

Seasonal variation in grass water content estimated from proximal sensing and MODIS time series in a Mediterranean Fluxnet site

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Abstract

This study evaluates three different metrics of water content of an herbaceous cover in a Mediterranean wooded grassland (*dehesa*) ecosystem. Fuel Moisture Content (FMC), Equivalent Water Thickness (EWT) and Canopy Water Content (CWC) were estimated from proximal sensing and MODIS satellite imagery. Dry matter (Dm) and Leaf area Index (LAI) connect the three metrics and were also analyzed. Metrics were derived from field sampling of grass cover within a 500 m MODIS pixel. Hand held hyperspectral measurements and

MODIS images were simultaneously acquired and predictive empirical models were parametrized. Two methods of estimating FMC and CWC using different field protocols were tested in order to evaluate the consistency of the metrics and the relationships with the predictive empirical models. In addition, Radiative Transfer Models (RTM) were used to produce estimates of CWC and FMC, which were compared with the empirical ones.

Results revealed that, for all metrics spatial variability was significantly lower than temporal. Thus we concluded that experimental design should prioritize sampling frequency rather than sample size. Dm variability was high which demonstrate that a constant annual Dm value should not be used to predict EWT from FMC as other previous studies did. Relative root mean square error (RRMSE) evaluated the performance of nine spectral indices to compute each variable. Visible Atmospherically Resistant Index (VARI) provided the lowest explicative power in all cases. For proximal sensing, Global Environment Monitoring Index (GEMI) showed higher statistical relationships both for FMC (RRMSE = 34.5%) and EWT (RRMSE = 27.43%) while Normalized Difference Infrared Index (NDII) and Global Vegetation Monitoring Index (GVMI) for CWC (RRMSE =30.27% and 31.58% respectively). When MODIS data was used, results showed an increase in R^2 and Enhanced Vegetation Index (EVI) as the best predictor for FMC (RRMSE=33.81%) and CWC (RRMSE=27.56%) and GEMI for EWT (RRMSE=24.6%). Differences in the viewing geometry of the platforms can explain these differences as the portion of vegetation observed by MODIS is larger than when using proximal sensing including the spectral response from scattered trees and its shadows. CWC was better predicted than the other two water content metrics, probably because CWC depends on LAI, that shows a notable seasonal variation in this ecosystem. Strong statistical relationship was found between empirical models using indices sensible to chlorophyll activity (NDVI or EVI which are not directly related to water content) due to the close relationship between LAI, water content and chlorophyll activity in grassland cover, which is not true for other types of vegetation such as forest or shrubs. The empirical methods tested outperformed FMC and CWC products based on radiative transfer model inversion.

1 Introduction

Water in leaves is a limiting factor for different physiological processes of vegetation and its deficit causes malfunctioning of different cellular processes. Water is involved in the thermal

regulation of plant through transpiration and also becomes crucial in the uptake of CO₂ for photosynthesis (Chaves et al., 2003). It is also fundamental to maintain turgor pressure, which controls different functional processes of plants like cell enlargement or gas exchange (Taiz and Zeiger, 2010).

Different metrics quantify vegetation water content. Fuel Moisture Content (FMC) (Desbois et al., 1997), defined as the mass of water per unit mass of vegetation,

$$FMC (\%) = \frac{W_{Fresh} - W_{Dry}}{W_{Dry}} * 100 \quad (1)$$

where W_{Fresh} is the fresh weight of the sample measured in the field and W_{Dry} is the oven dried weight. FMC has been extensively used to estimate fire risk and fire propagation (García et al., 2008; Yebra et al., 2008b). Equivalent Water Thickness (EWT) or Leaf Water Content (LWC), defined as the mass of water per leaf area, measures the thickness of the water layer with the same leaf area (Danson et al., 1992)

$$EWT (g/cm^2) = \frac{W_{Fresh} - W_{Dry}}{Area_{Leaf}} \quad (2)$$

where $Area_{Leaf}$ is the leaf area.

Several studies showed that EWT can be retrieved from spectral information at leaf level as it is directly related to the water absorption depth of leaves (Ceccato et al., 2001; Datt, 1999).

FMC and EWT are related each other since:

$$EWT (g/cm^2) = \left(\frac{FMC \cdot Dm}{100} \right) \quad (3)$$

where Dm is defined as the ratio of leaf dry weight and leaf area:

$$Dm (g/cm^2) = \frac{W_{Dry}}{Area_{Leaf}} \quad (4)$$

Finally, another metric is the Canopy Water Content (CWC), the mass of water in the canopy per ground area (Cheng et al., 2008; Trombetti et al., 2008). CWC represent the product of EWT and Leaf Area Index (LAI), offering information on vegetation water content at canopy level and can be expressed as:

$$CWC (g/cm^2) = EWT \cdot LAI \quad (5)$$

or

$$1 \quad \text{CWC}(\text{g/cm}^2) = \frac{W_{\text{Fresh}} - W_{\text{Dry}}}{\text{Area}} \quad (6)$$

2 where Area denotes for the area of the spatial unit used to collect the sample.

3 FMC, EWT or CWC are usually estimated from vegetation samples using gravitational
4 methods. Different field and laboratory protocols are used, despite of the need for
5 standardization (Yebra et al., 2013). In several studies FMC is sampled using a bag were 100-
6 200g of the fresh sample are introduced and considered as representative (Verbesselt et al.,
7 2007; Chuvieco et al., 2003). In other studies vegetation is sampled within a quadrant whose
8 area is used as reference (Sims and Gamon, 2003). However, uncertainties introduced by the
9 different protocols and therefore their comparability are unknown. The three metrics can be
10 used to measure water content, but relationships existing among them remains also unknown.
11 No comparative studies for grasslands have been reported.

12 Moreover, field sampling is limited and cannot provide estimates at regional or global scales,
13 since it requires interpolation to bridge the gaps in both time and space. Remote sensing is a
14 powerful alternative data source to provide information on vegetation water content as it fills
15 such temporal and spatial gaps. Monitoring vegetation water content with remote sensing
16 benefits agriculture, to control crop production and prevent stress in plants (Peñuelas et al.,
17 1992; Sepulcre-Cantó et al., 2006) and forestry, to assess fire danger associated with
18 vegetation water conditions (Chuvieco et al., 2003; Chuvieco et al., 2004; García et al.,
19 2008; Yebra et al., 2008b).

20 To estimate plant water content with remote sensing, vegetation spectral reflectance has been
21 primarily related to specific water absorption bands in the Short Wave Infrared region (SWIR,
22 1300-2500 nm) (Ceccato et al., 2001; Zarco-Tejada et al., 2003). Other studies related
23 vegetation water content to spectral indices that do not include SWIR bands. In the case of
24 grass the relationship with bands in the Visible (VIS) and Near Infrared (NIR) spectral region,
25 has shown a close relationship between vegetation biomass, chlorophyll and water content
26 (Chuvieco et al., 2003; Chuvieco et al., 2004; García et al., 2008; Yebra et al., 2008b) as water
27 stress produces changes in the chlorophyll activity and biomass of the plant. Least squares
28 regression models have served to empirically relate observed measurements of vegetation
29 water content to spectral indices. These models are site dependent, requiring long datasets for
30 calibration (Chuvieco et al., 2009) and showing different results when the models are

extrapolated to other sites using different data sets, making difficult their applicability (Riaño et al., 2005; Yebra et al., 2008a).

Radiative Transfer Models (RTM) simulate vegetation spectra and are a sound alternative to empirical modeling. They can be applied to different locations to estimate different vegetation parameters, as long as the RTM is a true representation of the vegetation canopy. For example, Trombetti et al (2008) predicted CWC for the continental US using RTM PROSAILH (Jacquemoud et al., 1995) simulations. Their model was calibrated with CWC from Airborne Visible / Infrared Imaging Spectrometer (AVIRIS) hyperspectral water absorption bands. Yebra et al. (2008b) used also PROSAILH to quantify FMC, and more recently, Jurdao et al (2013) inverted the RTM GEOSAIL (Huemmrich, 2001) combined with PROSAILH to estimate FMC. The estimations were validated with extensive field sampling data in Spain. RTM estimates are based on a physical principle, and one of the advantages is that are not constrained to local conditions as is the case of empirically derived relationships. Therefore, in theory they can be extensively applied at different locations with good results (Yebra et al., 2008a; Yebra et al., 2008b). This study compares the performance of the different empirically derived models and RTM based estimates models. The former were created establishing empirical relationships between three different metrics of vegetation water content measured simultaneously in the field (FMC, EWT, CWC) and nine spectral indices calculated at two scales, from proximal sensing and MODIS spectral data. In addition Dm and LAI were also analyzed in order to connect metrics which estimates water content at leaf and canopy level. Firstly, an analysis of the temporal and spatial variability of the different vegetation samples collected in the field was conducted to evaluate which biophysical parameter offers more information. Secondly, the performance statistics of the fitting equations were evaluated to select the most accurate empirical models. Finally, these models were compared to three RTM based estimates, proposed in the literature to derive two FMC (Jurdao et al., 2013; Yebra et al., 2008b) and the other for CWC (Trombetti et al., 2008).

2 Methods

2.1 Site description

The study site is located at Las Majadas del Tiétar (Spain) FLUXNET site (<http://fluxnet.ornl.gov/site/440>, last accessed 2014/06/05) (Fig. 1). The area is a *dehesa*, a

typical Mediterranean wooded grassland, ecosystem that occupies about 4% (2.5 Mha) of the Iberian Peninsula (Castro, 1997). Common tree species are different varieties of oaks, here mostly *Quercus ilex* subsp. *ballota* (L.), whose acorns and leaves are mainly used as forage for pigs and cows, respectively. The scattered oak trees have a 9 m mean height and 6 m mean crown diameter. Due to its deep and wide root system, this species is resistant to long drought periods (Camarero et al., 2012). Short grassland covers 86% of the area that is managed for cow shepherding. It is mainly composed by *Rumex acetosella*, L., *Plantago carinata* Schrad, *Trifolium subterraneum* L., *Cynodon dactylon* (L.) Pers., *Taraxacum dens -leonis* Desf. and *Vulpia myuros* (L.) C. C. Gmel. During the summer, grass dries out rapidly and turns into dead matter. Summers are hot and dry, with 30 °C daily average temperature and only 67 mm total precipitation, which are not representative of mean annual 16.7 °C and 572 mm. The average altitude is 256 m above mean sea level. Soils are lixisols with an average thickness of 80 cm. Due to the presence of a clay layer in some of the areas, small water pools may appear in winter after rainy periods. The occurrence of this type of ecosystem in Mediterranean areas worldwide, the need to track the responses to water stress conditions, together with the presence of a FLUXNET eddy covariance flux tower (<http://fluxnet.ornl.gov/site/440>) justifies the selection of this site.

2.2 Field data

2.2.1 Vegetation sampling

Grass water status was estimated through destructively sampling every two weeks from April 2009 to April 2011. Sampling was performed assuring no rain occurred in the two previous days to avoid sampling superficial water on the leaves. During the 2009 summer, when grass became completely dry, samples were not collected. However, to ensure the time series continuity of at least one phenological cycle, sampling was restated throughout the summer of 2010. This sampling strategy led to a total of 21 valid sampling days for the whole study period.

Six 25 x 25 m plots were randomly located within the 500 m MODIS pixel that contained the eddy covariance flux tower that was established as the center of the study site (Fig. 1). Three grass samples were collected from 25 x 25 cm quadrants randomly positioned within each plot. All rooted grasses were collected inside the quadrant using clippers (IQ_{Sample} hereafter). Additionally, a different sampling strategy was tested and a smaller sample was collected

outside of the quadrant but nearby, containing a representative proportion of surrounding species (OQ_{Sample} hereafter) (Fig. 2). All samples were placed in sealed plastic bags, weighed on a scale with 0.01 g precision and then transported in a cooler to the laboratory. Every OQ_{Sample} and a sub-sample from each IQ_{Sample} were scanned at 150 pixels per inch (ppi) in an Epson Perfection V30 color scanner (Epson American Inc., Long Beach, CA, USA). Leaf area was calculated automatically from the scanned images using the unsupervised classification algorithm ISOCLUS with 16 iterations in PCI Geomatica (PCI Geomatics, Richmond Hill, Ontario, Canada). All samples were then placed in an oven for 48 hours at a constant temperature of 60°C to obtain their dry weigh. Five biophysical variables were obtained from the collected vegetation samples: FMC, EWT, Dm, CWC and LAI.

FMC was determined from the fresh and dry weights of both the IQ_{Sample} (FMC_{IQ}) and the OQ_{Sample} (FMC_{OQ}) according to Eq. 1. The OQ_{Sample} permitted to calculate both, EWT and Dm using Eq. 2 and Eq. 4 respectively, since fresh/dry weight and leaf area were measured. The IQ_{Sample} was not used in this case as it was unfeasible to obtain the area of the total sample collected inside the quadrant and neither the fresh weight of a sub-sample.

CWC was calculated from two different approaches. In the first one, information corresponding to the IQ_{Sample} and OQ_{Sample} were combined using Eq. 5

The grass height was very short due to cow shepherding during some periods, so the only feasible technique to estimate LAI, was using gravitational methods (He et al., 2007). The biomass to leaf area ratio of a sub-sample inside the IQ_{Sample} to the total quadrant's biomass provided LAI using the following expression (Eq 7):

$$LAI(\text{cm}^2/\text{cm}^2) = \frac{\frac{W_{\text{Dry}}}{W_{\text{Dry}}^{\text{Sub}}} \text{Area}_{\text{Leaf}}^{\text{Sub}}}{\text{Area}} \quad (7)$$

where W_{Dry} is the total dry weight of the whole sample inside the IQ_{Sample}, $W_{\text{Dry}}^{\text{Sub}}$ is the dry weight of a sub-sample of W_{Dry} , $\text{Area}_{\text{Leaf}}^{\text{Sub}}$ is the sub-sample leaf area and Area is the total area of the quadrant. The second approach measured CWC from the fresh and dry weight difference of the IQ_{Sample} as in (Eq. 6).

2.2.2 Proximal sensing

Simultaneously to vegetation sampling, proximal sensing data were acquired using an ASD FieldSpec® 3 spectroradiometer (<http://www.asdi.com/>) along NE-SW and NW-SE transects in each 25x25 m plot. This instrument measures Hemispherical-Conical Reflectance Factor (HCRF) from 350 to 2500 nm. Before measuring along each transect, dark current was recorded, instrument settings were optimized and reference spectra were acquired using a Spectralon® 99% reflective reference panel (Labsphere Inc., North Sutton, NH, USA). All measurements were taken under clear sky within about ± 2 hours from local solar noon, to guarantee homogeneous illumination and maximum solar irradiance. Sky conditions were recorded in the field logs, and a quality control check removed the spectra where illumination changes may have occurred after calibration. The ASD was handled using bare fiber. Spectra were acquired at approximately 1.2 m height, rendering a sensor footprint diameter of about 53 cm, since nominal FOV is 25°.

An average of approximately 10 spectral measurements was calculated for each transect and this information was spectrally resampled to MODIS bands using ITT ENVI 4.7. (EXELIS, Boulder CO, USA).

2.2.3 MODIS data images

MODIS Terra daily surface reflectance (MOD09GA) data from April 1st, 2009 to April 15th, 2011 were downloaded from NASA Land Processes Distributed Active Archive Center (LP DAAC) at the USGS/Earth Resources Observation and Science (EROS) Center, Sioux Falls, South Dakota, USA. This product includes the reflectance of bands 1 to 7, from 469 to 2130 nm at 500 m spatial resolution, as well as sensor and solar observation angles and quality flags at 1 km. A script programmed in Matlab (Mathworks, Batick, Massachusetts, USA) extracted the MODIS pixel value of our study site from all the images to build the time series. The impact of angular effects on reflectance was reduced by removing images with sensor zenith angles wider than 20°, which also assures the accuracy of the geometrical location of the pixel (Wolfe et al., 2002). In addition, the quality flag layer eliminated images under clouds, cloud shadows and/or with high atmospheric aerosol content. The algorithm selected the closest valid MODIS image to the field sampling day within ± 5 days window, or the MODIS image acquired before the sampling day in case they were equal. Minimal time lag between sensor and field data reduces the chances of discrepancy, as grassland grazing could

affect LAI in a short period of time. This led to a total of 14 days of MODIS data with coincident proximal sensing measurements and field data.

2.3 Vegetation indices

For the study 9 spectral indices were calculated from proximal and MODIS reflectance data according to the equations in Table 1. The indices selected to estimate the biophysical variables included bands in the water absorption SWIR region (Faurtyot and Baret, 1997) and bands sensitive to vegetation greenness and structure in the NIR region (Paltridge and Barber, 1988; Yebra et al., 2008b).

2.4 RTM based water metrics estimates

In order to compare performance with the empirical derived models, three RTM based models were used to estimate CWC (Trombetti et al., 2008) and FMC (Yebra et al. (2008b); Jurdao et al. (2013)). As for the empirical models, the spectral information used to run the RTMs was the one obtained using proximal sensing and MODIS data.

2.4.1 CWC

CWC was estimated in the study site following Trombetti et al. (2008). This method uses PROSAILH RTM (Jacquemoud and Baret, 1990; Jacquemoud et al., 1995) and Artificial Neural Networks (ANN) to estimate CWC. Trombetti et al. (2008) trained their model by using MODIS synthetic spectra based on a set of empirical relationships. Different MODIS spectra combinations and vegetation indices were later used as input variables to train a neural network and obtaining as outputs CWC, leaf water content, and LAI. The outputs were validated against AVIRIS CWC and MODIS MOD15A2 LAI product. Multiple linear regression approach is later used to establish the equations for each landcover type. In our case we used the original calibration from Trombetti et al. (2008) for grassland.

Further details on this method can be found in Trombetti et al. (2008).

2.4.2 FMC

The FMC estimates are based on Look Up Table (LUT) inversion technique. This technique compares each observed spectra against previously generated spectra stored in a LUT. In this study two LUTs were tested. One specifically designated for grassland based on the study of

Yebra et al. (2008b) and that was generated using PROSAILH (Jacquemoud and Baret, 1990). The second LUT was generated using a link between PROSAILH (Jacquemoud and Baret, 1990) at leaf level and GEOSAIL RTM (Huemmrich, 2001) at canopy level and originally proposed to estimate FMC in a mixed-oak-tree-grassland cover (Jurdao et al., 2013). This model includes some additional parameters that allow to account for shadows, especially important in areas with disperse tree coverage as is the case in our study site. Further details on these methods can be found in Yebra et al. (2008b) and Jurdao et al. (2013).

2.5 Empirical models fitting

Intra-group, inter-group and overall R^2 values between FMC_{IQ} , FMC_{OQ} , EWT, CWC_{IQ} , CWC_{OQ} or LAI, and each of the proximal sensing spectral indices were calculated to investigate their variability within the 500 m MODIS pixel. More specifically, the intra-group R^2 offers information about the spatial variability, due to the collection of samples from different plots within the MODIS pixel. A linear regression model was created for each sampling day where the biophysical variable and the spectral index were the dependent and the independent variable, respectively. The average R^2 of all the regression models for each day provided the intra-group R^2 . Instead, the inter-group R^2 explains the temporal variability due to the collection of the samples on different days. In this case, the biophysical variable and the spectral index for all plots were averaged for each sampling day. The linear regression model of these averaged values determined the inter-group R^2 . To explain temporal and spatial variability together, the overall R^2 fitted in a single regression model including all plots and sampling days for each spectral index and biophysical variable.

Later, using the mean values of each biophysical variable and the proximal sensing spectral indices, a univariate linear regression model was applied. The same procedure was repeated for MODIS data. Bootstrapping techniques evaluated the empirical model robustness, which is a valid alternative to traditional leave-one-out methods to validate regression models predictability according to Richter et al. (2012) and following Steyerberg et al. (2001) to that recommends two hundred simulations. Later the median value of each statistics was used as indicative of its performance. Root Mean Square Error (RMSE), Relative Root Mean Square Error (RRMSE), determination coefficient (R^2) and Taylor's diagrams evaluated the models'

performance. The RMSE measured the error in the estimation of the biophysical variable by each model:

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^n (V_{est}^i - V_{obs}^i)^2} \quad (8)$$

Where V_{est}^i is the estimated variable and V_{obs}^i is its observed field measurement. RMSE cannot compare the error of different variables with different units. To address this limitation in order to compare the model performances between different variables, RRMSE divides RMSE by the average of the observed values \overline{V}_{obs} (Richter et al., 2012):

$$RRMSE = 100 \frac{RMSE}{\overline{V}_{obs}} \quad (9)$$

The R^2 measures the proportion of variance explained by the model and is calculated as:

$$R^2 = 1 - \frac{\sigma_r^2}{\sigma^2} \quad (10)$$

where σ_r^2 represents the residual variance and σ^2 is the variance of the dependent variable.

2.6 Comparing performance between empirical and RTM based estimates

Taylor diagrams allowed the comparison between the FMC and CWC predicted by empirical models fit and the RTM inversion estimates. In these plots the observed variable and its standard deviation (SD) are plotted in the x-axes. RMSE is represented as semicircles centered at the observed data. The correlation coefficient (r) is displayed in the azimuthal position. Best models are closer in the plot to the observed measurement; therefore they will have a high r , a low RMSE and a SD similar to the observed values.

3 Results

3.1 Empirical models fitting

All variables showed similar temporal evolution, a strong variability controlled by the meteorological conditions with a peak in spring and second minor peak in the winter except Dm (Fig. 3). Dm fluctuated throughout the year and exhibited its highest values in the

summer. The 47% Coefficient of Variation (CV) for Dm was less than for CWC_{IQ} (CV= 95%), CWC_{OQ} (CV=0.95%), FMC_{IQ} (CV= 60%) and FMC_{OQ} (CV= 56%), but higher than for EWT (CV= 38%). A higher precipitation in the spring of 2010 compared to previous year translated into higher FMC, CWC and LAI values. FMC_{OQ} and CWC_{OQ} , calculated from the OQ_{Sample} , presented similar trends but in some cases higher values than FMC_{IQ} and CWC_{IQ} , calculated from the IQ_{Sample} .

A low intra-group R^2 for all the variables indicates a low spatial variability between plots (Fig. 4). Contrary, the high inter-group R^2 also for all variables points to the high temporal variability between sampling dates. The main differences between variables occurred for overall R^2 . Similar overall and inter-group R^2 values for CWC_{OQ} and FMC_{OQ} indicated that the combination of the temporal and spatial factors matched in importance each factor on its own. Instead, overall R^2 for CWC_{IQ} and FMC_{IQ} laid in between the inter-group and the intra-group R^2 underling the temporal factor as the main source of variation. GEMI offers the best R^2 for all variables while VARI had the weakest R^2 .

The explicative model with the highest R^2 to retrieve each variable differed between proximal sensing and MODIS (Fig. 5). FMC_{OQ} and FMC_{IQ} showed the best correlations with GEMI from proximal sensing data but EVI was the index that presented the highest R^2 when using MODIS images. EWT offered the poorest adjustments among all variables analyzed both for proximal sensing and MODIS data. In this case GEMI was the best predictor. NDII and GVMI were the most accurate predictors for LAI, CWC_{OQ} and CWC_{IQ} with proximal sensing. When using MODIS, the most accurate results for LAI were achieved with NDII and GVMI, but EVI did so for CWC_{OQ} and CWC_{IQ} . When the IQ_{Sample} was used instead of the OQ_{Sample} , both FMC and CWC showed higher R^2 results (Fig. 5) with lower RRMSE, although the RRMSE results obtained presented small differences (Fig. 6).

Smaller confidence intervals of R^2 were observed when proximal sensing reflectance was used with the exception of EWT in which MODIS presented smaller intervals.

3.2 Comparing performance between empirical based and RTM estimates

Taylor diagrams in Figs. 7 and 8 compare FMC and CWC estimates using spectral indices and RTM. In the case of FMC_{IQ} from proximal sensing (Fig. 7 left), RTMs are distant from empirical index-based models. They presented higher RMSE and lower r than the spectral indices whereas RTM SD was more similar to the observed values. In the case of FMC_{IQ}

estimated from MODIS (Fig. 7 right), RTMs were closer to the empirical models in the Taylor diagram and therefore perform more similar to those. For CWC_{IQ} (Fig. 8), the differences between the empirical and RTMs are larger. Using proximal sensing data (Fig. 8 left), RTM overestimated the SD of the observed CWC_{IQ} . Using MODIS (Fig. 8 right), RTM showed a very high overestimation of the CWC_{IQ} .

Temporal evolution of the biophysical variables estimated using the most explicative model for proximal sensing and MODIS in Fig. 5 and 6 are shown in Fig. 9. Fitting equations for the different variables are shown in Table 2. Both sensors predicted well EWT, FMC_{IQ} and FMC_{OQ} but showed an overestimation, especially during the dry season. Contrary, the models for LAI, CWC_{OQ} and CWC_{IQ} adjusted well even during the dry season.

4 Discussion

Results revealed that Dm varies significantly throughout the year ($CV=47\%$) with high values in the summer. These changes could be related to the temporal variation in plant community structure, species composition and diversity in this ecosystem (Casado et al., 1986). Summer should be the best time of the year to invert RTM and predict Dm, since leaves are drier and therefore EWT does mask the Dm spectral absorption signal (Riaño et al., 2005). Casas et al. (2014) applied a constant annual Dm value from the literature to successfully predict seasonal variations in EWT and CWC. However, our study suggests that, due to the high seasonal variation in Dm, a constant annual value would not be recommended in grassland ecosystems as the one analyzed in this work.

The high inter-group and low intra-group R^2 implies that the temporal trend is much more critical than the spatial variation within the MODIS pixel (Fig. 4). Therefore, the strategy to better capture the variability of grass water content in this ecosystem should consist in increasing the number of samples in time and but sampling less number of plots per day. In addition, CWC_{IQ} and FMC_{IQ} , generated from larger sample sizes than CWC_{OQ} and FMC_{OQ} , presented higher inter-group R^2 values, which indicate a better characterization of the temporal variability. Even though similar conclusion were obtained using the two strategies the results in this study showed that the higher R^2 are found in the case of the IQ_{Sample} . Using the quadrant also presented some advantages as it allows not just the retrieval of FMC but also CWC (as in Eq. 6) without going through the time consuming leaf scanning process to retrieve leaf area needed to estimate EWT. This suggests the need to standardize sampling

1 protocols for the estimation of vegetation biophysical parameters to ensure data quality,
2 repeatability and to facilitate accurate cross comparison from different studies. Some
3 initiatives already exist to facilitate this standardization, as the Global Terrestrial Carbon
4 System (GTOS) guidelines in support of carbon cycle science (Law et al., 2008). However,
5 currently there is no international backbone that ensures this and an agreement in the
6 protocols is needed in order to validate remote sensing products.

7 CWC was better predicted than the other two water content metrics, FMC and EWT (Fig. 4).
8 CWC depends on LAI which is showing higher correlation values to the empirical models
9 than other metrics such as FMC or EWT. Some studies have shown that LAI contributions to
10 total reflectance variability is much higher than water (Bowyer and Danson, 2004) for this
11 reason also, CWC should provide more accurate retrievals than FMC or EWT. It is possible to
12 have the same FMC and EWT for different LAI and hence different CWC and amount of soil
13 background, which will change its reflectance. Yebra et al. (2013) demonstrated through
14 PROSAILH simulations how a very different CWC for the same EWT based on changes of
15 LAI translates into a large range of NDII values. Our results confirm this theoretical
16 assumption described in Yebra et al. (2013). This issue is especially critical over areas like the
17 one analyzed in this work with an herbaceous cover exhibiting large dynamic annual growth.
18 Very low R^2 values were obtained in this study regarding the EWT. More research needs to
19 be done in this line as EWT is a key input parameter in many RTM.

20 The empirical methods estimated FMC and CWC with slightly different results for proximal
21 sensing and MODIS (Figs. 5 and 6). While GEMI and NDII were the most accurate for FMC
22 and CWC respectively from proximal sensing in our study; EVI was the most explicative
23 estimator of both variables from MODIS. The relationship between these indices and water
24 metric is indirect, since none of them include spectral bands in the SWIR region where water
25 absorption is strong. However, there is a strong link between grass water content, chlorophyll
26 activity and LAI in this ecosystem. During wet periods the grass grows very rapidly,
27 increasing the LAI, biomass and chlorophyll content, but as soon as the dry season starts with
28 high temperatures and low rainfall the grass becomes cured rapidly losing all chlorophyll and
29 quickly decreasing the LAI and biomass. This explains the empirical relationships with high
30 R^2 between water metrics and indices sensible to chlorophyll activity, or those more sensible
31 to water in the SWIR region. In addition, it is remarkable that MODIS estimations presented
32 higher R^2 than proximal sensing. Bootstrap confidence intervals indicated that R^2 and

1 RRMSE presented large intervals, larger when using MODIS images. Roberts et al. (2006)
2 also observed different correlations between indices and platforms and the discrepancies here
3 need further investigation. The difference in the confidence interval amplitude between
4 proximal sensing and MODIS can be explained because the pixel included not only grass but
5 also trees, their shades, and other marginal covers like bare soil and a water pond (Fig. 1), and
6 its view angle could be up to 20° whilst proximal sensing measures only two transects within
7 each of the six plots and provides only nadiral measurements of herbaceous cover which
8 could be more affected by the soil signal.

9 Similarly to this study, Casas et al. (2014) reliably predicted water content variables in
10 California (USA) from GEMI, NDII and EVI using simulated MODIS spectral response from
11 airborne hyperspectral AVIRIS instrument. In their case, it was actually VARI the most
12 accurate for grasslands (FMC and CWC), chaparral (EWT, FMC and CWC) and a
13 Mediterranean oak forest (EWT). Contrary, VARI showed very poor accuracies in our case to
14 estimate FMC, EWT and CWC, but was still capable of capturing the variability in LAI (Fig.
15 4). This fact also contradicts other studies that predicted FMC from VARI on chaparral
16 (Peterson et al., 2008; Roberts et al., 2006; Stow et al., 2005, 2006). VARI was developed to
17 detect vegetation fraction in homogenous wheat crops (Gitelson et al., 2002b), but Gitelson et
18 al. (2002a) nor the above studies have tested this spectral index to detect vegetation water
19 content on sites like ours, with strong seasonal changes in species composition and LAI.

20 The empirical methods calibrated for this specific site outperformed the physical RTM
21 estimates for CWC and FMC (Figs. 7 and-8). This confirms the results in Casas et al. (2014)
22 where the CWC algorithm based on RTM inversion developed by Trombetti et al. (2008) also
23 failed to improve results from empirical estimates. Regarding the RTM-based-FMC estimates,
24 considering that the FMC inversion models were not calibrated with any data from the field
25 campaign and that the results were similar to those obtained using empirical approach (Fig. 7)
26 we believe that the models can be applied in other similar areas.

27 Future work in this line can still be done, testing other inversion techniques, using multiple
28 observations or other optimization algorithms might help to improve the performance of
29 physical based estimates of biophysical variables of vegetation.

5 Conclusions

This work showed a complete analysis of three metrics, EWT, FMC and CWC, to measure grass water content at two different spatial scales by using proximal sensing from a field spectroradiometer and MODIS images. The temporal changes in these metrics are more critical than their spatial variation within the MODIS pixel. Results indicated that larger samples collected using quadrants as spatial reference sampling units are more representative than small samples in order to follow the temporal trends in FMC and CWC. Protocol standardization should be considered to make different dataset comparable both spatially and temporally. Due to the high seasonal Dm variability, a constant annual value should not be used to estimate EWT from FMC in this ecosystem. The dependence of CWC on LAI makes this vegetation water content variable easier to predict than FMC or EWT in grasslands due to the strong existing link between LAI, water content and chlorophyll activity.

GEMI, NDII and EVI reliably predicted vegetation water content. The best empirical estimator differed between sensors. Empirical models based on vegetation indices showed higher R^2 for MODIS than from proximal sensing, probably due to differences induced by observation geometry and canopy observed. These empirical methods still exceed RTM inversions developed for other sites to predict FMC (Jurdao et al., 2013; Yebra et al., 2008b) and CWC (Trombetti et al., 2008). Conclusions from this study are much related to grassland physiology and cannot be extended to other vegetation types such as forest or shrubs.

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1 Table 1: Spectral indices calculated using field HCRF measurements and MODIS data. B_x
2 designates the band number corresponding to the MOD09GA product surface reflectance
3 product.

Index	Formula	Reference
Normalized difference vegetation index (NDVI)	$NDVI = \frac{B_2 - B_1}{B_2 + B_1}$	(Rouse et al., 1973)
Enhanced Vegetation Index (EVI)	$EVI = 2.5 \cdot \left(\frac{B_2 - B_1}{B_2 + 6 \cdot B_1 - 7.5 \cdot B_3} \right)$	(Huete et al., 2002)
Normalized Difference Water Index (NDWI)	$NDWI = \frac{B_2 - B_5}{B_2 + B_5}$	(Gao, 1996)
Normalized Difference Infrared Index (NDII)	$NDII = \frac{B_2 - B_6}{B_2 + B_6}$	(Hardisky et al., 1983)
Simple Ratio Water Index (SRWI)	$SRWI = \frac{B_2}{B_5}$	(Zarco-Tejada et al., 2003)
Soil Adjusted Vegetation Index (SAVI)	$SAVI = \left(\frac{B_2 - B_1}{B_2 + B_1 + L} \right) \cdot (1 + L)$ Where $L = 0.5$	(Huete, 1988)
Global Environment Monitoring Index (GEMI)	$GEMI = \eta \cdot (1 - 0.25\eta) - \frac{B_1 - 0.125}{1 - B_1}$ $\eta = \frac{2 \cdot (B_2^2 - B_1^2) + 1.5 \cdot B_2 + 0.5 \cdot B_2}{B_2 + B_1 + 0.5}$ where	(Pinty and Verstraete, 1992)
Visible Atmospherically Resistant Index (VARI)	$VARI = \frac{B_4 - B_1}{B_4 + B_1 - B_3}$	(Gitelson et al., 2002a)

Global Monitoring (GVMI)	Vegetation Index	$GVMI = \frac{\left(NIR_{REC}^* + 0.1\right) - \left(SWIR - 0.02\right)}{\left(NIR_{REC}^* + 0.1\right) + \left(SWIR - 0.02\right)}$	(Ceccato et al., 2002)
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Central band wavelength	B1= 645.5 nm, B2= 856.5 nm, B3= 465.6 nm, B4= 553.6 nm, B5= 1241.6 nm, B6= 1629.1 nm, B7= 2114.1 nm
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-
- | | |
|---|--|
| 1 | <ul style="list-style-type: none"> NIR_{REC} stands for the information in the Near Infra Red rectified as the index was designed for SPOT-VEGETATION (Ceccato et al., 2002). In this study the index was calculated using the spectral bands from MODIS corresponding to that B2 for the NIR and B5 for the SWIR regions |
| 2 | |
| 3 | |
| 4 | |

1

Table 2: Empirical fitting equations obtained after bootstrap.

Fitting equation	Fitting equation
Proximal Sensing	MODIS
$FMC_{OQ} = (1184.400 \cdot GEMI) - 734.405$	$FMC_{OQ} = (1727.326 \cdot EVI) - 216.433$
$FMC_{IQ} = (999.707 \cdot GEMI) - 626.932$	$FMC_{IQ} = (1398.385 \cdot EVI) - 173.518$
$EWT = (0.029 \cdot EVI) + 0.011$	$EWT = (0.059 \cdot EVI) + 0.003$
$LAI = (2.621 \cdot NDII) + 1.268$	$LAI = (3.524 \cdot NDII) + 1.189$
$CWC_{OQ} = (0.075 \cdot NDII) + 0.029$	$CWC_{OQ} = (0.195 \cdot EVI) - 0.032$
$CWC_{IQ} = (0.063 \cdot NDII) + 0.023$	$CWC_{IQ} = (0.157 \cdot EVI) - 0.026$

2

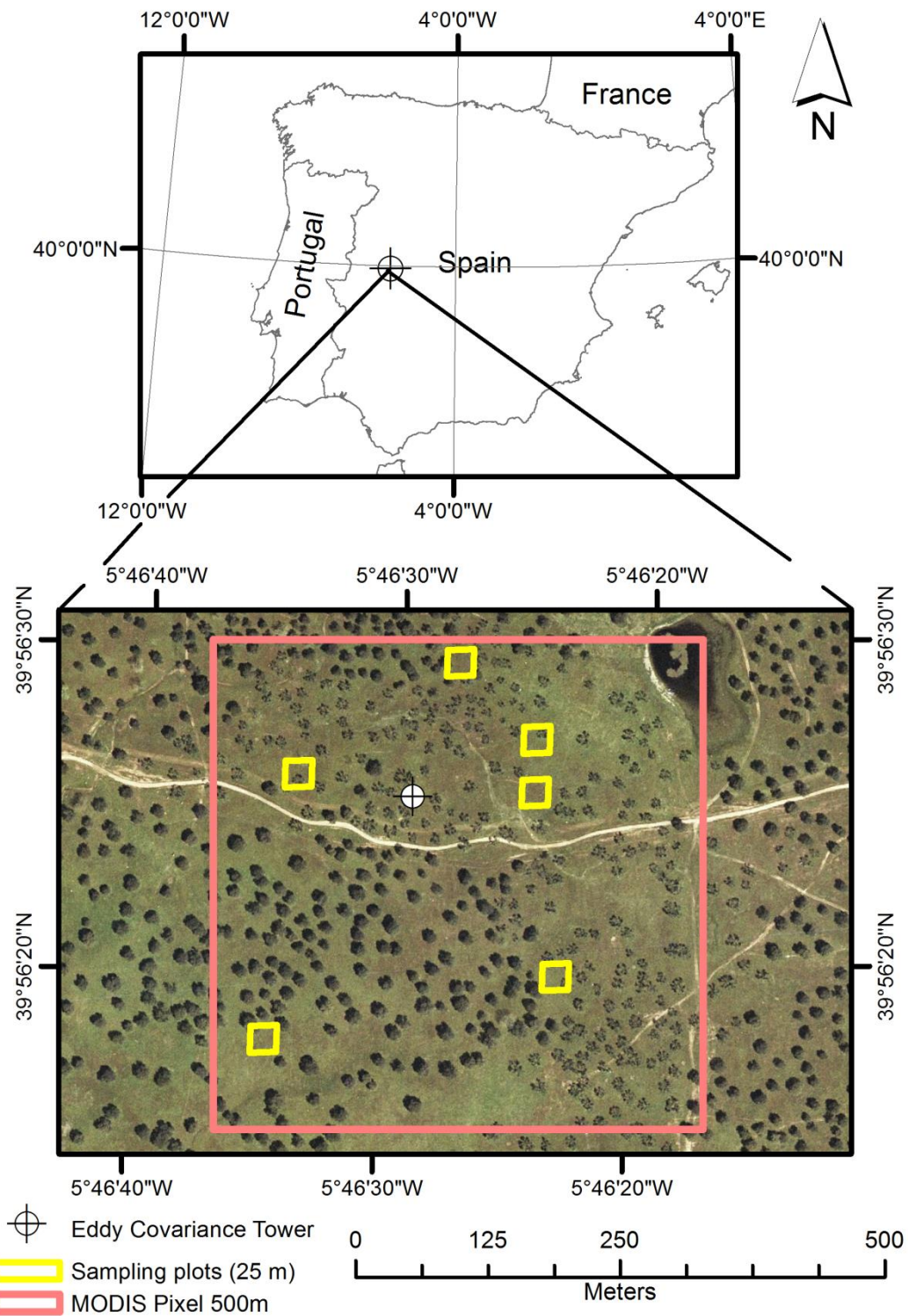
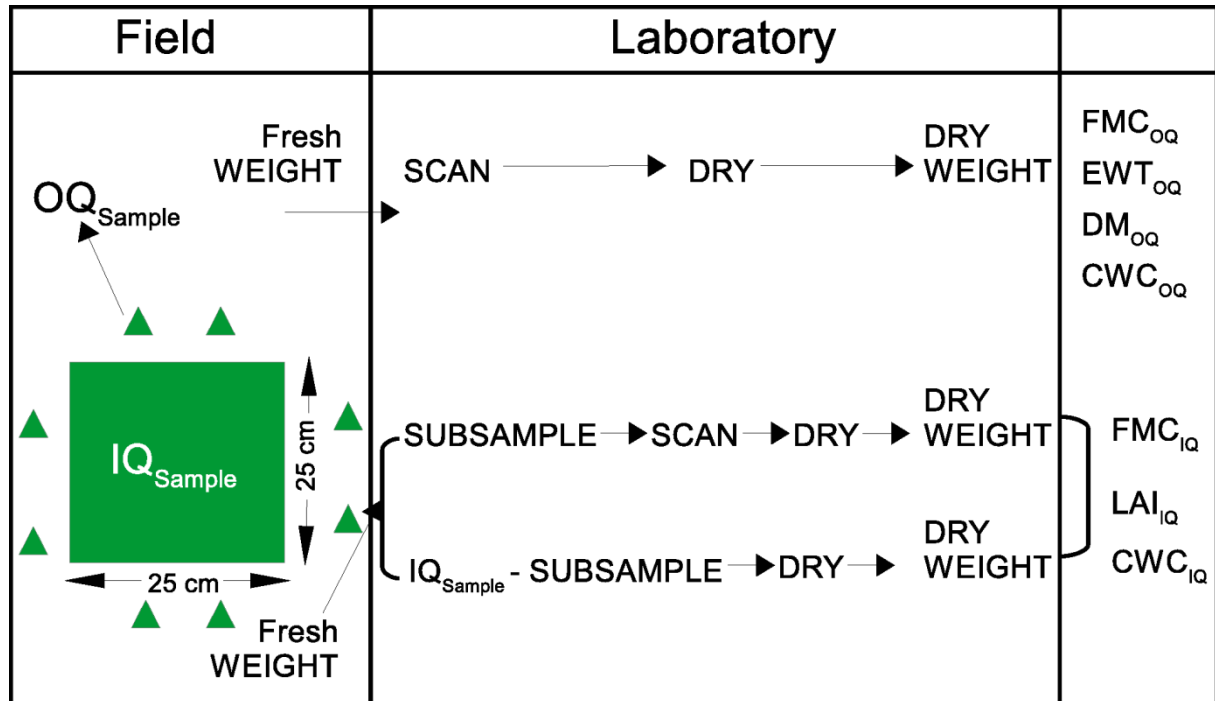


Figure 1. Plots sampled near the FLUXNET tower within the 500 m MODIS pixel at Las Majadas del Tiétar (Spain) study site.

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4 Figure 2. Scheme showing the different samples collected in the field and how they are

5 processed in the laboratory. Metrics obtained as results are also indicated in the last column.

6

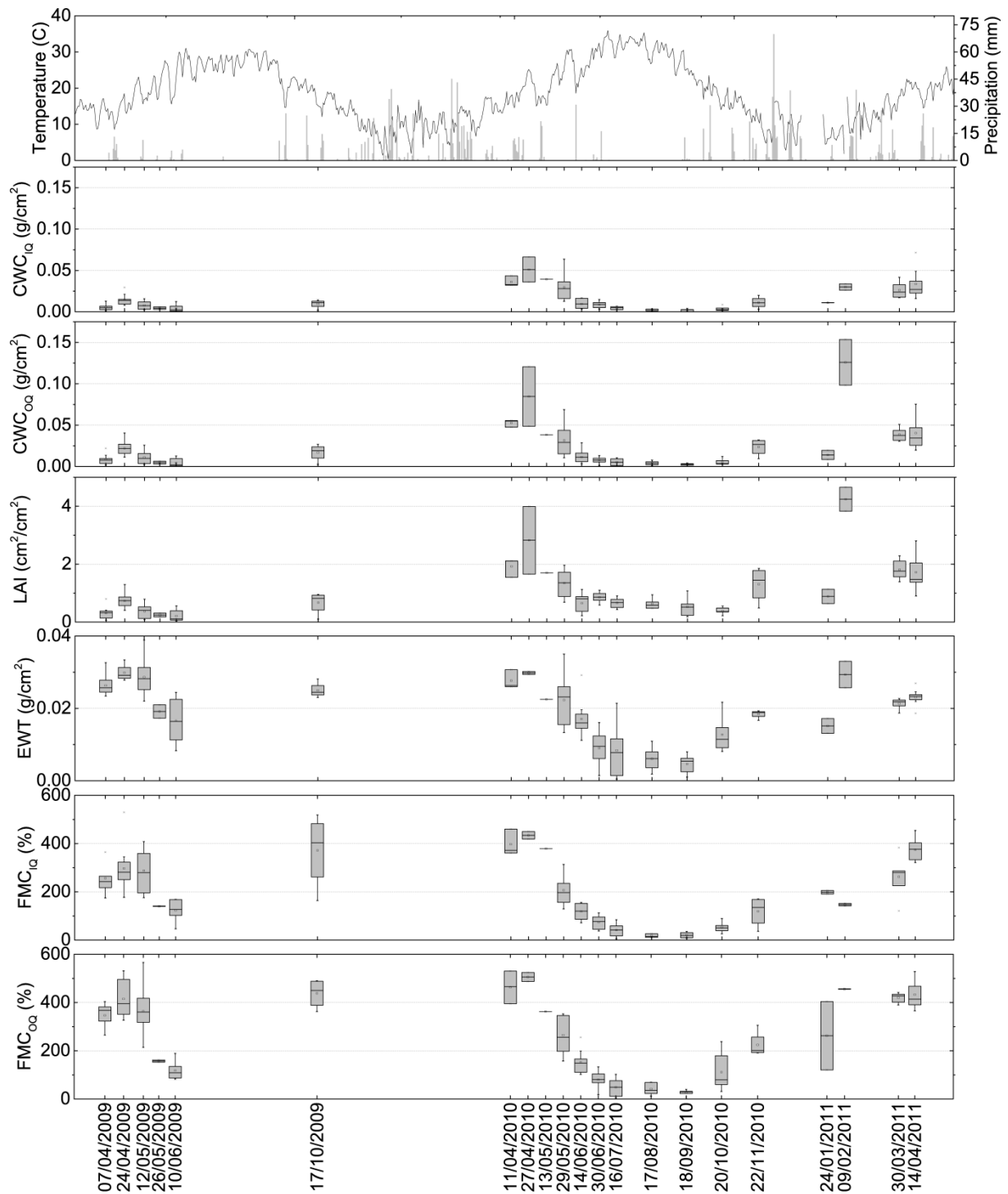


Figure 3. Box plot showing the temporal evolution of field biophysical variables measured. Filled points represent the median of the daily measurements, the boxes indicate the position of the 1st and 3rd quartile, lines delimit the maximum and minimum values. Line inside the boxes showed the median value of the day and the point the mean value. Precipitation is represented using bars and temperature is represented with a solid line

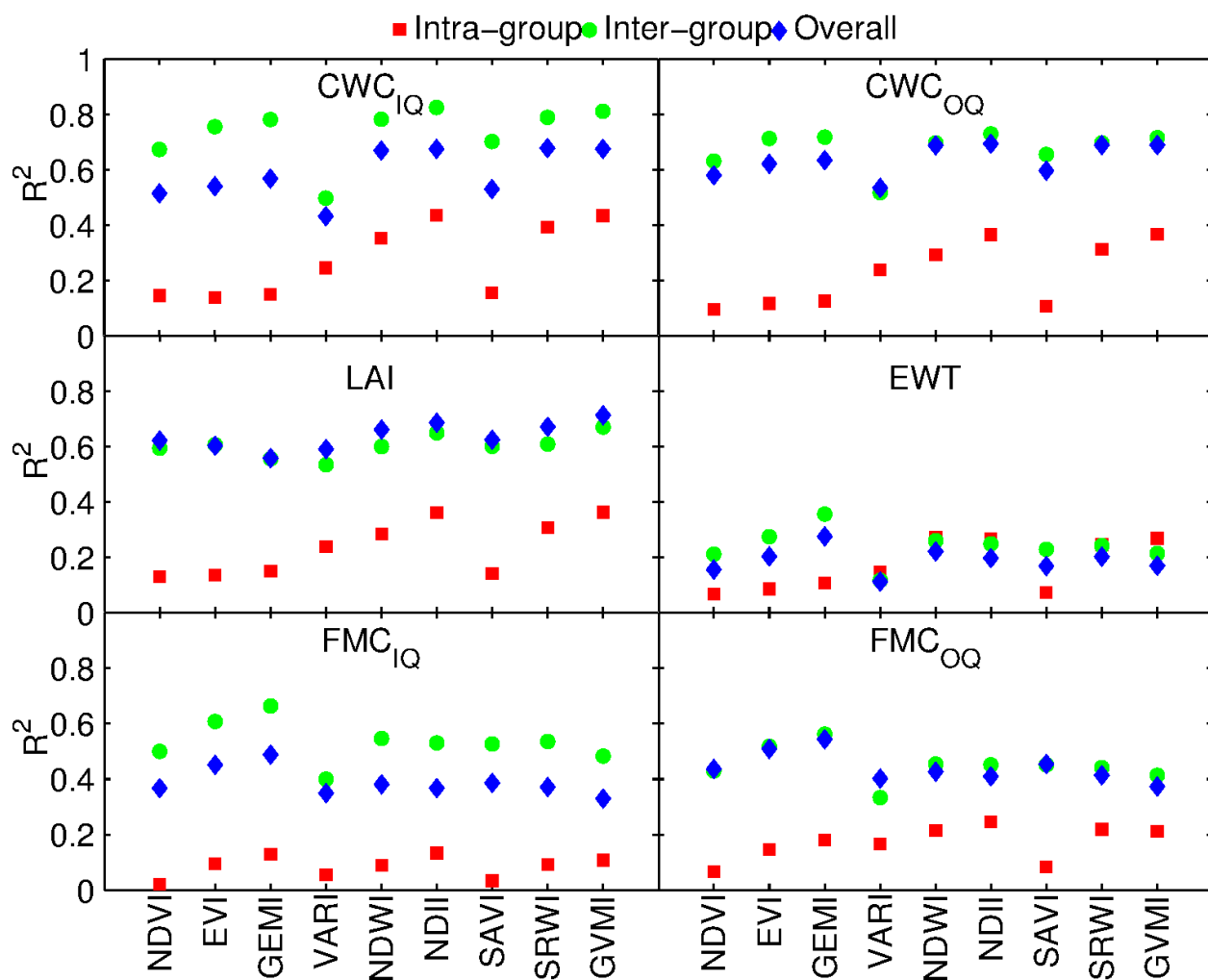


Figure 4. Intra-group, inter-group and overall R^2 values between proximal sensing spectral indexes and biophysical variables measured in the field.

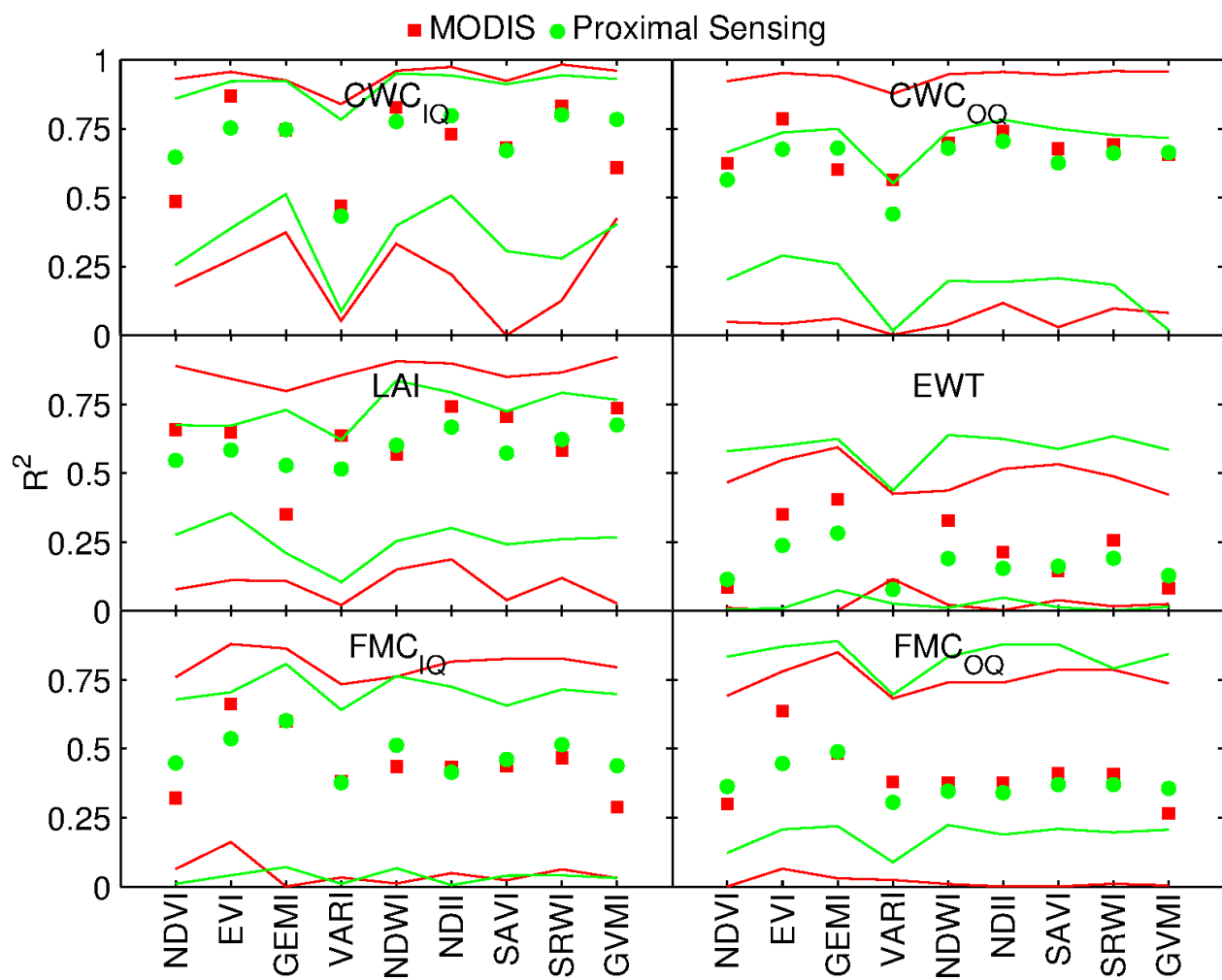


Figure 5. Determination coefficient for proximal (green circles) and MODIS (red squares) empirical models after bootstrap. Upper and lower limits of the confidence intervals for MODIS and proximal sensing are presented.

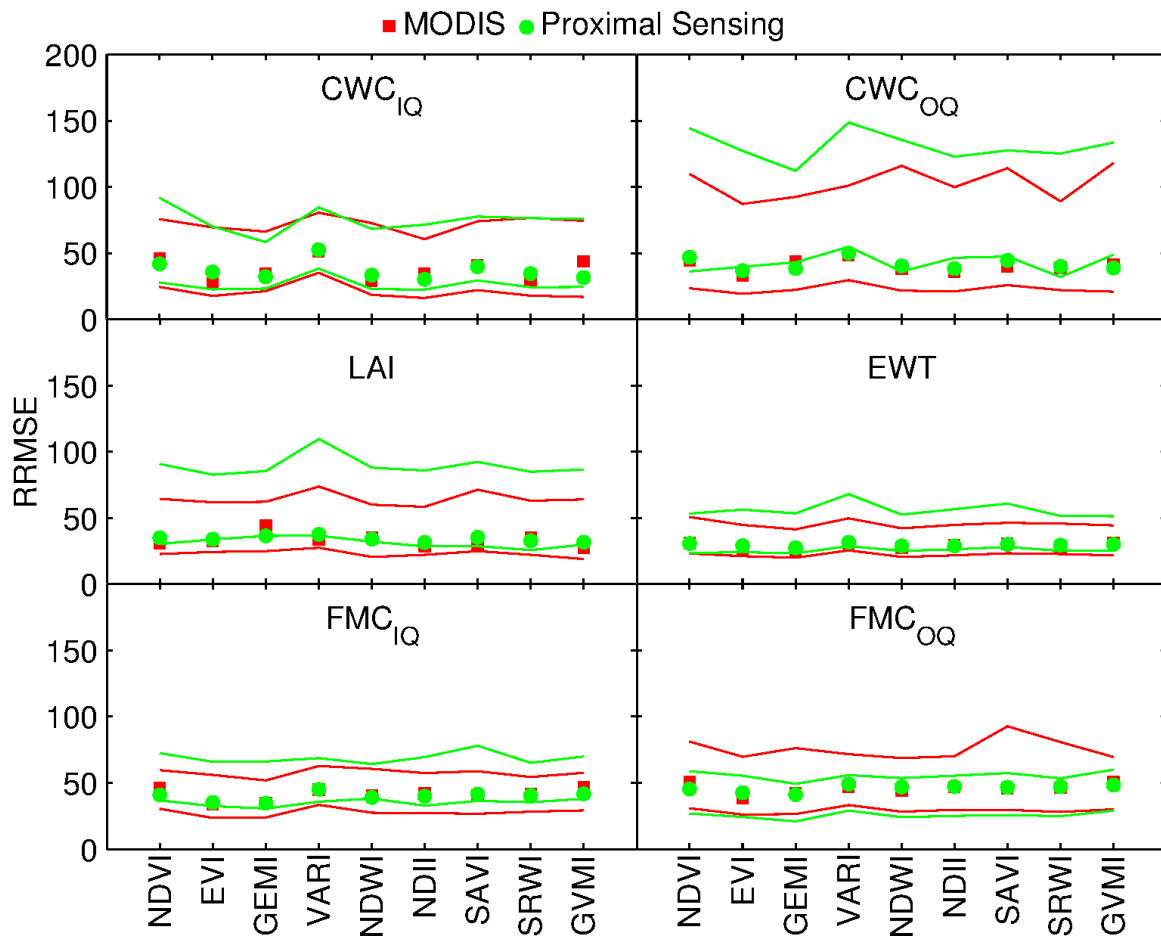


Figure 6. Relative root mean square error for proximal (green circles) and MODIS (red squares) empirical models after bootstrap. Upper and lower limits of the confidence intervals for MODIS and Proximal sensing are presented.

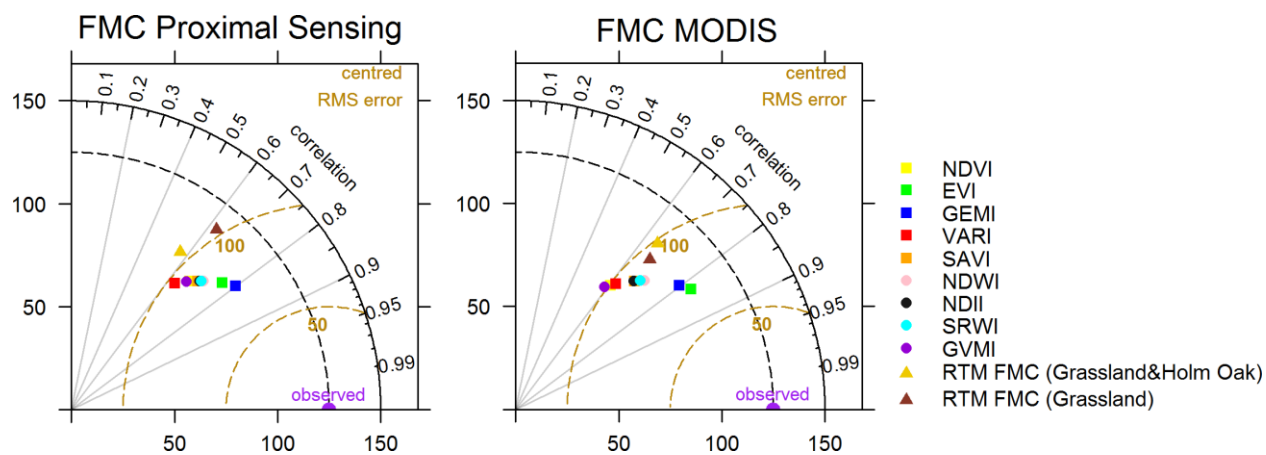


Figure 7. Comparison of empirical vs RTM models to estimate FMC with proximal sensing (left) and MODIS (right). RTM FMC (Grassland) obtained from the LUT proposed by (Yebara et al., 2008b). RTM FMC (Grassland& Holm Oak) obtained from the LUT proposed by Jurdao et al. (2013).

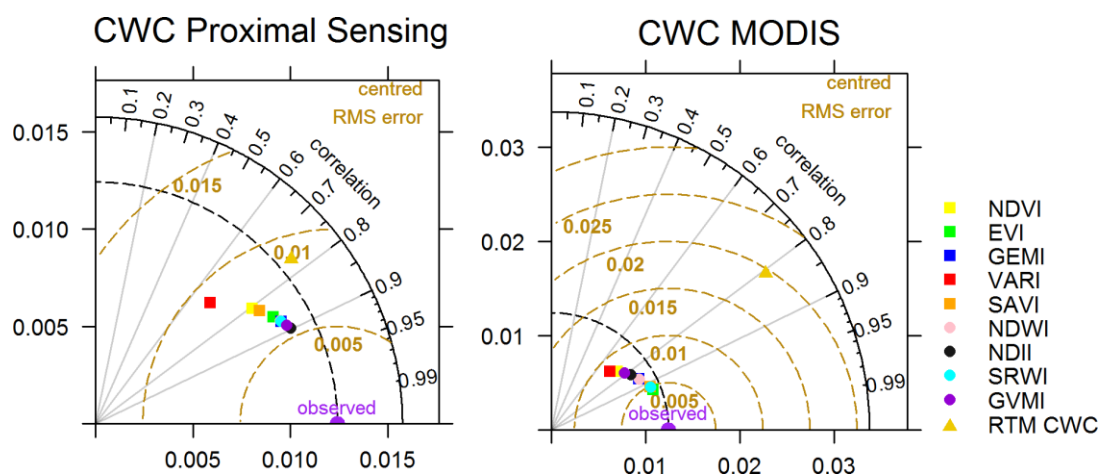


Figure 8. Comparison of empirical vs RTM models to estimate CWC with proximal sensing (left) and MODIS (right). RTM CWC is based on Trombetti et al. (2008).

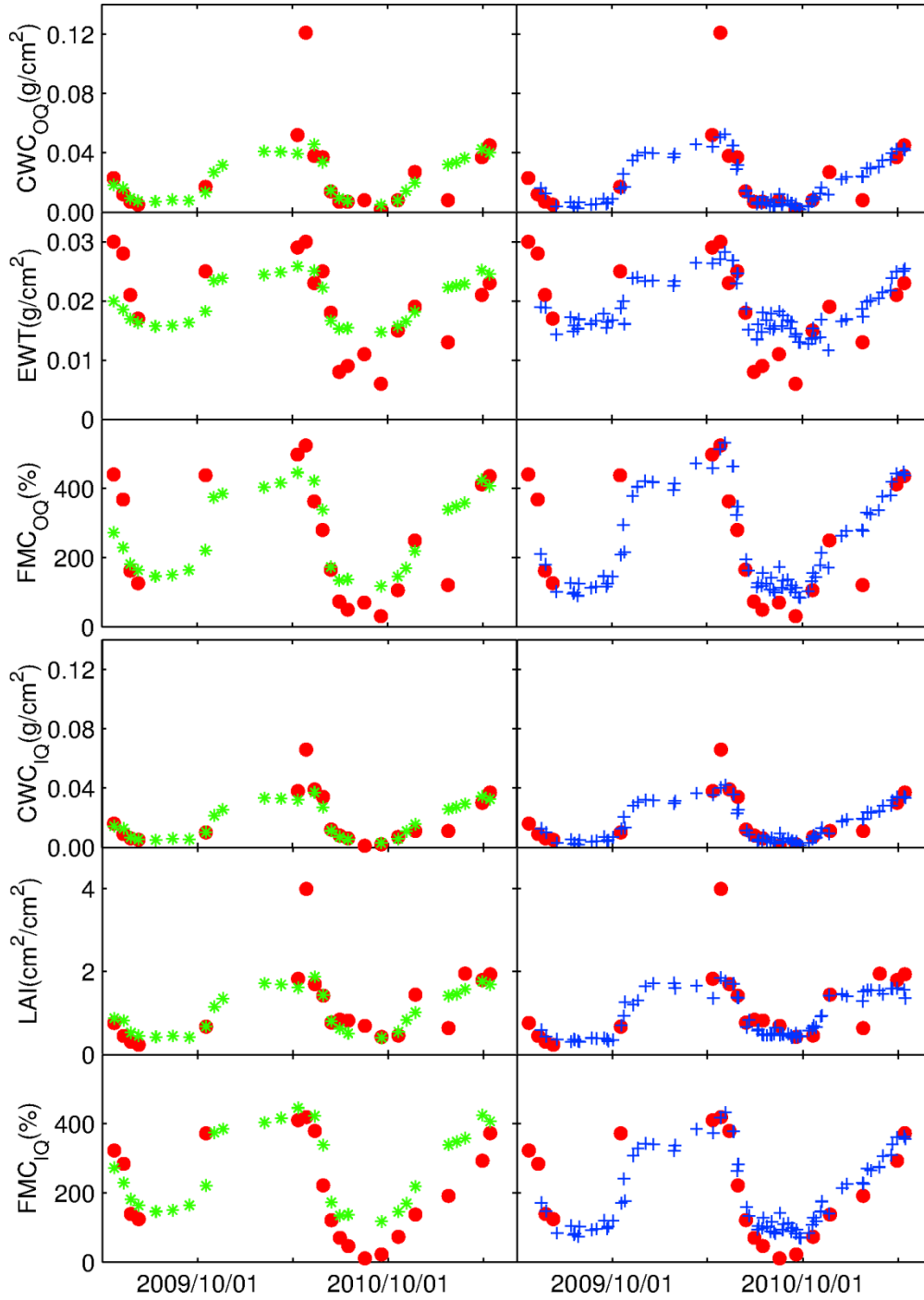


Figure 9. Temporal evolution of the observed (red circles) and estimated FMC_{OQ} , FMC_{IQ} , EWT , LAI , CWC_{OQ} and CWC_{IQ} obtained for proximal sensing (green asterisks) and MODIS (blue crosses). Fitting equations are presented in Table 2.