation values in order to mimic typical between-replicate variability. We then, in accordance with the procedure applied to the original variables, standardized the altered variables in the same way. After that, for each grid pixel, each scenario, and each time slice (i.e., decade), we then calculated the Euclidean distance between original variable tuple and altered variable tuple. This delivered a total of 887848 Euclidean distance values overall that (artifically) represent the typical between-replicate Euclidean distance range. The mean value of this sample was $0.13 \pm 0.06$, the $95 \%$ percentile 0.23 , and the $99 \%$ percentile was 0.29 . It is therefore fairly safe to assume any Euclidean distance $>0.29$ between transient and equilibrium decades is larger than zero.

