

Components of near-surface energy balance derived from satellite soundings: ii. Noontime latent heat flux

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Abstract

20 This paper introduces a relatively simple method for recovering global fields of latent
heat flux. The method focuses on specifying Bowen ratio estimates through exploiting air
temperature and vapor pressure measurements obtained from infra-red soundings of the
AIRS (Atmospheric Infrared Sounder) sensor onboard the NASA-Aqua platform.
Through combining these Bowen ratio retrievals with satellite surface net available
energy data we have specified estimates of global noontime surface latent heat flux at the
25 1° by 1° scale. These estimates were provisionally evaluated against data from 30
terrestrial tower flux sites covering a broad spectrum of biomes. Taking monthly average
13:30 hour data for 2003, this revealed promising agreement between the satellite and
tower measurements of latent heat flux, with a pooled root mean square deviation of 79
W m⁻², and no significant bias. However, this success partly arose as a product of the
30 under specification of the AIRS Bowen ratio compensating for the under specification of
the AIRS net available energy suggesting further refinement of the approach is required.
The error analysis suggested that the landscape level variability in vegetation index (EVI)
and land surface temperature contributed significantly to the statistical metric of the
predicted latent heat fluxes.

35 **Key words:** Bowen ratio, latent heat flux, satellite sounder, AIRS, FLUXNET, tower,
eddy covariance.

1 Introduction

The specter of increasing global surface temperatures mean our ability to both monitor
and predict changes in the activity of the water cycle becomes critical if we are to
develop the adaptive capability needed to manage the effects of this change (Lawford et
40 al., 2004). As a result, significant investments have been and are being made in
developing both monitoring and modelling capacity in the related areas of water resource
management (Nickel et al., 2005), flood and drought risk assessment (Lehner et al., 2006)
and weather and climate prediction (Irannejad et al., 2003; Brennan and Lackmann,
2005). Of the various components of the water cycle, the accuracy with which
45 evaporative fluxes, E (or latent heat fluxes, λE), are both measured and hence modelled at

scales relevant to decision making has been identified as an area where greater capacity is needed, particularly in order to evaluate and hence better constrain model performance (Chen and Dudhia, 2001; McCabe et al., 2008). These scales range from 1 km to 100 km (i.e., 0.01° to 1°) in the spatial extent.

50 Satellites offer a potentially attractive source of data for calculating E at scales directly relevant to model development (from 0.01° to 1° ; Jiminez et al., 2009). Over the past 30 years a variety of schemes for specifying E using remote sensing data have been developed and used to evaluate the spatio-temporal behaviour of evaporation for field (Tasumi et al., 2005), regional (Bastiaanssen et al., 1998; Su, 2002; Mu et al., 2007; 55 Mallick et al., 2007; Jang et al., 2010) and continental scales (Anderson et al., 2007, Sahoo et al., 2011). The methods employed thus far can be categorized based on the various approaches followed to determine E. The most common approach centres on assuming a physical model of evaporation given many of the variables required to compute evaporation using these models are available directly as satellite products (e.g., 60 land surface temperature, vegetation index, albedo etc.) (Choudhury and Di Girolamo, 1998; Mu et al., 2007, 2011). The Priestley-Taylor (Priestley and Taylor, 1972) based model for estimating monthly global E relies on constraining the Priestley-Taylor parameter with meteorological and satellite based biophysical variables (fractional vegetation cover, green canopy fraction, vegetation index, etc.) (Fisher et al., 2008; 65 Vinukollu et al., 2011). In contrast, a number of studies have also tried to resolve E indirectly by estimating the evaporative fraction from the relationship between satellite derived albedo, vegetation indices, and land surface temperature (Verstraeten et al., 2005; Batra et al., 2006; Mallick et al., 2009). More recently, Salvucci and Gentine (2013) proposed a novel method for determining E based on minimizing the vertical variance of 70 relative humidity while simultaneously estimating water vapor conductance and E. A list of the widely used global and regional scale satellite based E models is listed in Table 1.

What is common to all these approaches is that they rely to a greater or lesser extent on parameterization of surface characteristics in order to derive the estimates of E and, therefore, the products from these approaches are conditional on these parameterizations.

75 For example, in schemes which exploit the Penman-Monteith equation both the
aerodynamic and surface resistance terms require some form of calibration of surface
characteristics, often involving vegetation indices, whether empirically (Mu et al., 2007)
or through linking to photosynthesis (Anderson et al., 2008). This is obviously a
confounding factor when one attempts to use these data to evaluate surface
80 parameterisations in weather, climate and hydrological models, particularly when the
models we wish to evaluate may contain very similar model descriptions for E. What is
required therefore are methods for deriving E estimates from satellite data that do not rely
unduly on surface parameterizations so that they become a valid and valuable data source
for model evaluation. One approach that appears to fulfill this requirement is where λE is
85 estimated from satellite data as a residual term in the energy balance equation (Tasumi et
al., 2005; Mallick et al., 2007). However, this approach suffers from the effects of error
propagation because all errors, including any lack of observed closure of the regional
energy budget, are lumped into the estimate of λE (Foken et al., 2006). From this we can
see that something more akin to a satellite 'observation' would be attractive.

90 Global polar orbiting sounders like AIRS (Atmospheric Infrared Sounder) provide
profiles of air temperature and relative humidity at different pressure levels from the
surface to the upper troposphere, along with several other geophysical variables (for
example surface temperature, near surface air temperature, precipitable water, cloudiness,
surface emissivity, geopotential height etc.). Profile information like this points to the
95 possibility of exploring gradient-based methods such as Bowen ratio (Bowen, 1926) to
produce large scale estimates of E. Despite having been used to refine estimate of near
surface air temperature over the oceans (e.g. Hsu, 1998), the use of Bowen ratio methods
in conjunction with satellite sounder data somewhat surprisingly appears to have been
overlooked as a method for estimating E. The reasons for this are probably be twofold.
100 Firstly, the resolutions of the temperature and humidity retrievals are assumed to be
inadequate for differential methods like this. Secondly, there can be reservations over the
applicability of the underlying assumptions of gradient methods on this scale. Although
these appear valid concerns, there are important counter arguments to consider also.
Firstly, the degree of signal integration going on at the scale of the satellite sounding

105 should help relax the requirement on signal resolution. Sounders integrate signal
horizontally over scales of thousands of square kilometres and hence benefit from strong
spatial averaging characteristics in the measurement, despite suffering from ambiguities
in the vertical integration of signal. However, this later drawback is aided by an
effectively large sensor separation in the vertical (Thompson and Hou, 1990). Secondly,
110 studies over both ocean and land indicate that the Bowen ratio method can be relatively
robust under non-ideal conditions (Tanner, 1961; Todd et al., 2000; Konda, 2004). Given
the potential benefits of having non-parametric estimates of E at the scales and spatial
coverage offered by the satellites, we argue that the possibility of using sounder products
within a Bowen ratio framework merits investigation.

115 This paper presents the development and evaluation of 1° by 1° AIRS sounder-Bowen
ratio derived latent heat flux, λE . We focus on terrestrial systems because of the
availability of an extensive tower-based flux measurement network against which we can
evaluate the various satellite derived components.

2 Methodology

2.1 Bowen ratio methodology

120 The Bowen ratio (β) is the ratio of sensible, H (W m^{-2}), to latent, λE (W m^{-2}), heat flux
(Bowen, 1926),

$$\beta = \frac{H}{\lambda E} \quad (1)$$

where λ is the latent heat of vaporization of water (J kg^{-1}) and surface to atmosphere
fluxes are positive. If the instantaneous energy balance of the plane across which H and
 λE are being considered is given by

$$\Phi = R_N - G = \lambda E + H \quad (2)$$

125 where Φ (W m^{-2}) is known as the net available energy, R_N (W m^{-2}) is the net radiation
across that plane and G (W m^{-2}) is the rate of system heat accumulation below that plane,
then combining equations (1) and (2) one gets,

$$\lambda E = \frac{\Phi}{1 + \beta} \quad (3)$$

130 Therefore, if Φ and β are available, λE can be computed (Dyer, 1974). The estimation of Φ from satellite data is covered in a companion paper (Mallick et al., 2014). β was estimated as follows.

H and λE are assumed to be linearly related to the vertical gradients in air temperature and partial pressure of water vapor, $\partial T/\partial z$ and $\partial p/\partial z$, through assuming similarity in the pathways for the two fluxes.

$$\lambda E = \rho \lambda \varepsilon k_E \frac{\partial p}{\partial z} \quad (4a)$$

and,

$$H = \rho c_p k_H \frac{\partial T}{\partial z} \quad (4b)$$

135 where ε is the ratio of the molecular weight of water vapor to that of dry air, ρ is air density (kg m^{-3}), c_p is air specific heat ($\text{J kg}^{-1} \text{K}^{-1}$), k_E and k_H are the effective transfer coefficients for water vapor and heat respectively (m s^{-1}) (Fritschen and Fritschen, 2005). If heat and water vapor occupy the same transfer pathway and mechanism through a plane then $k_E \approx k_H$ (Verma et al., 1978) and equations (1) and (4) reduce to,

$$\beta = \frac{c_p \partial T}{\lambda \varepsilon \partial p} \quad (5)$$

140 suggesting β can be estimated from the relative vertical gradient in T and p (Bowen, 1926). In the turbulent region of the atmosphere, eddy diffusivities for all the conserved scalars are generally assumed equal because they are carried by the same eddies and, therefore, are associated at source (Swinbank and Dyer, 1967). There is evidence to suggest k_H is greater than k_E under stable (early morning and late afternoon) conditions
 145 when heat gets transferred more efficiently than the water vapor (Katul et al., 1995) and when the effects of lateral advection of heat are significant (Verma et al., 1978). For the

non-neutral atmospheric conditions the turbulent efficiency for transporting water vapor is more than that for heat (Katul et al., 1995) and under such conditions k_E is greater than k_H . For the near-convective conditions (early to mid-afternoon) the ratio of k_H to k_E is unity (Katul et al., 1995).
150

AIRS soundings for T and p are available for a range of pressure levels in the atmosphere (Tobin et al., 2006). Assuming the lowest available two pressure levels $p_{1,2}$ occur within a region of the planetary boundary layer within which equations (4a and b) hold, then a finite difference approximation of equation (5) gives,

$$\beta = \frac{c_P (T_1 - T_2 + \Gamma)}{\lambda \varepsilon (p_1 - p_2)} \quad (6)$$

155 where Γ accounts for the adiabatic lapse rate in T which in this case will be significant. Here we specify Γ following equation (6.15) in Salby (1996) which when rearranged gives:

$$\Gamma = \frac{\ln(T_2/T_1)\Gamma_d}{\ln(p_2/p_1)\kappa} \quad (7)$$

where Γ_d is the dry adiabatic lapse rate ($\sim 9.8 \text{ K km}^{-1}$) and κ is the ratio of the specific gas constant ($\text{J kg}^{-1} \text{ K}^{-1}$) to the isobaric specific heat capacity ($\text{J kg}^{-1} \text{ K}^{-1}$).

160 There are typically three dominant assumptions affecting the applicability of Bowen ratio methods and the validity of these is important in the present context. The first is that the observations of the vertical gradients are dominated by vertical transport and hence the effects of advective fluxes are minimal. This is a real problem in traditional, small scale, near surface applications because the length of the vertical flux path being sampled
165 is similar to that of many of the turbulent fluxes involved in near surface heat and mass exchange. As a result, the observed vertical gradient can become partially distorted by the lateral advection of heat and water vapor (Wilson et al., 2001). In contrast, the satellite sounding data sample a radically different space with a horizontal extent varying from 0.5 degree to 1 degree. In this preliminary investigation we have opted to use the AIRS
170 sounding data where the horizontal footprint is one degree by one degree (or

approximately 100 by 100 km). For the vertical profile we exploit the 1000 and 925 mb pressure level soundings, corresponding to heights of approximately 10 and 500m. Therefore the vertical scale is nearly three and a half orders of magnitude smaller than the horizontal. Although advective fluxes occur across a range of scales in space, they are slow relative to the vertical exchange on these scales and hence should tend to distort the vertical gradient to a lesser extent than traditional Bowen towers.

The second assumption is related to the first in that the lateral advective fluxes become particularly important when the underlying land surface is heterogeneous because lateral import of heat or mass into the observation space from adjacent land patches will again distort the gradient measurements. For the reasons articulated above on the relative scales of the vertical and horizontal footprint of the sounding observations, such ‘edge effects’ should be diminished, although it is important to appreciate that the landscape heterogeneity is likely to increase with scale. Therefore, although the satellite-based method we are proposing has promise as an observation platform, relating these observations to unique surface characteristics is likely to be problematic [despite an attempt is made (Figure 6) to explain the retrieval errors in light of the vegetation biophysical heterogeneity].

The final assumption is that the land-atmosphere system is in some form of dynamic equilibrium so that the vertical gradients representing vertical fluxes and changes in storage are trivial. The soundings we utilize are for a 13:30 overpass time. Although not universally so, the turbulent boundary layer tends to be approaching its most mature by this time of day and the average depth of the turbulent boundary layer should extend well beyond the 925 mb level (Fisch et al., 2004). Therefore, the steady state assumption implicit in Bowen ratio methods (Fritschen and Simpson, 1989) is probably closest to being fulfilled. That said, the development of the turbulent boundary layer depends on the nature of the (radiative) forcing it is experiencing and there may be many circumstances when it is still evolving at the 13:30 overpass time. Although this has implications for the steady state assumption, it probably has bigger implications for the assumption that the

boundary layer has developed beyond the lowest two available soundings and hence can
200 be considered fully turbulent.

Although the system we are sampling is not the constant flux region near the surface,
in affect we have a surface source region (sampled by the 1000 mb sounding) exchanging
with a well-mixed volume (sampled by the 925 mb sounding). The flux exchange
between these two should be approximately linear and equivalent in the concentration
205 differences between the two providing we are near dynamic equilibrium (i.e. the turbulent
boundary layer isn't growing/contracting excessively) and that additional fluxes into and
out of the boundary layer (including phase changes) are small relative to the surface
sourced fluxes of heat and water vapor.

The principle difficulty as far as we can ascertain is the effect of phase changes
210 associated with cloud formation, producing latent warming of the boundary layer whilst
removing water vapor. Providing this happens above the 925 mb sounding we anticipate
it being less of a problem, but if it happens below this level then clearly this is
problematic. Of course, this also impacts on the estimation of the net available energy.

The reliability of the estimates of β also depend on the accuracy and resolution of the
215 measurements of the temperature and humidity gradients. The AIRS products are quoted
as having resolutions and accuracies of ± 1 K per km for T and ± 10 percent per km for p
(Aumann et al., 2003; Tobin et al., 2006). Given Bowen ratio studies are invariably
applied to small sensor separations of the order of meters and at the point scale,
precisions of ± 0.01 °C for temperature and ± 0.01 kPa for vapor pressure are required
220 (Campbell Scientific, 2005), making the AIRS sensitivities appear untenable. However,
as mentioned above, the effective sensor separation of the order of hundreds of meters
allied to the sounding integrating at the 10,000 km² scale should help lift these
restrictions. There are missing data segments in the AIRS sounder profiles, which are
particularly prominent at high latitudes where presumably it is difficult to profile the
225 atmosphere reliably near the surface and over the mountain belts where the lower
pressure levels are intercepted by the ground.

A general sensitivity/uncertainty analysis was carried out to assess the propagation of uncertainty through the calculation scheme onto the estimates of λE (see Mallick et al., 2014 for details).

230 **2.2 Satellite data sources**

The AIRS sounder is carried by the NASA Aqua satellite, which was launched into a sun-synchronous low Earth orbit on May 4, 2002 as part of the NASA Earth Observing System (Tobin et al., 2006). It gives global, twice daily coverage at 1:30 am-pm from an altitude of 705-km. In the present study we have used AIRS level 3 standard monthly
235 products from 2003, with a spatial resolution of 1° by 1° . The monthly products are simply the arithmetic mean, weighted by counts, of the daily data of each grid box. The monthly merged product have been used here because the infrared retrievals are not cloud proof and the monthly products gave decent spatial cover in light of missing cloudy sky data. The data products were obtained in hierarchical data format (HDF4) with associated latitude-longitude
240 projection from the NASA Mirador data holdings (<http://mirador.gsfc.nasa.gov/>). These datasets included all the meteorological variables required to realise equations (6) and (7).

2.3 Tower evaluation data

The satellite estimates of β , λE , and H were evaluated against 2003 data from 30 terrestrial FLUXNET eddy covariance towers (Baldocchi et al., 2001) covering 7
245 different biome classes. These tower sites were selected to cover a range of hydro-meteorological environments in South America, North America, Europe, Asia, Oceania and Africa. A comprehensive list of the site characteristics and the site locations are given in a companion paper (Mallick et al., 2014) which describes the specification of the satellite net available energy used here.

250 Eddy covariance has largely replaced gradient-based methods like Bowen ratio as the preferred method for tower measurements of terrestrial water vapor and sensible heat flux. Because eddy covariance is not a gradient method it is an attractive source of evaluation data. Sensible and latent heat flux measurements were used as reported in the FLUXNET data base, in other words no corrections for any lack in energy balance
255 closure (Foken, 2008; Wohlfahrt et al., 2009) were applied. The spatial scale of tower

eddy covariance footprint is of the order of $\sim 1 \text{ km}^2$ and hence are approximately four orders of magnitude smaller scale than the $10,000 \text{ km}^2$ satellite data, which obviously has implications in heterogeneous environments (see above). The most important implications for spatial heterogeneity in the present context is that, in addition to
260 complicating comparison with tower data, relating these observations to unique surface characteristics is likely to be problematic.

3 Results

3.1 Bowen ratio - evaporative fraction evaluation

Figure 1a shows the global distribution of annual average, 13:30 hour estimates for β for the year 2003 derived using the sounder method. The missing data segments are due
265 to two data rejection criteria, one of which is already mentioned in section 2.1. We have additionally imposed our own data rejection for β when there is reversal of the vertical vapor pressure gradient under high radiative load. This condition is often encountered in hot, arid settings when large scale advection causes the assumptions behind Bowen ratio methodology to become invalid (Rider and Philip, 1960; Perez et al., 1999). This
270 condition was particularly prevalent over Australia in summer 2003 (Feng et al., 2008) and hence this region is not covered particularly well.

The first thing to note from Figure 1a is that there is a clear land-sea contrast with β being relatively low and uniform over the sea as expected. The values of β over the oceans are in the region of 0.1, in line with commonly quoted figures for the sea (Betts and Ridgway, 1989; Hoen et al., 2002). Over the tropical forest regions of Amazonia and
275 the Congo β is in the range 0.1 to 0.3, which also compares with values reported for these areas (da Rocha et al., 2004, 2009; Russel et al., 2006). The more arid areas are also clearly delineated. Although somewhat variable, the Sahara gives a range of 1.5 – 3.5 which corresponds with the results of Kohler et al. (2009) and Wohlfahrt et al. (2009) for
280 the Mojave Desert. The South American savanna gives a range between 0.5 – 1 which corresponds with values reported by Giambelluca et al. (2009). One notable feature is the homogeneity of the β fields over the Americas in contrast to the heterogeneity over

Eurasia. 2003 was associated with widespread drying over Europe (Fink et al., 2004) which may explain this feature.

285 In an attempt to reassure the reader about the validity of the assumptions we are making we have first tested the proposed methodology over a surface flux measurement site of SMEX02 experiment (Kustas et al., 2005) in the central United States where both the radiosonde measurements and eddy covariance flux observations were available. Bowen ratio was estimated from the air temperature and dewpoint temperature
290 measurements of the radiosonde observations using the same methodology as described in the manuscript. We have elected to evaluate β in terms of evaporative fraction (Λ) ($= (1+\beta)^{-1}$) (Shuttleworth et al., 1989) because, unlike β , Λ is bounded and more linearly related to the tower fluxes from which it is derived ($\lambda E = \Lambda \Phi$, c.f. equation (3)). Figure 2 shows the relationship between the radiosonde and tower derived estimates of Λ and
295 reveals a fair degree of correspondence between the two. This analysis produces a significant and modest correlation ($r = 0.69 \pm 0.10^1$), reasonably low RMSE (0.11) and mean absolute percent deviation (14%) between radiosonde derived Λ and tower observed Λ .

Figure 3a shows the relationship between the satellite and tower derived estimates of
300 Λ . The evaluation in Figure 3a reveals a significant correlation ($r = 0.34 \pm 0.06^1$) between $\Lambda(\text{satellite})$ and $\Lambda(\text{tower})$, albeit one corrupted by significant variability. This is to be expected given β is defined as a ratio of either four uncertain soundings (for the satellite) or two uncertain fluxes (for the tower). Assuming both measures are co-related through some 'true' intermediate scale variable then the slope and intercept of the regression
305 relationship between the AIRS and tower observed Λ are 0.31 (± 0.02) and 0.49 (± 0.04), respectively.

The sensitivity analysis results are given in Table 2 and show a differentially higher sensitivity to the vapor pressure observations than for temperature, and a standard

¹ All uncertainties are expressed as \pm one standard deviation unless otherwise stated.

310 deviation of 0.11 on the estimates of $\Lambda(\text{satellite})$, although these results are dependent on the level of the input data given the inverse nonlinearity in equation (6).

3.2 Latent and sensible heat evaluation

Figure 1b and 3b shows the geographical distribution of the average noontime net available energy and its evaluation for the year 2003 taken from Mallick et al. (2014). The corresponding geographical distributions of λE and H are shown in Figures 1c and d. Figure 3c shows the relationship between the satellite and tower λE for all 30 evaluation sites. This gives an overall correlation of $r = 0.75(\pm 0.04)$. Assuming both the tower and satellite data are linearly co-related, linear regression between the satellite and tower λE gave $\lambda E(\text{satellite}) = 0.98(\pm 0.02)\lambda E(\text{tower})$ (offset not significant) with a root mean square deviation (RMSD) of 79 W m^{-2} (see Figure 3c). The biome specific statistics for λE are given in Table 3 which reveals correlations ranging between $r = 0.41(\pm 0.22)$ (SAV) to $r = 0.76(\pm 0.10)$ (ENF), RMSD ranging between 61 (MF) to 141 (SAV) W m^{-2} and regression gains ranging between $0.85(\pm 0.08)$ (CRO) to $2.00(\pm 0.28)$ (SAV). Higher correlations ($r = 0.65 - 0.76$) were evident over the forest sites where the tower height ranged between 40 – 65 m, followed by moderate correlation over crops (CRO) and grasses (GRA) ($r = 0.59 - 0.67$) having tower height of 5 – 10 m (Table 3). Similarly the slope of the correlation was close to unity for the forests and less than unity for CRO and GRA (Table 3) (Figure 4). The only exception was found in savanna (SAV) that showed significant overestimation and low correlation (Table 3) (Figure 4) (reasons discussed later).

330 The relationship between the satellite and tower H for all 30 evaluation sites is shown in Figure 3d. Here, $r = 0.56(\pm 0.05)$ and the regression between the satellite predicted and tower observed H produced a regression line of $H(\text{satellite}) = 0.59(\pm 0.02)H(\text{tower})$ with an RMSD of 77 W m^{-2} for the pooled data. Again, the biome specific statistics for H are given in Table 3 and reveal correlations ranging between $0.43(\pm 0.15)$ (GRA) to $0.79(\pm 0.11)$ (CRO), RMSD ranging between 52 (CRO) to 149 (SAV) W m^{-2} and regression gains ranging between $0.45(\pm 0.05)$ (SAV) to $0.93(\pm 0.06)$ (CRO). Figure 5 shows some examples of monthly time series of λE for both the satellite and the towers for a range of sites. This reveals that the seasonality in $\lambda E(\text{tower})$ is relatively well

captured in $\lambda E(\text{satellite})$ in the majority of cases with the exception of Vielsalm, Tsukuba and Skukuza. Therefore, the individual site statistics given in Table 3 largely reflect the seasonality in the tower data.

The sensitivity-uncertainty results for λE are given in Table 2 revealing a standard deviation on the estimate of λE from the ensemble of 60 W m^{-2} and significant sensitivity to the range of inputs used to calculate both β and Φ .

4 Discussion

The results in Figure 3a may be interpreted through considering the effect of noise in the satellite sounding observations on the estimation of β and hence Λ . From Table 2 we see the ensemble distribution of Λ has a significant negative skew due to taking the inverse of the noise on p_1 and p_2 (c.f. equation (6)). As a result, there will be a tendency to over specify Λ from the sounding data given the ‘true’ value will be less than the mode. Both the likelihood and the magnitude of this over specification will increase as $p_1 - p_2 \rightarrow 0$ (i.e. as $\Lambda \rightarrow 0$) because of a decreasing signal to noise ratio. This explains why $\Lambda(\text{satellite})$ and $\Lambda(\text{tower})$ diverge as $\Lambda \rightarrow 0$. An additional reason for this divergence is provided by the fact that $H(\text{satellite}) < H(\text{tower})$ due to the effects of warm air entrainment (see later).

The retrieval of λE depends heavily on Φ , hence the increase in the satellite to tower correlation seen for λE relative to Λ . Indeed, Λ is a relatively stable characteristic within site so that the variance of λE is dominated by seasonal and diurnal variations in R_N and Φ (da Rocha et al., 2004; Kumagai et al., 2005). For a detailed discussion of the efficacy of the satellite derived values of Φ we have used here, the reader is referred to Mallick et al. (2014). To summarise, in comparing the satellite derived Φ with the tower $H + \lambda E$, Mallick et al. (2014) found that their satellite estimate underestimated the tower value by, on average, approximately 10 percent, i.e. $\Phi(\text{satellite}) \approx 0.90\Phi(\text{tower})$ (see Figure 3b). Therefore, the 2 percent underestimate in $\lambda E(\text{satellite})$ seen here would indicate that we are getting an approximately 8 percent compensation error in λE , introduced by the overspecification of $\Lambda(\text{satellite})$ seen in Figure 3a.

365 Given there appears to be a widespread lack of energy balance closure of the order of
20 percent observed at most FLUXNET sites (Wilson et al., 2002), this implies a
potential systematic under specification of $\lambda E(\text{tower})$ (and/or $H(\text{tower})$). However, by the
same argument the evaluation between satellite and tower for Φ would change by a
similar amount leading to little or no net change in the overall evaluation for λE . Mallick
370 et al. (2014) found that accommodating a 20 percent imbalance in $\Phi(\text{tower})$ gave
 $\Phi(\text{satellite}) \approx 0.72\Phi(\text{tower})$ and that this lack of agreement could be explained by the
under specification of the downwelling shortwave radiation component of $\Phi(\text{satellite})$. It
is unlikely that the entire energy imbalance is attributable solely to $\lambda E(\text{tower})$ (Foken,
2008). As a result, the likely range for the pooled gain between the satellite and tower λE
375 is between 0.8 to 1.0, determined by the combination of under specification of the
satellite downwelling shortwave combined with overspecification of satellite Λ .

The monthly infrared products of AIRS are, by definition, a sample of relatively cloud
free conditions whilst the tower fluxes are for a mixture of clear and cloudy atmospheric
conditions. The inclusion/omission of cloudy conditions should have little or no impact
380 on energy partitioning ratios such as β (Grimmond and Oke, 1995; Balogun et al., 2009).
Furthermore, despite being biased low, the shortwave component of Φ specified by
Mallick et al. (2014) was for all-sky conditions whilst the IR components of Φ appeared
to be somewhat insensitive to the clear sky sampling bias. As a result, the primary
motivation for attempting to recover satellite estimates for all-sky conditions would
385 appear to be for increasing the temporal resolution of the data, and not for removing bias
from the monthly satellite estimates.

The landscape scale β (and hence Λ) estimated from sounder data relate to a location
some few hundred meters above the surface, whilst the tower data relate to heights either
meters (for GRA, CRO and SAV) to tens of meters (for EBF, MF, DF, EF) above the
390 surface. These towers are designed to operate in the constant flux portion of the planetary
boundary layer which, as a rule-of-thumb, occupies the lower 10 percent of the planetary
boundary layer and where fluxes change by less than 10 percent with height (Stull, 1988).
Above this layer there is a tendency of H to decrease with height due to the entrainment

of warm air from aloft down into the mixed layer (Stull, 1988). This could partly explain
395 the results in Figure 3d where $H(\text{satellite})$ is significantly less than $H(\text{tower})$. In contrast,
 λE often tends to be preserved with height by the entrainment dry air from aloft (Stull,
1988; Mahrt et al., 2001). While comparing ground eddy covariance fluxes with aircraft
fluxes over diverse European regions, Gioli et al. (2004) found the value of H at an
average height of 70 m was 35 percent less than those at ground level, whereas no such
400 trend in λE was observed. Similarly, Migletta et al. (2009) found H lapsed by 36 percent
as one moved from the surface to a height of 100 m. The same behaviour has also been
frequently observed in both airborne and ground-based eddy covariance measurements in
USA (e.g. Desjardins et al., 1992) and Europe (Torralba et al., 2008; Migletta et al.,
2009). Because of the differing lapse properties of λE and H one would imagine
405 $\Lambda(\text{satellite})$ should, on average, be more than $\Lambda(\text{tower})$ which, despite being somewhat
uncertain, is what we observe both in Figures 2 and 3a.

The Bowen ratio method has been seen to break down under hot, dry conditions. This
is due to large scale regionally advected sensible heat desaturating the surface and
causing the vertical vapor pressure gradient to reverse (Perez et al., 1999); a condition
410 that appeared to persist in the AIRS soundings over central Australia throughout the
summer of 2003. Under these conditions k_H can become two to three times higher than k_E
so that $k_E \neq k_H$ (Verma et al., 1978; Katul et al., 1995). Although we rejected all samples
characterised by a reversal of the AIRS vapor pressure gradient, a tendency for
 $\Lambda(\text{satellite}) < \Lambda(\text{tower})$ should be observed in the data particularly for the drier biomes.
415 However, for the SAV data $\Lambda(\text{satellite}) > \Lambda(\text{tower})$ on average (see Figure 3a) indicating
this is not a dominant effect.

The satellite derived fluxes aggregate sub grid heterogeneity (surface geometry,
roughness, vegetation index, land surface temperature, surface wetness, albedo etc.) at the
10,000 km², whereas the towers aggregate at scales of ~1 km². This approximately four
420 orders of magnitude scale mismatch is an important potential source of disagreement
between the satellite and tower observed fluxes. Although towers are often installed in
relatively homogenous terrain at the local scale, rarely can this be assumed for scales

approaching the AIRS data. In addition, characteristics such as surface wetness and temperature can still be highly heterogeneous at the local tower scale (Kustas and Norman, 1999; McCabe and Wood, 2006; Li et al., 2008) whilst also exerting significant nonlinear effects on λE (Nykanen and Georgiou, 2001). If, for example, the probability of a tower being located in either a cool/wet or hot/dry patch is even, and yet the cool/wet regions contribute disproportionately to the satellite scale latent heat flux then, on average, there clearly is a tendency for the tower observed flux to be less than its satellite counterpart (Bastiaanssen et al., 1997). Because of the diversity of nonlinear surface characteristics effects on λE a detailed evaluation on the scaling characteristics of λE lies beyond the scope of this paper. However the slope of the regression between the observed and estimated λE of individual biome category was significantly related to the average variance of EVI (Enhanced Vegetation Index) [$\mu(\sigma^2_{EVI})$] and T_S (land surface temperature) [$\mu(\sigma^2_{T_S})$] for 10 x 10 km area surrounding the tower sites (Figure 6a and 6b) ($R^2 = 0.37$ and 0.39 , respectively). The slope of regression varied systematically with the landscape heterogeneity and the results are in corroboration with Stoy et al. (2013) who also found a systematic relationship between the surface energy balance closure and landscape heterogeneity over 173 FLUXNET tower sites. One general inference can be drawn however; the degree of agreement we see in the pooled evaluation would suggest that the spatial scaling from tower to satellite appears somewhat conserved, a feature that is no doubt greatly aided by investigating the monthly average data where the effects of dynamic spatial heterogeneity (e.g. in surface wetness and surface temperature) will tend to have been averaged out. However the results in Table 3 and Figure 4 suggest that the data from the taller, more extensive forest towers are more closely related to their satellite counterparts, although the higher correlations may also reflect the dominance of net radiation in driving latent heat flux over these sites.

The pooled RMSD of 79 W m^{-2} for the λE evaluation is comparable with the results reported elsewhere. Mecikalski et al. (1999) reported RMS errors in daily λE estimates in the range of 37 to 59 W m^{-2} while estimating continental scale fluxes over the USA using GOES (Geostationary Operational Environmental Satellite) data. Anderson et al. (2008) reported an RMSD for instantaneous λE estimates of 79 W m^{-2} using a Bowen Ratio

closure method and 66 W m^{-2} using the residual surface energy balance method. Another study of Anderson et al. (2007) reported an RMSD in hourly λE of 58 W m^{-2} using 10 km^2 scale GOES data over Iowa, although this reduced to 1.7 W m^{-2} when considering cumulative daily data. Jiang et al. (2009) reported an RMSD of $23 - 40 \text{ W m}^{-2}$ for daily λE retrievals using NOAA (National Oceanic and Atmospheric Administration) AVHRR (Advance Very High Resolution Radiometer) data over southern Florida. Interestingly, they also found a significant negative correlation between satellite and ground-truth evaporative fraction. Jiang and Islam (2001) and Batra et al., (2006) reported RMSD's for noontime λE retrievals from a series of studies over the Southern Great Plains of the USA in the range of 25 to 97 W m^{-2} using moderate resolution NOAA-16, NOAA-14 and MODIS-Terra optical and thermal data. In addressing the effects of scaling and surface heterogeneity issues on λE , McCabe and Wood (2006) obtained an RMSD of 64 W m^{-2} when comparing spatially aggregated LANDSAT (Land Remote-Sensing Satellite) derived instantaneous λE and MODIS Terra λE in central Iowa. Finally, using the surface temperature versus vegetation index triangle approach with MSG (Meteosat Second Generation) SEVIRI (Spinning Enhanced Visible and Infrared Imager) data, Stisen et al. (2008) obtained an RMSD of 41 W m^{-2} for daily data over the Senegal River basin. Finally, Prueger et al. (2005) obtained a disagreement of 45 W m^{-2} in instantaneous noontime λE while comparing 40 m aircraft and 2 m ground eddy covariance λE measurements again in central Iowa. Some additional studies also reported RMSD of monthly fluxes (for example, Cleugh et al., 2007; Mu et al., 2011). In these studies daily λE was modeled using daily radiation and meteorological variables and monthly fluxes were generated from the daily averages. Cleugh et al. (2007) reported RMSD of 27 W m^{-2} over two contrasting sites in Australia using tower meteorology and MODIS vegetation index over the eddy covariance footprints. Mu et al. (2007, 2011) reported RMSD of $8 - 180 \text{ W m}^{-2}$ on eight-day average λE and 12 mm on monthly average λE .

5 Conclusions

We conclude that the combination of the satellite sounding data and the Bowen ratio methodology shows significant promise for retrieving spatial fields of λE when compared with tower ground truth data, and warrants further investigation and refinement. The

specification of satellite net available energy, and its shortwave component in particular, requires further attention. There are also circumstances where the satellite Bowen ratio method is inapplicable, but these conditions could be easily flagged by internal checks on the sounding profiles. Where the method appears to work, this provides estimates of λE that would prove valuable in a range of applications. In particular, because no land surface model has been involved in their derivation, the estimates of λE we show can be used as independent data for evaluating land surface parameterisations in a broad range of spatially explicit hydrology, weather and climate models. Furthermore, the availability of sounding data at both 1° and 5 km resolution in conjunction with tower and scintillometer surface flux data would provide an excellent opportunity to explore robust scaling methods in these same models.

Given the Bowen ratio method should work best in the non-limiting water environments the sea estimates of latent heat we show here are potentially more reliable than their terrestrial counterparts.

The advent of microwave sounding platforms such as Megha Tropiques may afford an opportunity to extend the methodology to persistent overcast conditions, allowing for more detailed process studies. This approach could also exploit high spatial and temporal resolution geostationary sounder platforms like GOES and, in the near future, GIFTS (Geosynchronous Interferometric Fourier Transform Spectrometer) and INSAT (Indian National Satellite)-3D. We also expect that the high vertical resolution soundings these platforms will provide will improve the accuracy of the current approach, particularly over elevated terrain.

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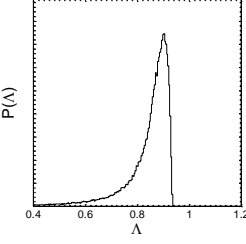
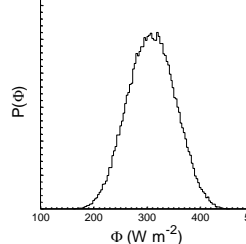
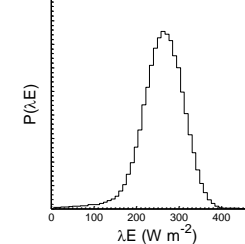
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Table 1. A list of satellite based evapotranspiration models.

Model name	Modeling approach	Input variables	Reference
ALEXI/TSEB	Two source aerodynamic model	$R_N, G, T_S, W_S, L_{AI}, f_C$	Anderson et al. (2007) Norman et al. (1995)
SEBS	Single source aerodynamic model	$R_N, G, T_S, T_A, W_S, L_{AI}, f_C$	Su (2002)
SEBAL	Single source aerodynamic model	$R_N, G, T_S, T_A, W_S, L_{AI}, f_C$	Bastiaanssen et al. (1998)
METRIC	Single source aerodynamic model	$R_N, G, T_S, T_A, W_S, L_{AI}, f_C$	Tasumi et al. (2005)
RHvariance	Single source Penman-Monteith model	R_N, G, R_H, T_A, W_S	Salvucci and Gentine (2013)
PM-MOD16	Three source Penman-Monteith model	$R_N, G, R_H, T_A, L_{AI}, f_C$	Mu et al. (2007)
PTJPL	Three source Priestley-Taylor model	$R_N, G, R_H, T_A, L_{AI}, f_C$	Fisher et al. (2008)
EF_{VI-T_S}	Two dimensional scatter between T_S and VI	R_N, G, T_S, T_A, VI	Batra et al. (2006)
EF_{alb-T_S}	Two dimensional scatter between T_S and albedo	$R_N, G, T_S, T_A,$ albedo	Verstraeten et al. (2005)

R_N = net radiation; G = ground heat flux; T_S = land surface temperature; VI = vegetation index; L_{AI} = leaf area index; f_C = fractional vegetation cover; T_A = air temperature; R_H = relative humidity; W_S = wind speed.

Table 2. Sensitivity analysis results of Λ , Φ and λE . The forcing data are taken for mid-summer, Southern Great Plains, US. Sensitivities are locally linear averaged across the ensemble response and expressed as dimensionless relative changes. Only absolute sensitivities > 0.1 are shown. $N = 10^5$ realisations.

		Λ	Φ (W m^{-2})	λE (W m^{-2})
x	sample range	dΛ/dx	dΦ/dx	dλE/dx
τ_A	$\pm 10\%$	-	1.58	1.56
f	$\pm 10\%$	-	-0.94	-0.92
α	$\pm 10\%$	-	-0.31	-0.29
ϵ_S	$\pm 10\%$	-	-0.37	-0.34
ϵ_A	$\pm 10\%$	-	1.19	1.20
T_S	± 1 K	-	-0.21	-0.19
T_{925}	± 1 K	0.45	-	0.54
T_{1000}	± 1 K	-0.46	-	-0.45
p_{925}	$\pm 10\%$	1.23	-	1.22
p_{1000}	$\pm 10\%$	-1.04	-	-1.02
				
standard deviation		0.11	44 W m^{-2}	60 W m^{-2}

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τ_A = atmospheric transmissivity; f = cloud cover fraction; α = surface albedo; ϵ_S = surface emissivity; ϵ_A = air emissivity; T_S = land surface temperature; T_{925} = air temperature at 925 mb sounding; T_{1000} = air temperature at 1000 mb sounding; p_{925} = partial pressure of water vapor at 925 mb sounding; p_{1000} = partial pressure of water vapor at 1000 mb sounding.

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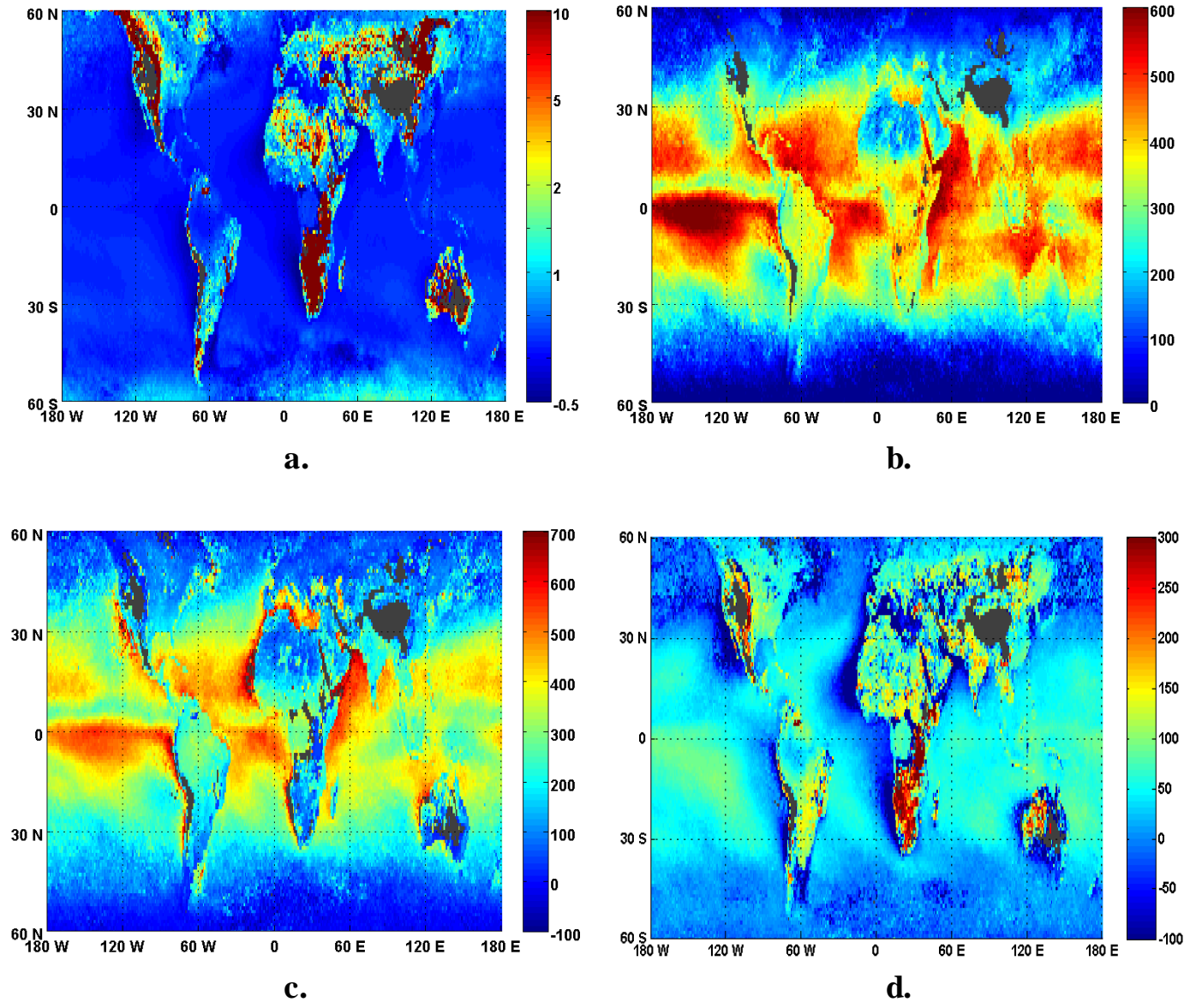
Table 3. Error analysis of AIRS derived λE and H over diverse plant functional types (biomes) of FLUXNET eddy covariance network. Values in the parenthesis are \pm one standard deviation unless otherwise stated.

Biome	Average tower height (m)	λE				H			
		RMSD (Wm^{-2})	Slope	r	N	RMSD (Wm^{-2})	Slope	r	N
EBF	60	84.84	1.02 (± 0.04)	0.70 (± 0.09)	65	53.2	0.64 (± 0.03)	0.73 (± 0.09)	66
MF	40	60.66	0.92 (± 0.09)	0.65 (± 0.14)	32	87.9	0.50 (± 0.04)	0.67 (± 0.14)	30
GRA	5	78.39	0.87 (± 0.08)	0.67 (± 0.12)	42	55.82	0.79 (± 0.09)	0.43 (± 0.15)	39
CRO	10	69.76	0.85 (± 0.08)	0.59 (± 0.15)	31	51.74	0.93 (± 0.06)	0.79 (± 0.11)	31
ENF	35	67.64	1.02 (± 0.07)	0.76 (± 0.10)	43	95.14	0.52 (± 0.04)	0.62 (± 0.13)	37
DBF	40	65.19	0.86 (± 0.06)	0.68 (± 0.09)	74	73.19	0.59 (± 0.04)	0.49 (± 0.11)	70
SAV	23	140.78	2.00 (± 0.28)	0.41 (± 0.22)	19	148.52	0.45 (± 0.05)	0.51 (± 0.22)	18
Pooled	-	78.74	0.98 (± 0.02)	0.75 (± 0.04)	306	76.94	0.59 (± 0.02)	0.56 (± 0.05)	291

N = number of data points falling under each biome category.

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EBF = Evergreen broadleaf forest, MF = Mixed forest, GRA = Grassland, CRO = Cropland, ENF = Evergreen needleleaf forest, DBF = Deciduous broadleaf forest, SAV = Savanna



815 **Figure 1.** Global fields of yearly average 13:30 hour derived from AIRS sounder observations for 2003. **a.** Bowen ratio β ($\text{W m}^{-2} / \text{W m}^{-2}$). **b.** Net available energy, Φ (Wm^{-2}). **c.** Latent heat flux, λE (Wm^{-2}). **d.** Sensible heat flux, H (Wm^{-2}). Missing data are marked in grey.

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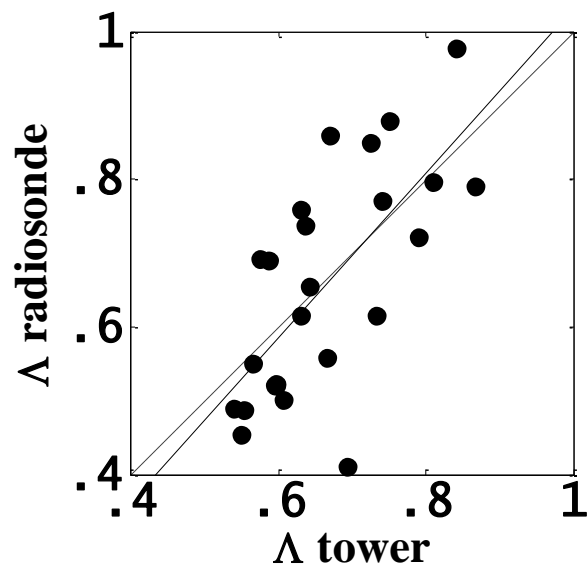
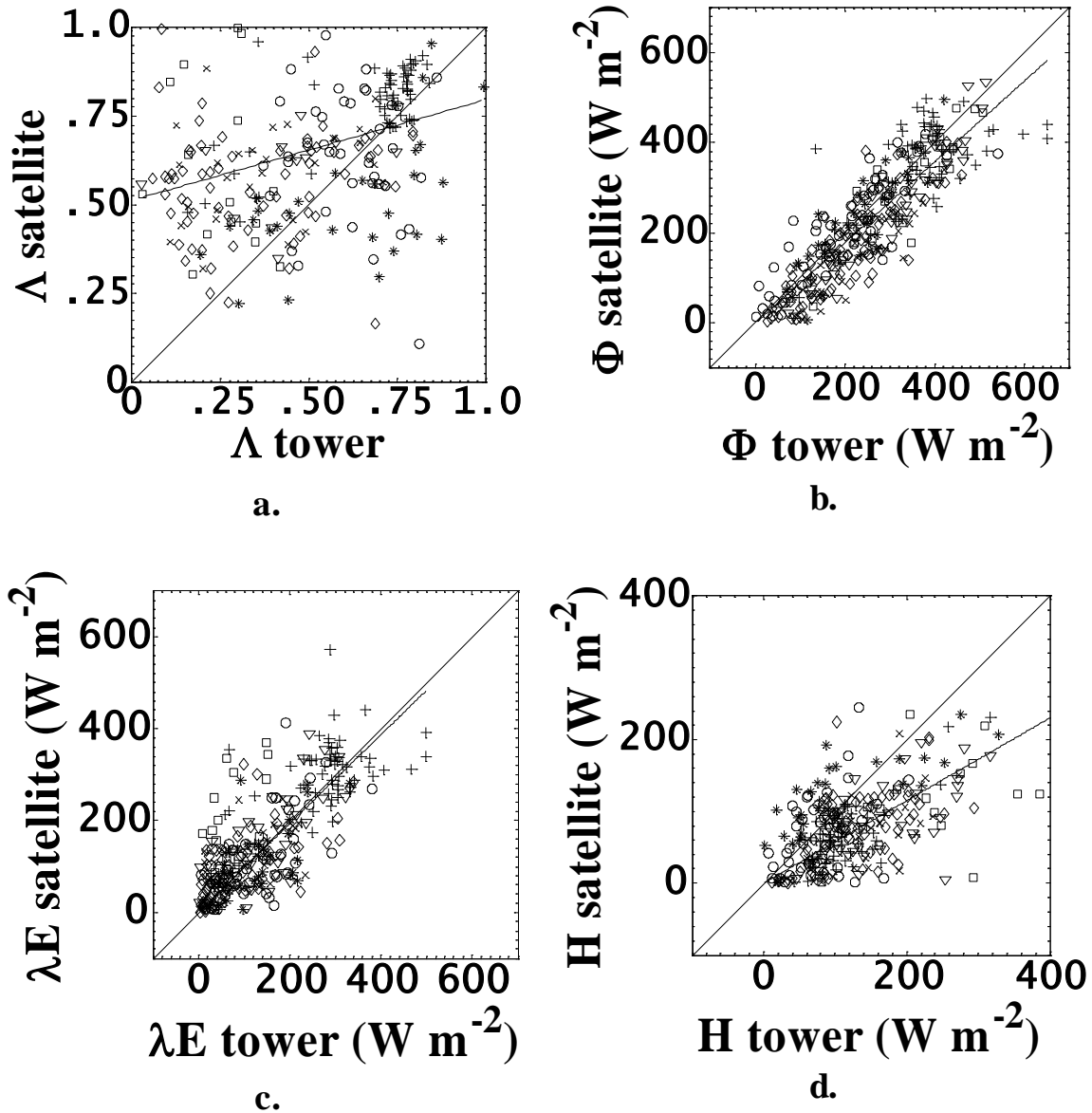


Figure 2. Evaluation of the radiosonde derived evaporative fraction, Λ . This produces a correlation of 0.69 ($R^2 = 0.48$) and a regression line (solid black line) of $\Lambda(\text{radiosonde}) = 1.12(\pm 0.24)\Lambda(\text{tower}) - 0.08(\pm 0.16)$.



830 **Figure 3.** The evaluation of the AIRS derived monthly 13:30 hour components against their tower equivalent. **a** Evaporative fraction, Λ . Here, the solid regression line denotes $\Lambda(\text{satellite}) = 0.31(\pm 0.02)\Lambda(\text{tower}) + 0.49(\pm 0.04)$. **b** Net available energy, Φ . Here, the solid regression line denotes $\Phi(\text{satellite}) = 0.90(\pm 0.03)\Phi(\text{tower}) - 2.43(\pm 8.19)$ (see Mallick et al., 2014). **c** latent heat flux, λE . **d** Sensible heat flux, H . For regression statistics see Table 3. 1:1 line is shown for reference.

835 EBF = Evergreen broadleaf forest, MF = Mixed forest, GRA = Grassland, CRO = Cropland, ENF = Evergreen needleleaf forest, DBF = Deciduous broadleaf forest, SAV = Savanna

(+ EBF; x MF; o GRA; * CRO; v ENF; diamond DBF; square SAV)

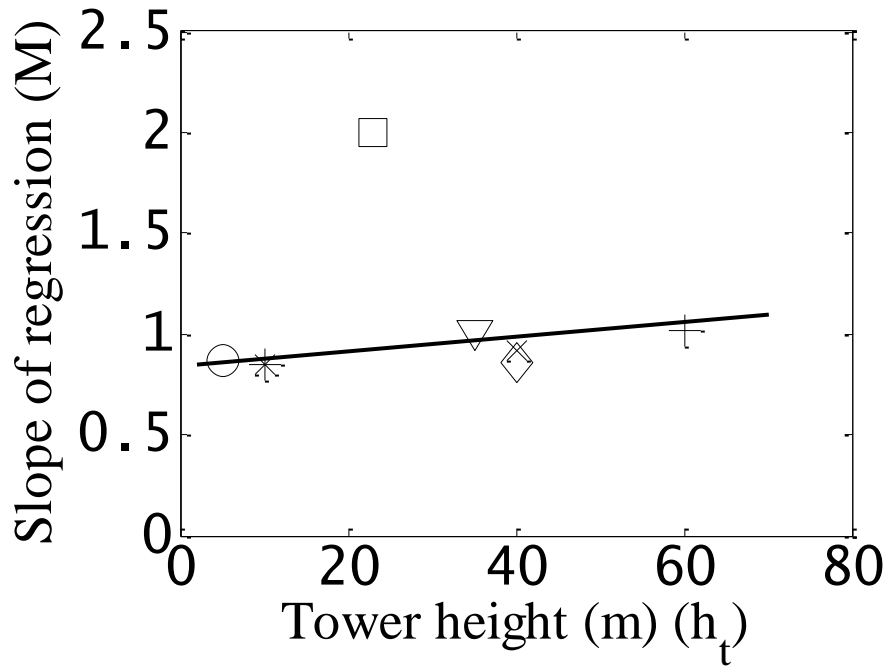


Figure 4. Scatterplot showing the slope of regression (M) between the observed and estimated λE as a function of the corresponding λE measurement height (tower height, h_t) for different biome classes. The tower heights of similar biomes are averaged. The solid line is the best fit relationship ($M = 0.003h_t + 0.84$, $R^2 = 0.46$) after removing the SAV biome type. This shows M approaches unity with h_t .

(+ EBF; x MF; o GRA; * CRO; ∇ ENF; ◇ DBF; □ SAV)

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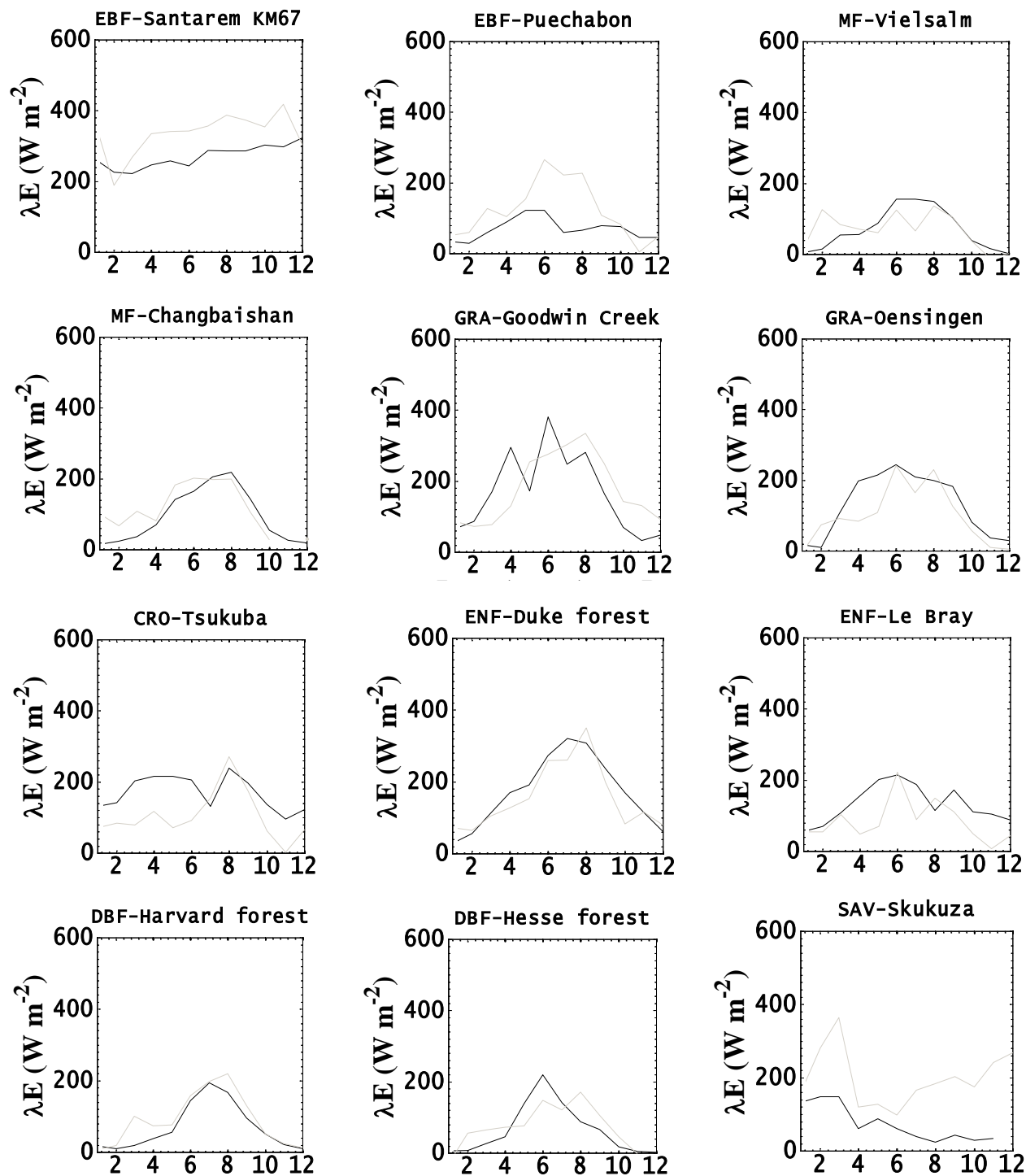


Figure 5. Satellite (grey) and tower (black) time series of monthly average 13:30 hour latent heat flux, λE , for a selection of sites for 2003. The numbers in the x-axis are the month numbers 850 indicating January (as month number 1) to December (as month number 12).

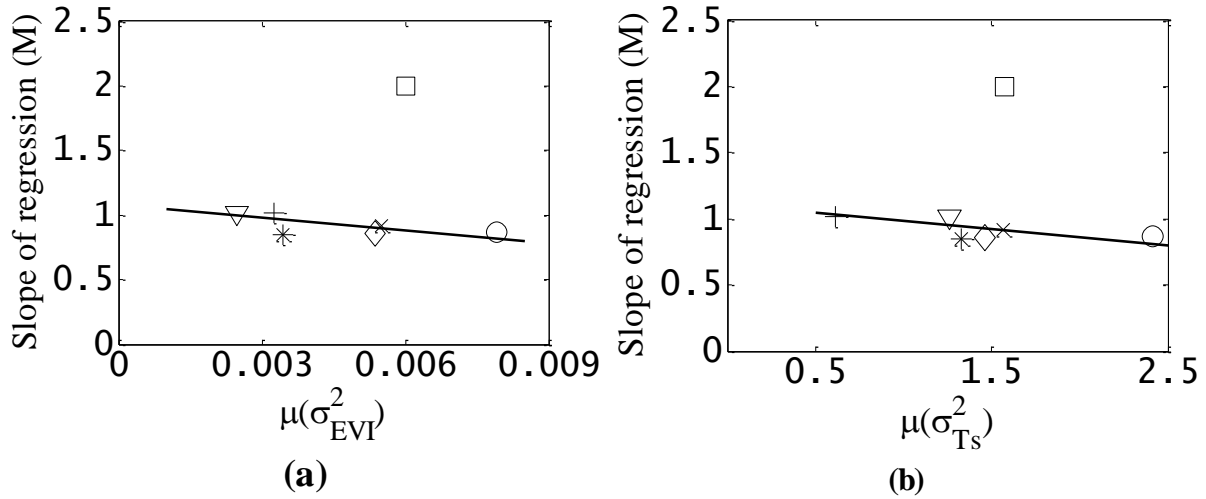


Figure 6 (a & b). Scatterplot showing the slope of regression between the observed and estimated λE as a function of the mean variance of EVI and T_S for 10 x 10 km area surrounding the tower sites of each biome categories. Variances of individual sites falling under each biome are averaged. The solid lines are the best fit relationships ($M = -23.90\mu(\sigma^2_{EVI}) + 1.03$, $R^2 = 0.37$; $M = -0.08\mu(\sigma^2_{TS}) + 1.04$, $R^2 = 0.39$) after removing the SAV biome type. This shows M approaches unity with increasing homogeneity.

(+ EBF; x MF; o GRA; * CRO; ∇ ENF; ◇ DBF; □ SAV)