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An inversion approach for determining production depth and temperature sensitivity of soil respiration

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Abstract

Physical soil properties create lags between temperature change and corresponding soil responses, which obscure true Q_{10} values and other biophysical parameters such as depth of production. This study examines an inversion approach for estimating Q_{10} and depth of production (Z_p) using physically based soil models, constrained by observed high-frequency surface fluxes and/or concentrations. Our inversion strategy uses a 1-D multi-layered soil model that simulates realistic temperature and gas diffusion. We tested inversion scenarios on synthetic data using a range of constraining parameters, time averaging techniques, mechanisms to improve computational efficiency, and various methods of incorporating real data into the model. Overall, we have found that with carefully constrained data, inversion was possible. While inversions using exclusively surface flux measurements could succeed, constraining the inversion using multiple shallow subsurface CO_2 measurements proved to be most successful. Inversions constrained by these shallow measurements returned Q_{10} and Z_p values with average errors of 1.85 and 0.16 % respectively. This work is a first step toward building a reliable framework for removing physical effects from high frequency soil CO_2 data. Ultimately, we hope that this process will lead to better estimates of biophysical soil parameters and their variability on short timescales.

1 Introduction

Soil respiration, which includes both root and microbial respiration, represents the largest outward flux of CO_2 from terrestrial ecosystems, with a magnitude far above that of anthropogenic emissions (Raich et al., 2002). Small changes in the soil CO_2 flux could therefore have a significant impact on the carbon balance and global atmospheric CO_2 concentrations. In predictions of atmospheric CO_2 over the 21st century, uncertainties surrounding the response of land flux to climate change are second only to uncertainties surrounding future anthropogenic emissions (Meir et al., 2006). In or-

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der to accurately predict future atmospheric CO₂ concentrations, it is crucial to gain a better understanding of how land systems will respond to changing temperature and moisture regimes.

Soil CO₂ production originates from plant root respiration and microbial decomposition of organic matter. The temperature sensitivity of soil respiration describes how the flux of CO₂ from soils will respond to a change in temperature. Normally soil microbial and plant root processes are treated together because they are not readily distinguished from one another. Temperature sensitivity is often quantified by a parameter Q_{10} , which describes the factor increase in soil respiration with a temperature increase of 10 °C. This Q_{10} parameter is used in global climate models to quantify soil feedbacks to climate change. It has been found that Q_{10} values are influenced by a range of environmental factors including soil temperature (Lloyd and Taylor, 1994; Luo et al., 2001), soil volumetric water content (Davidson et al., 1998; Reichstein et al., 2002) and soil organic matter content (Taylor et al., 1989; Wan and Luo, 2003). As these factors exhibit high spatial heterogeneity across ecosystems as well as within a given ecosystem, it has long been expected that Q_{10} will also exhibit high spatial variability. Despite this, most existing models continue to use a globally constant Q_{10} value. This may reduce or enhance predicted release of CO₂ from soils, leading to large over- or under-estimates of the contribution of soil respiration to terrestrial CO₂ flux in the face of climate change. There has been considerable debate over the usage and magnitude of Q_{10} (Davidson et al., 2006; Mahecha et al., 2010), with different studies producing widely variant values. While most studies agree that CO₂ flux feedback will be positive, there is no consensus on how best to estimate the magnitude of Q_{10} .

Historically, Q_{10} values have been determined through regression analysis of soil temperature and CO₂ surface flux measurements. A known source of error in this approach originates in the physics of soil heat and gas transport, which might separate a change in surface soil temperature (normally a 5 or 10 cm temperature is used for deriving Q_{10}) from the resultant change in CO₂ flux measured at the surface. The lags depend most heavily on soil heat transport (Phillips et al., 2011), because changes

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in surface temperature are shifted and dampened significantly as a function of depth, with each successive soil layer experiencing a reduced temperature change in amplitude. Gas diffusion also plays an important role, and even if soil microbes and roots produced CO_2 instantaneously upon receipt of thermal energy at the characteristic production depths, gases still take time to diffuse upward. Soil properties including heat and gas diffusion, and the production depth (Z_p), all contribute to these lags (Fig. 1). Phillips et al. (2011) demonstrated that such lags can lead to severe misinterpretation of data when attempting to extract true Q_{10} values through regression of surface flux and a temperature measurement at a single depth.

These thermal and gas diffusion processes, and the resulting lags, can be captured in a simple 1-D physical heat and gas transport soil model (Nickerson and Risk, 2009; Phillips et al., 2011). Though not done to date for the soil respiration system, it is possible to use such a model in inverse fashion for estimating the value of parameters like Q_{10} and Z_p by looping the forward model iteratively through possible parameter combinations, with observed measurements as a constraint. Normally, an objective function is used for helping decide which parameter set best minimizes the difference between modelled and measured data. This method has been identified as a promising tool for determining unknown soil parameters (Zhou et al., 2009), with an increasing availability of high frequency data sets allowing for rigorous constraints on known model parameters.

This study seeks to develop a reliable inversion framework for determining the Q_{10} and Z_p of different sites given continuous soil measurements. It also seeks to provide guidance for researchers who would like to build field observational sites suited for inversion analysis. Working exclusively with synthetic soil data that mimics the form of collected field data and of which all parameters are known, we first undertake sensitivity tests to determine optimal sensor placing in the field, and decide whether soil CO_2 surface flux, and/or profile measurements, are more suited for anchoring inversion approaches with the necessary field data for parameter constraint. Using the best

and dampened through the soil profile using:

$$T[i] = T_{\text{avg}} + \Delta T_D e^{\frac{-z_i}{d_{Td}}} \sin\left(\omega_D t - \frac{-z_i}{d_{Td}}\right) + \Delta T_Y e^{\frac{-z_i}{d_{Ty}}} \sin\left(\omega_Y t - \frac{-z_i}{d_{Ty}}\right) \quad (2)$$

$$d_{Td} = \sqrt{\frac{2D_T[i]}{\omega_D}}, \quad d_{Ty} = \sqrt{\frac{2D_T[i]}{\omega_Y}} \quad (3)$$

which simulates the lags related to the rates of thermal diffusion. In this equation, T_{avg} is the average temperature in the air and soil profile for the duration of the simulation, ΔT_D is the amplitude of the daily temperature fluctuation, ΔT_Y is the amplitude of the yearly temperature fluctuation, ω_D is the radial frequency for daily oscillations ($\omega_D = 2\pi/86400$ s), ω_Y is the radial frequency for annual oscillations, z_i is the layer depth (m), and D_T is the thermal diffusivity of the soil ($\text{m}^2 \text{s}^{-1}$).

Biological CO_2 production in each layer is calculated using an exponentially decreasing function (Nickerson and Risk, 2009):

$$P[i] = \frac{\Gamma_0}{\sum_{i=1}^N e^{\frac{-z_i}{d_p}}} e^{\frac{-z_i}{d_p}} Q_{10}^{\frac{T[i]-T_{\text{avg}}}{10}} \quad (4)$$

where Γ_0 is the total basal soil production ($\mu\text{mol m}^{-3} \text{s}^{-1}$), N is the number of soil layers, Q_{10} is the temperature sensitivity of soil respiration, z_i is the depth of the layer (m) and Z_p is the depth of production (m), defined as the depth below which the total fraction of CO_2 production remaining is $1/e$ (also called the e-folding depth).

Initially, the diffusivity of CO_2 in the soil profile is calculated using the Millington Model (Millington, 1959), an empirically derived approximation for calculating diffusivity in the field:

$$D_c = \frac{\theta_w^{\frac{10}{3}} \frac{D_{fw}}{H} + \theta_g^{\frac{10}{3}} D_{fg}}{\theta_T^2} \quad (5)$$

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D_{fw} and D_{fg} are the diffusivity of CO_2 in free water and free air ($\text{m}^2 \text{s}^{-1}$), H is the dimensionless form of Henry's solubility constant for CO_2 in water, and θ_w , θ_g and θ_T are the water filled, air filled and total soil porosities, respectively.

At each time step, the diffusivity of each soil layer is calculated using a temperature correction on this Millington diffusivity:

$$D[i] = D_c \left(\frac{T[i]}{T_{\text{avg}}} \right)^{1.75} \quad (6)$$

As previously mentioned, the flux from each layer is determined by Fick's first law, written explicitly as:

$$F[i] = D[i] \frac{(C[i] - C[i - 1])}{dz} dt \quad (7)$$

where $C[i]$ is the CO_2 concentration of layer i ($\mu\text{mol m}^{-3}$), $C[i - 1]$ is the concentration of the layer above, and dt is the time step (s).

Finally, at each time step CO_2 concentration in each layer i is calculated using:

$$C[i] = \frac{C_{t-1} \theta_g dz - F[i] + F[i + 1] + P[i]}{\theta_g dz} \quad (8)$$

where $C_{t-1}[i]$ is the layer concentration at the previous time step, $F[i]$ is the flux of CO_2 leaving layer i , $F[i + 1]$ is the flux of CO_2 entering the layer from the layer below, $P[i]$ is the CO_2 production within layer i .

2.2 Model execution and validation

Before beginning the simulation, the system is initialized using input parameters seen in Table 1. Atmospheric CO_2 concentration remains constant for the duration of the

simulation; it is assumed that any flux from the soil will quickly dissipate into the atmosphere. Flux from the bottom soil boundary is set to zero, as production at this depth is negligible according to the exponentially decreasing production function. These system parameters were changed depending on the soil type being simulated.

After initialization, the system undergoes spin-up, during which layer temperatures are held constant at their initial values, and the model is run until the CO₂ concentration in each layer is constant. The duration of the spin up period is dependent on soil diffusivity (and therefore θ_w), and is determined by plotting concentration vs time through the soil profile. This period ranges from 5 to 23 model days within the range of θ_w (0.1 to 0.25). The CO₂ concentration in each layer after spin up is the initial layer concentration at the beginning of the actual simulation.

For each modelled time step ($dt = 1.0$ s), temperature, CO₂ diffusivity, CO₂ production and CO₂ flux are calculated in each soil layer. Every soil layer is then revisited, and the new CO₂ layer concentrations are calculated. The progress of the simulation is monitored by outputting the CO₂ concentration and temperature of specified layers.

2.2.1 Validation

To ensure the model was performing correctly, steady state concentrations through depth (following spin-up) were compared to the steady state solution proposed by Cerling (1984). Daily and yearly temperature fluctuations were removed from the model, and the model was run until CO₂ concentrations in each layer were constant. Deviations of modelled from analytic concentrations were found to be far less than 1 %.

2.3 Incorporating external data

In order to model soil conditions at field sites, real soil measurements must be used to drive the simulation. Measurements of temperature through depth, soil volumetric water content, CO₂ surface flux and CO₂ concentrations take place at 1800 s intervals in the field. Soil temperature is an explicit model driver, while CO₂ surface flux and con-

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centration are used as model constraints. soil volumetric water content is not formally incorporated as a driver of respiration, so simulations are performed over periods of constant soil volumetric water content. Soil volumetric water content is also assumed to be constant through the soil profile.

5 Accurately modelling soil temperature through depth and time is crucial, as temperature is the known determinant of soil lags (Phillips et al., 2011). For each set of temperature measurements through depth, a linear regression (in R) is performed, resulting in a 5th order polynomial for temperature through depth every 1800 s. A linear interpolation through time is performed to obtain temperature values in each layer for
10 every modelled time step. The resultant temperature values replace our originally sinusoidally varying temperature function in the model. The value of thermal diffusivity is implicitly built into these measurements and is no longer required as a direct model input.

2.4 Inversion process

15 The soil profile CO₂ concentrations and soil CO₂ surface flux are outputs of the simulation. Their values are dependent on all of the system input parameters. A method called inverse parameter estimation is employed to determine the values of Q_{10} and depth of production that would have given rise to the observed concentrations and fluxes. Through this process, model outputs are compared to measured field data or
20 synthetic data over a range of model input parameters. The field measurements used in this process will be referred to as the model constraints; these constraints consist of CO₂ concentration measurements at various depths in the soil profile, as well as CO₂ surface flux measurements.

2.4.1 Inversion steps

25 The model is run for Q_{10} values ranging from 1 to 5.5 in steps of 0.1, and Z_p from 0.02 to 0.3 m in steps of 0.01 m. This results in a total of 1260 parameter combinations.

Inversion seeks to identify the parameter set that minimizes the objective function

$$\sqrt{(S_1 - M_1)^2 + (S_2 - M_2)^2 + (S_3 - M_3)^2 + \dots} \quad (9)$$

where S_i and M_i correspond to modelled and measured CO₂ concentrations at various profile depths. For each parameter set, this objective function is calculated every 1800 timesteps and averaged at the end of the simulation. The pair that minimizes Eq. (9) is output as the inversion result.

2.5 Validation of the inverse method

Before applying the inversion method to real field data, tests must be done to ensure method accuracy, and this manuscript focuses on such tests. We created synthetic timeseries using the original soil model, that mimic the form of real data sets. The values of Q_{10} and Z_p were known for each synthetic timeseries, as these parameters are required to run the model. This synthetic data included temperature measurements at six depths in the profile, volumetric water content, CO₂ surface flux and CO₂ concentration measurements at various depths in the soil profile.

The inverse method was applied to these synthetic data sets, and the output value of Q_{10} and Z_p could then be compared to the actual values of these parameters used to create the timeseries.

2.5.1 Constraint, sensitivity, and random error testing

To determine which model constraints resulted in the highest accuracy of the inversion method, the error (Eq. 9) was calculated using a large range of constraining parameters and combinations thereof. A total of 35 different constraint combinations were tested, representing various combinations of surface CO₂ flux, and subsurface CO₂ concentration measurements up to 0.6 m depth. These combinations are illustrated in Table 2. Testing which constraints consistently returned the most accurate values of Q_{10} and Z_p aids in determining optimal sensor placing the field.

ments alone are less suited for elucidating information on depth of production, whereas a combination of shallow and deep measurements is best for reconstructing the distribution of CO₂ production in the soil profile.

In examining inversion accuracy for both parameters Q_{10} and Z_p simultaneously (Fig. 3), we found that multiple concentration measurements shallow in the soil (≤ 15 cm), or combinations shallow in the soil with one deep concentration measurement (≥ 30 cm) were the best constraints. Deep soil measurements and surface flux constraints should therefore be avoided if the aim is the minimize overall error. This overall result is a combination of what was found for Q_{10} and Z_p individually, where shallow measurements were best for Q_{10} and a combination of shallow and deep measurements resulted in most accurate Z_p .

Depending on error tolerance for the final parameter estimates, it is conceivable that the accuracy of all inversions performed here might be sufficient for the community of soil scientists. Out of the 35 combinations tested, 19 resulted in an overall average error less than 5%. The top constraint (measurements at 5, 10 and 15 cm) had an average error of 2.01%, and the top 6 combinations all had error less than 3%. These errors are small compared to the degree of random error in CO₂ flux studies (Lavoie et al., 2015). These results are summarized in Table 4, where the top and bottom 5 combinations are listed individually and overall.

This assessment was performed using synthetic data, and even the most ideal field settings will depart from these modelled profiles. For example, we represented CO₂ production through depth using an exponential production function, but a field site may show a linear decrease in production at increasing depths. Clearly users of the inversion process will want to characterize as many site-specific parameters as possible so as to provide proper guideposts and constraints for the inversion, otherwise additional error will be introduced. The sensitivity of the inversion to error is an important question, and will be addressed in a later section.

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3.2 Effect of soil-specific parameters on inversion success

Having determined the best CO₂ sensor concentration measurement depth to constrain inversions, we can examine how site-specific parameters such as soil diffusivity, depth of CO₂ production and Q_{10} affect inversion results. For this assessment, we will use the best performing measurement configurations established. Even when not a top choice, we will always include CO₂ surface flux measurements in this section, because of the likelihood that scientists will want to use inversion to analyze these data which are increasing in number rapidly.

Figure 4a and b illustrate how deviation in Q_{10} and Z_p were affected by the diffusivity of soils. When subsurface sensor combinations were used as a constraint, there was an overall downward trend in Q_{10} and Z_p error with increasing diffusivity. As diffusivity increases (drier soils), CO₂ travels through the soil layers to the surface more quickly which results in decreased lag times, more rapid concentration changes, and more distinct soil responses. Under these conditions of rapid diffusion, inversions were most successful. Sites that are frequently waterlogged with limited air filled pore space tended to be less ideal for inversion, but the optimal instrument configuration still helps ensure reasonably small error throughout the entire range of diffusivities, so there is no strict limitation on the use of the inversion approach in low diffusivity soils.

Figure 4c and d demonstrate the impact of the Z_p parameter value on inversion success in terms of deviation in returned Q_{10} and Z_p values. For small Z_p values, shallow CO₂ concentration measurements (≤ 15 cm) were the best constraints, presumably because the soil is most active in these top layers. As depth of production increases, the production of CO₂ is no longer limited to the shallow soil, the exponential production function decreases more slowly. With increasing Z_p , CO₂ production in deeper soil layers is higher, and more useful as an inversion constraint. Some matching of deployment depth was also found, where for example shallow concentration measurements were more accurate for returning the correct value of shallow CO₂ production.

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Sensitivity tests indicate that increasing the temperature sensitivity of respiration had opposite effects on Q_{10} and Z_p error. Deviation in returned Q_{10} values increased rather uniformly across the best subsurface measurements, while for most subsurface combinations the Z_p error decreased. With increasing Q_{10} , respiration becomes more sensitive to temperature changes, leading to larger variations in production in the event of a temperature fluctuation. Figure 4e and f illustrate the impact of this parameter on Q_{10} and Z_p error.

With large amounts of existing surface flux data, it is also worth examining the effectiveness of the soil CO_2 surface flux as a constraint, even when it is not the preferred constraint. It is immediately evident from Fig. 4 that inversions constrained by the surface flux resulted in Q_{10} and Z_p deviations that responded much differently to changes in soil diffusivity, depth of production and Q_{10} . These deviations were often significantly larger than when subsurface constraints were used. Deviations in Q_{10} and Z_p generally increased as all three parameters increased. This suggests that for low diffusivity, depth of production and Q_{10} , surface flux was a reasonable model constraint, producing errors comparable to the subsurface measurements. This constraint was much less effective for determining depth of CO_2 production. However, Z_p was always returned within at least 3.5 cm of its actual value, which for some uses may be an acceptable level of uncertainty. Inversions constrained by surface flux were quite effective in returning Q_{10} . Returning to Fig. 3, the overall average Q_{10} error associated with surface flux was less than 5%, which is significantly better than results using deep subsurface measurements. Figure 4e suggests that inversions using large Q_{10} values were responsible for the majority of this error. For Q_{10} of 1.5, these inversions returned Q_{10} with 100% accuracy. For the largest Q_{10} , deviation from the true value climbed as high as 0.6–0.7, which is non-negligible. A shorter model time step could potentially reduce this error, as it may be able to better capture the larger and faster responses associated with high Q_{10} and diffusivity. As we cannot estimate the Q_{10} of a site prior to inversion, however, this insight may not be overly useful in site selection. Overall, inversions constrained

by the CO₂ surface flux are possible but should be performed with caution, and with reasonable expectations as to the resultant error level.

It is also of interest to examine how the amount of CO₂ production in the soil profile affects inversion. The bulk of our sensitivity tests were performed using a basal CO₂ production of 10 μmol m⁻³ s⁻¹, which is a fairly high. In order to test the other extreme, several inversions were performed using a production level of 1 μmol m⁻³ s⁻¹. These inversions performed with exactly the same accuracy as those with a production level of 10. From this, we can conclude that the magnitude of production has no effect on inversion success.

3.2.1 Random error and inversion

The measurements performed by sensors in the field will always be uncertain to some degree. It is therefore important to examine how these uncertainties in recorded temperature, CO₂ and soil volumetric water content measurements will impact the accuracy of the inversion method. Inversions performed on synthetic data to which random errors of 1, 5 and 10% had been added were indeed less accurate than those performed on idealized data. However the resulting errors in returned Q_{10} and Z_p were not proportional to the amount of error added to the input data, but actually much lower. That is, errors of 5% in the input data did not result in an additional 5% error in output values. An example of this is illustrated in Fig. 5. This plot demonstrates that with random measurement errors in the ranges of 1–5%, Q_{10} values were still determined with reasonable accuracy. Prior to error addition, deviation in Q_{10} was around 0.12. This deviation increased to 0.14 for 1% error and 0.17 for 5% error. As sensors in the field are typically uncertain by 1 to 5%, the inversion method remains feasible. We can thus conclude that the inversion process is rather tolerant of error in measurement.

3.3 Multi-parameter error landscape

It is worth investigating in detail the error landscape of the inversion process using a multi-parameter sensitivity tests. For this test, we chose the combination of measurements at 5, 10 and 15 cm which had resulted in the most accurate inversions on average.

The results from the sensitivity tests are shown in Fig. 6a–f. In all combinations, the error in Z_p was very small, with the maximum error for any single inversion being just over 2%. Despite this small error, it remains evident which soil conditions should be avoided for most accuracy. Sites with low diffusivity, production deep in the soil and low Q_{10} are the most problematic. This is consistent with the results from Fig. 4a, c and e. Trends were not as evident for error in Q_{10} . In panels a, e and c the most notable error was found in panel a for high depth of production, low Q_{10} . There is an error in Q_{10} here of almost 15%, which equates to a deviation in Q_{10} of about 0.225 from its actual value. This result is not unreasonable, but it is significantly higher than results from the other inversions. Plot e demonstrates an interesting result, where there seems to be a valley in the Q_{10} error, illustrating a tradeoff between depth of production and diffusivity. This is not evident in the other plots, and does not have an intuitive physical explanation. The effect of Q_{10} on inversion varies, but success hinges quite clearly on soil diffusivity and depth of CO_2 production. Choosing a site in the appropriate ranges of these two parameters will maximize chances of success.

Some of the soil parameters across which we tested are obviously unknown a priori. The unknown value of Q_{10} has already been noted, and depth of CO_2 production may also be unknown prior to inversion. Knowledge of root distribution in the soil could be one aid in site selection and instrumental configuration. On average, root respiration accounts for 50% of soil respiration (Hanson et al., 2000) and Jackson et al. (1996) provides root distributions for different terrestrial biomes. Jackson et al. (1996) found that tundra, boreal forest and temperate grasslands had upwards of 80–90% of roots within the top 30 cm of soil whereas deserts and temperate coniferous forests had

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much deeper rooting profiles, with only 50 % of roots within the top 30 cm. These and other methods may help inform the configuration of field experiments, and may be helpful in providing constraint data when running inversions on real timeseries.

4 Conclusions

Overall, this inversion method proved successful in preliminary testing on synthetic data. Depending on the tolerable level of error for a given application, almost every tested combination resulted in reasonably accurate returned Q_{10} and Z_p values. The subsurface concentration measurements that yielded the highest error were typically those that would be of least convenience to install and maintain deep in the soil profile.

The other constraint associated with high overall error was CO_2 surface flux, which would likely be the data with highest availability. Most of the error from this constraint arises in estimating the Z_p parameter. The CO_2 surface flux is still a reasonable means of estimating Q_{10} values via inversion. While in most cases the error was lower for high diffusivity, shallow production soils, the application of this method is certainly not limited to such regions.

This method is computationally intensive as it performs a sweep through all possible combinations in parameter space. This study used roughly 2.5 core-years of time despite the fact that synthetic timeseries were short. This full sweep ensures that the global minimum in the objective function is located every time, and when solving inversely for two unknown parameters (as we are), this is not an unreasonable approach. However, if it was of interest in the future to examine longer timeseries, or additional parameters such as the depth dependence of Q_{10} , resulting in additional unknown parameters, it may be beneficial to explore other search algorithms to increase efficiency, such as Simulated Annealing.

The next step for this work would be to perform inversions on real timeseries with appropriate measurement constraints, to obtain temperature sensitivity and CO_2 production depth estimates for various sites. With the increasing availability of high fre-

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quency soil data, there would be no shortage in data to analyze. Applying this method for periods of varying constant moisture levels could also help build an understanding of moisture effects on temperature sensitivity of respiration.

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Table 2. Measurement combinations used for the simulations. The combination number is listed at the beginning of each row. The columns represent the type of measurement (e.g. CO₂ surface flux), or the depth of concentration measurement in centimetres. The “X” values denote whether the type or depth of measurement was included in the combination.

Combination	Flux	5	10	15	20	25	30	35	40	45	50	55	60
1	X												
2		X											
3			X										
4				X									
5					X								
6						X							
7							X						
8								X					
9									X				
10										X			
11											X		
12												X	
13													X
14		X		X									
15		X					X						
16		X								X			
17		X										X	
18				X			X						
19				X						X			
20				X								X	
21							X			X			
22							X					X	
23										X		X	
24		X		X			X						
25		X		X						X			
26		X		X								X	
27				X			X			X			
28				X			X					X	
29							X			X		X	
30		X		X			X			X			
31		X		X			X					X	
32				X			X			X		X	
33		X	X	X									
34						X	X	X					
35										X	X	X	

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Table 3. Default parameter values for sensitivity testing.

Parameter	Abbr.	Minimum	Maximum	Increment
Total basal CO ₂ production (μmol m ⁻² s ⁻¹)	Γ ₀	1	10	10
Production exponential folding depth (m)	Z _p	0.05	0.2	0.05
Q ₁₀		1.5	4.5	1
Volumetric water content (ν/ν)	θ _w	0.1	0.25	0.05

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Table 4. Best and worst sensor combinations for determining Q_{10} , Z_p and overall through inversion.

Rank	Q_{10}	Combination	
		Z_p	Overall
1	5 + 10 + 15 cm	n/a	5 + 10 + 15 cm
2	5 + 15 cm	n/a	5 + 15 cm
3	5 cm	n/a	5 + 15 + 30 cm
4	10 cm	n/a	5 + 15 + 30 + 60 cm
5	5 + 15 + 30 cm	n/a	5 + 30 cm
31	45 cm	55 cm	50 cm
32	50 cm	50 cm	50 + 60/50 + 55 + 60 cm
33	50 + 60/50 + 55 + 60 cm	60 cm	55 cm
34	55 cm	5 cm	60 cm
35	60 cm	Surface Flux	Surface flux

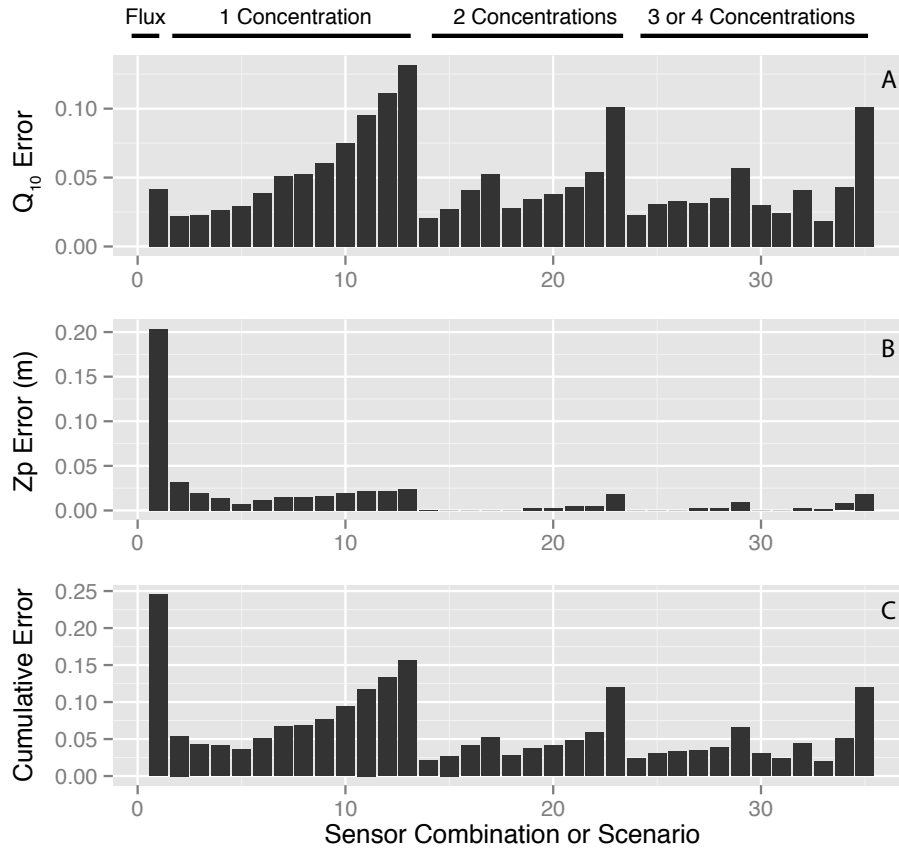


Figure 3. Fractional Error in Q_{10} and Z_p individually for different sensor combination scenarios, plus cumulative fractional error in Q_{10} and Z_p for the same scenarios.

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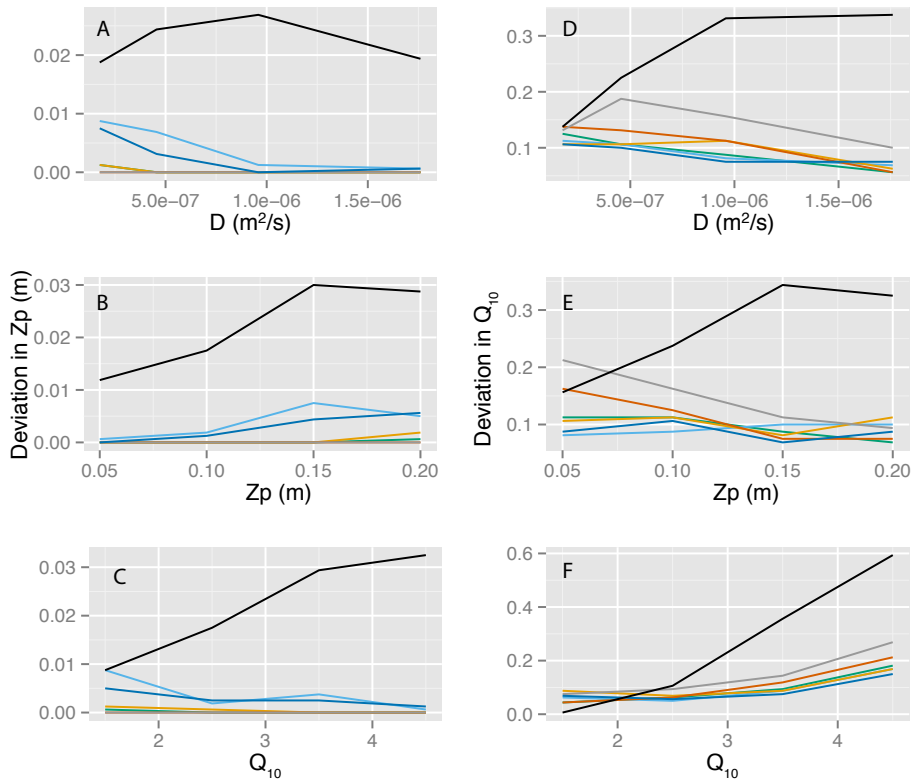


Figure 4. Error in Q_{10} and Z_p as a function of Q_{10} (Panels **c**, **f**), Z_p (Panels **b**, **e**), D (Panels **a**, **d**), for a grouping of the best sensor measurement depth combinations. Individual 5 and 10cm observational scenarios are shown in light blue and dark blue, respectively. The 5 + 15cm measurement scenario is shown in green. Orange and red illustrate sensitivity of the 5 + 10 + 15cm and 5 + 10 + 30cm scenarios, respectively. Finally, the 4-point 5 + 15 + 30 + 60cm measurement sensitivity is represented in grey while the surface flux scenario is shown in black. For these sensitivity tests, the known Q_{10} was 2.0, and a Z_p of 0.2 m was used.

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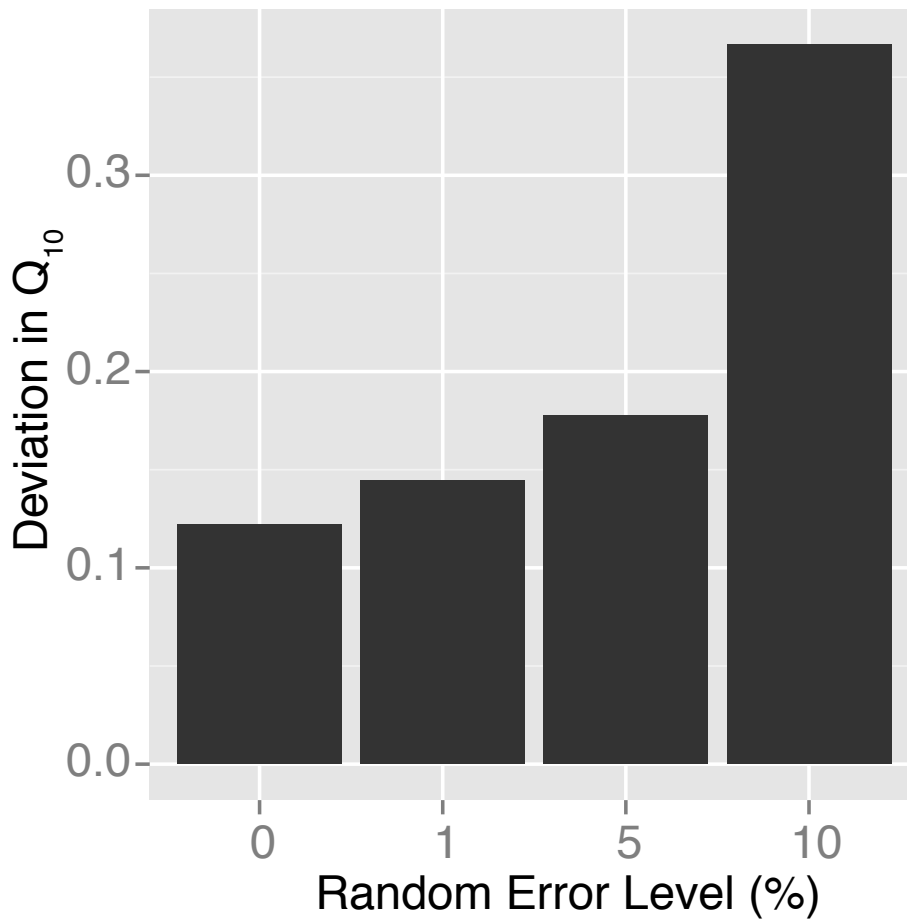


Figure 5. Sample of random error effects on inversion, constrained by one concentration measurement at 5 cm. For this sensitivity test, the known Q_{10} was 2.0.

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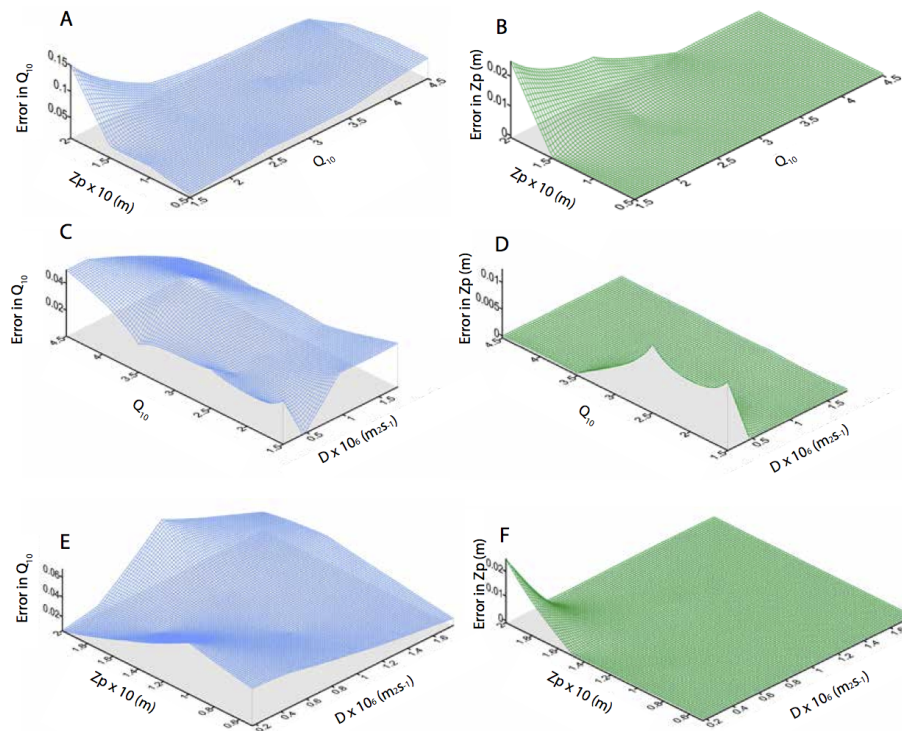
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Figure 6. Error in Q_{10} and Z_p as a function of Q_{10} , Z_p and Diffusivity for the constraint 5 + 10 + 15 cm. For these sensitivity tests, the known Q_{10} was 2.0, and a Z_p of 0.2 m was used.

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