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Differential long-term effects of climate change and management on stocks and distribution of soil organic carbon in productive grasslands

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Abstract

We studied the impact of climate change on the dynamics of soil organic carbon (SOC) stocks in productive grassland systems undergoing two types of management, an intensive type with frequent harvests and fertilizer applications and an extensive system
where fertilization is omitted and harvests are fewer. The Oensingen Grassland Model was explicitly developed for this study. It was calibrated using measurements taken in a recently established permanent sward in Central Switzerland, and run to simulate SOC dynamics over 2001–2100 under three climate change scenarios assuming different elements of IPCC A2 emission scenarios. We found that: (1) management intensity dominates SOC until approximately 20 yr after grassland establishment. Differences in SOC between climate scenarios become significant after 20 yr and climate effects dominate SOC dynamics from approximately 50 yr after establishment, (2) carbon supplied through manure contributes about 60 % to measured organic C increase in fertilized grassland. (3) Soil C accumulates particularly in the top 10 cm soil un-

- til 5 yr after establishment. In the long-term, C accumulation takes place in the top 15 cm of the soil profile, while C content decreases below this depth. The transitional depth between gains and losses of C mainly depends on the vertical distribution of root senescence and root biomass. We discuss the importance of previous land use on carbon sequestration potentials that are much lower at the Oensingen site under ley-
- arable rotation and with much higher SOC stocks than most soils under arable crops. We further discuss the importance of biomass senescence rates, because C balance estimations indicate that these may differ considerably between the two management systems.

1 Introduction

²⁵ Grasslands tend to store more carbon (C) than arable lands, most C in the soil being organic (Soil Organic Carbon). For this reason, previous studies have focused on land



use conversion as a measure to mitigate climate change (Schimel, 1995; IPCC, 2000; Conant et al., 2001; Ammann et al., 2007; Lal, 2007; Poeplau et al., 2011). Some published estimates based on measured changes in SOC (ΔSOC) in new grasslands are shown in Table 1. Discussion has evolved however, on the importance of management on SOC in grassland (Ammann et al., 2007; Leifeld and Fuhrer, 2010; van Wesemael et al., 2010).

Dynamics of SOC tend to be mainly driven by litter input and soil respiration, but additional import of manure-derived C has also been shown to increment SOC substantially (Leifeld and Fuhrer, 2010; Van Wesemael et al., 2010). Ammann et al. (2007) found

- that ΔSOC is negative in a newly established grassland when it is not fertilized. Furthermore, effects of climate changes on the efficiency of grassland establishment as a mitigation policy are uncertain (Kätterer, 1998; IPCC, 2000; De Bruijn and Butterbach-Bahl, 2010). Some climatic drivers (air temperature and precipitation) effect both C input by vegetation growth and soil respiration, while others (radiation, atmospheric and precipitation) and a solution of the solution of the solution.
- ¹⁵ CO₂ concentrations) effect growth alone. Further consideration deserves also Δ SOC in deeper soil. Estimates of total SOC, for example by IPCC (2000) or Poeplau et al. (2011) are typically based on statistical upscaling of field measurements. Field sampling however, tends to focus in the upper soil (~30 cm) whereas 70 % of SOC is typically located below 20 cm depth (Poeplau et al., 2011).

The goal of our study was to examine how ΔSOC depends on climate and management at different soil depths and time scales in a newly established grassland. Biogeochemical models have proven useful to improve knowledge about long-term ΔSOC (DNDC: Li et al., 1992, RothC: Jenkinson, 1991, PaSim: Riedo et al., 1998, Century: Parton et al., 1987; Kulshreshtha and Sobool, 2006). An issue which has been iden-

tified in some of the commonly used biogeochemical models is a loss of robustness, model stiffness or over-parameterization, due to the complexity of dealing with a large range of biological, chemical and physical processes (Kesik et al., 2005; De Bruijn and Butterbach-Bahl, 2010).



We developed a new semi-empirical computer simulation model that describes interactions between plant and soil C:N processes to study Δ SOC after conversion of cropland to grassland at a site in Central Switzerland (Oensingen). The Oensingen Grassland Model (OGM) was calibrated using measurements taken in 2002–2009 at the ongoing long-term experiment at Oensingen that started in 2000. These data are particularly valuable because two parallel plots were established on the same arable field, but developed under different management (Ammann et al., 2007, 2009). Model runs were used to simulate long term (100 yr) Δ SOC under variable management and

climatic conditions.

10 2 Materials and methods

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2.1 Field observation dataset

Relevant measurements are shown in Table 2. The FLUXNET grassland site Oensingen is located in central Switzerland (7°44′ E, 47°17′ N, 450 m a.s.l.). It has a mixed maritime/continental climate with high annual rainfall (1100 mm). Mean annual air temperature is 9.5 °C. The soil is classified as Eutri-Stagnic Cambisol (FAO, ISRIC and ISSS, 1998) developed on clayey alluvial deposits. Clay content is between 42 and 44 %, total pore volume is 50–55 % and fine pore volume is 32 %. Before 2000, the field has been under ley-arable rotation with a typical 8-yr cycle. Fertilization with N depended on crop type and followed the Swiss standard fertilization practice (110 kg N ha⁻¹ yr⁻¹ on average). The field was last ploughed in November 2000 after which it was divided into two equal sized (0.77 ha) rectangular plots (Ammann et al., 2007).

The two management systems were named intensive management (INT) and extensive management (EXT) in previous publications that discuss the Oensingen experiments (Ammann et al., 2007, 2009; Leifeld et al., 2010). The plots were sown in May 2001: INT with 7 species of grass and clover, EXT with 30 species of grass, clover



and herbs (Ammann et al., 2009). Grass clippings are usually hayed except for the last cut, which is fermented. INT is fertilized with solid ammonium nitrate (± 120 kg ha⁻¹ per treatment) or liquid cattle manure (± 32 m³ ha⁻¹ per treatment) at the beginning of each growing cycle. EXT remains unfertilized. The number of harvests depended on the observed productivity of the field and followed the normal agricultural practice in the region. EXT typically remained uncut until June and is typically cut 3 times per year whereas INT is typically cut 4 times per year. Ammann et al. (2009) found that EXT had a negative N balance during 2001–2006.

2.2 Model description

- In general, we were aiming to maintain the advantages of a process-based model (e.g. the ability to improve qualitative understanding rather than just to quantify relevant processes), while using few parameters and mathematical descriptions that are basic. The OGM model simplifies by lumping molecular varieties in which C and N elements occur in the soil and vegetation, it does not explicitly calculate microbial pop-
- ¹⁵ ulation dynamics, uses few decomposition pools and a limited number of input parameters. When compared to some of the more frequently used biogeochemical models, it resembles RothC and Century rather than DNDC or PaSim. In contrast with RothC and Century however, it maintains daily integration steps rather than monthly or annual. The development of a new model, moreover, allowed us to experiment with some alternative approaches.

OGM simulates a soil-plant system in one spatial dimension, with modules for temperature, moisture and C and N dynamics (Fig. 1). It uses three driving climatic variables (temperature, radiation, and precipitation), atmospheric CO_2 concentration, 4 input parameters per soil layer (bulk density, porosity, C content and C:N ratio), 19 pa-

rameters that are specific for a vegetation type (e.g. water use efficiency, root/shoot turnover rate, Specific Leaf Area), and 24 parameters that are site or soil type specific (e.g. potential decomposition rates, optimum decomposition temperature, moisture). The latter, when describing soil properties, are assumed constant with soil depth. The



OGM model uses a daily time step, with daily averages for temperature and radiation, and daily sums for precipitation. The user can decrease the time step to prevent oscillations. Results presented here were obtained with an hourly time step. The model integrates virtual soil layers, assuming constant conditions in each layer. The user can

set the thickness of each layer depending on research interests and the availability of data. For the present simulations, the soil profile was divided into 11 layers (2 × 5 cm, 9 × 10 cm) to simulate down to 1.0 m depth. OGM has a Microsoft windows-specific (Visual C++) user interface which is separated from the model calculations that are ansii compliant (C++).

10 2.2.1 Temperature and moisture

The temperature submodel is common to many soil biogeochemistry models; we will not describe it in detail here. A simple cascade approach was used to model soil moisture. The main processes that drive soil moisture are soil water movement and uptake of soil moisture by the vegetation. Water movement depends on water potentials that change with soil moisture in adjacent layers. Water uptake depends on soil moisture and root density. Further details of the water and temperature submodel can be found in Müller (2000).

2.2.2 Carbon and nitrogen balance

Plants can assimilate atmospheric CO₂ and fix N₂ through root symbiosis with rhizobia
 (Biological Nitrogen Fixation, BNF). The model treats organic manure-related additions of C and N (organic manure is always cattle slurry in INT) similar to inputs of plant residues since it increases the decomposition pools according to concentrations of C, N and a fraction of manure that is labile.

While acknowledging that there is ongoing discussion about the biophysical interpretation of modeled decomposition pools, OGM confirms with models such as RothC, DNDC, COUP or also the century model, by using conceptual rather than measurable



decomposition pools, mainly in order to reduce the number of pools and to simplify model parameterization (De Bruijn and Butterback-Bahl, 2010; Parton et al., 1987; Li et al., 1992; Xu et al., 2011). OGM uses four decomposition pools, two for C and two for N distinguished according to decomposability (C_{labile} N_{labile}, $C_{recalcitrant}$, N_{recalcitrant}). Inorganic manure-bound N increases a separate pool of dissolved N, which represents both organic (DON) and inorganic (DIN) nitrogen (N_{diss_{sl}}: DON+DIN in soil layer sl). Extraction of C and N occurs with harvests, net emission of CO₂ and nitrogenous

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gases, or through leaching of $N_{diss_{sl}}$. Leaching of DOC has not been investigated at the Oensingen field site, but Zeeman (2008) found that C leaching in a similar site in Switzerland was very small (0.05 tC ha⁻¹ yr⁻¹).

OGM calculates gaseous N emissions ($N_{emissions}$) or N leachates ($N_{leaching}$), but it does not specify species of N gases (N_xO_y , NH_3^+) or leachates (DON, NO_3^- , NH_4^+). In consequence, OGM cannot be calibrated for accuracy of N emission rates, even though emissions are constrained by the decomposition rates and C:N ratio of the decompo-¹⁵ sition pools in the model. The OGM model uses plant functional types (i.e. categories of species with similar biochemical characteristics) to deal with interspecies variability. Biochemical behavior of a functional type is described with unified equations that can be parameterized differently. For the present simulations two plant functional types were used: legumes (v = 0) and grasses (v = 1). In the following, subscripts "v", "d" and

²⁰ "sl" are used to refer to individual vegetation types {v = 0, 1 for grass and legumes}, decomposition pools {d = 0, 1 for labile and recalcitrant}, and soil layers {sl = 0, slMax for increasing depth}.

Net ecosystem exchange (NEE) is the sum of CO₂ assimilation and respiration:

$$NEE = \sum_{v=0}^{1} \left(\frac{\delta C}{\delta t}\right)_{assim,v} - \sum_{d=0}^{1} \left(\frac{\delta C}{\delta t}\right)_{decomposition,d}$$
(1)

where $(\frac{\delta C}{\delta t})_{assim,v}$ is net assimilation by v, and $(\frac{\delta C}{\delta t})_{decomposition,d}$ is decompositionrelated loss of C from d. Net biomass productivity (NBP) is the sum of C input and



losses including management induced changes:

NBP = NEE +
$$\left(\frac{\delta C}{\delta t}\right)_{\text{manure}} - \sum_{v=0}^{1} \left(\frac{\delta C}{\delta t}\right)_{\text{harvest,v}}$$

where $(\frac{\delta C}{\delta t})_{\text{harvest,v}}$ is biomass that is removed with harvests and $(\frac{\delta C}{\delta t})_{\text{manure}}$ is manurebound C. All variables are expressed in g C m⁻². The N balance is calculated according to:

$$\left(\frac{\delta N}{\delta t}\right)_{\text{system}} = \sum_{\nu=0}^{1} \left(\left(\frac{\delta N}{\delta t}\right)_{\text{BNF},\nu} - \left(\frac{\delta N}{\delta t}\right)_{\text{harvest},\nu} \right) + \left(\frac{\delta N}{\delta t}\right)_{\text{manure}} - \left(\frac{\delta N}{\delta t}\right)_{\text{emission}} - \left(\frac{\delta N}{\delta t}\right)_{\text{leaching}}$$
(3)

where $(\frac{\delta N}{\delta t})_{BNF,v}$ is N fixation by v, $(\frac{\delta N}{\delta t})_{harvest,v}$ is N that is removed with harvest. $(\frac{\delta N}{\delta t})_{manure}$ is manure-bound N, $(\frac{\delta N}{\delta t})_{emission}$ is N gaseous emission. $(\frac{\delta N}{\delta t})_{leaching}$ is N leaching. All variables are expressed in g N m⁻².

10 2.2.3 Vegetation

Steduto et al. (2009) developed the AquaCrop model which assumes that plant growth correlates well with crop transpiration under nutrient-saturated conditions. In agreement with AquaCrop, OGM uses crop transpiration as the main driver of assimilation:

$$\left(\frac{\delta C}{\delta t}\right)_{\text{assim},v} = Ns_{v} \cdot WUE_{v} \cdot \left(1.0 + P_{CO_{2},v}\right) \cdot Tr_{v}$$
(4)

¹⁵ where WUE_v is the potential water use efficiency of *v* under pre-industrial levels of atmospheric CO₂ (g C mm⁻¹ H₂O), Ns_v is a growth rate reduction factor that depends on the concentration of N in leaves and Tr_v is transpiration by *v*. P_{CO_2} is the relative increase of WUE (%) with increasing concentrations of atmospheric CO₂:

$$P_{\rm CO_2,v} = \frac{D_{\rm CO_2,v}}{100\%} \cdot \left(\frac{\rho_{\rm CO_2} - 370}{370}\right)$$

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(2)

(5)

where ρ_{CO_2} is the concentration of atmospheric CO_2 in ppm, $D_{CO_2,v}$ is the rate increase of photosynthesis in *v* if atmospheric concentration of CO_2 doubles compared to preindustrial $\rho_{CO_2} = 370$ ppm. Published estimates of $D_{CO_2,v}$ for species in INT and EXT range from 20–40% and estimates of individual species typically differ as much as those between species (Aeschlimann et al., 2005; Ainsworth et al., 2003; Casella and Soussana, 1997; Ryle et al., 1992). In the present model applications, we used $D_{CO_2} =$ 33% for both grasses and legumes (C3 plants) based on an extensive literature review by Wand et al. (1999).

The N stress factor Ns_v is calculated from foliage N according to

$$10 \quad Ns_{v} = \left(\frac{C2Nf_{v}}{C2N_{OPT,v}}\right)^{\lambda Ns_{v}}$$

where C2Nf_v and C2N_{OPT,v} are current and optimal C:N ratio in foliage of v, λNs_v is a tuning parameter applied to v, and transpiration Tr_v is calculated from potential evapotranspiration (ET₀), which is estimated from air temperature and radiation according to Priestley and Taylor (1972). Soil evaporation E and potential transpiration PT_{tot} (PT_{tot} = ΣPT_v) are calculated from ET₀ using the total leaf area LAI_{tot} (LAI_{tot} = ΣLAI_v) assuming that E is negligible when LAI_{tot} > 1.0 m² m⁻² (PT_{tot} = $\Sigma (LAI_v ET_0)$ when LAI_{tot} < 1.0 or PT_{SUM} = ET₀ when LAI_{tot} > 1.0). PT_v is derived from PT_{tot} using the dominance in foliage cover dom_v (dom_v = LAI_v/LAI_{tot}) assuming that the capacity of a vegetation type to dominate water uptake of an ecosystem with more than one type of vegetation (PT_v/PT_{tot}) correlates linearly with dom_v (PT_v = dom_v PT_{tot}). The actual transpiration of v (Tr_v) is estimated from PT_v according to root biomass and moisture availability in individual soil layers:

$$\mathsf{Tr}_{\mathsf{v}} = \sum_{\mathsf{sl}=0}^{\mathsf{slMax}} \left(\mathsf{fr}_{\mathsf{sl},\mathsf{v}} \cdot \left(\frac{\theta_{\mathsf{sl}} - \theta_{\mathsf{wilt},\mathsf{v}}}{\theta_{\mathsf{poro}} - \theta_{\mathsf{wilt},\mathsf{v}}} \right)^{\lambda s_{\mathsf{v}}} \cdot \mathsf{PT}_{\mathsf{v}} \right)$$

where $fr_{sl,v}$ is the fraction of root biomass of v in soil layer sl (see also Eq. 12), slMax ²⁵ is the number of soil layers and θ_{sl} is the water content in sl (VOL%), $\theta_{wilt,v}$ is soil

(6)

(7)

moisture content at the level where v starts to wilt (VOL%), θ_{poro} is water content at field capacity (VOL%) and λs_v is a tuning parameter applied to v. N uptake by plant roots is calculated according to:

$$\left(\frac{\delta N}{\delta t}\right)_{uptake,v} = \sum_{sl=0}^{slMax} Nup_v \cdot N_{diss_{sl}} \cdot fr_{sl,v} \cdot Br_v$$

⁵ where Nup_v is uptake capacity by roots of $v (g_N/g_{DW(root)})$, Br_v = root biomass of $v (g_{DW} m^{-2})$. The OGM model assumes that BNF correlates linearly with root volume:

$$\left(\frac{\delta N}{\delta t}\right)_{BNF,v} = \sum_{sl=0}^{slMax} \left(BNFC_{v} \cdot fr_{sl,v} \cdot Br_{v}\right)$$
(9)

where BNFC_v is the rate of N₂ fixation by roots of v ($g_N g_{DW(root)}^{-1}$), with BNFC_v = 0.0 when simulating species that are incapable of fixing atmospheric N₂.

¹⁰ Two pools are used to describe vegetation development (Bs: shoot biomass and Br: root biomass; both in g DW m⁻²). The density of C in a component is a fixed parameter but the C:N ratio fluctuates. We are assuming that plants improve access to N by investing in roots when the C:N ratio in foliage increases, or vice versa, plants increase foliage biomass to improve assimilation of C when the C:N ratio drops (Thornley and Johnson, 1990):

$$fCa_{v} = \lambda Ca_{v} \cdot \left(\frac{C2N_{OPT,v}}{C2Ns}\right)$$

20

where fCa_v is the fraction of assimilated C that is allocated aboveground, $C2N_{opt,v}/C2Ns$ is shoot N status (capped to exclude values larger than 1.0) and λCa_v is a tuning parameter applied to v. We further assume that foliage growth and N allocation does not depend on root C:N ratio, and that aboveground allocation of N (*f*Na: the

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(8)

(10)

fraction of N that is allocated to above ground parts) decreases as C2Ns drops below $C2N_{opt,v}$ and roots are used to store excess N.

$$f \operatorname{Na}_{v} = 1.0 - \lambda \operatorname{Cb}_{v} \cdot \left(\frac{\operatorname{C2N}_{\operatorname{OPT},v}}{\operatorname{C2Ns}}\right)$$
(11)

Root biomass distribution is commonly modeled assuming an exponential decrease of root biomass with depth (Gerwitz and Page, 1974). However, data for root biomass measured at Oensingen suggest that this assumption tends to underestimate root biomass in the top soil layer. Alternatively, we used:

$$Br_{v,sl} = Br_{v} \cdot \frac{\left(D_{max_{v}}/D_{sl}\right)^{\lambda Br}}{\sum_{sl=0}^{slMax} \left(D_{max_{v}}/D_{sl}\right)^{\lambda Br}}$$

where $Br_{v,sl}$ is root biomass of v in sl, Br_v is the total root biomass of v ($g_{DW} m^{-2}$), D_{max_v} is rooting depth of vegetation type v (m), and D_{sl} is the depth of sl (m). Parameter λBr is a shape parameter. Foliage turnover $(\frac{\delta Bs}{\delta t})_{turnover,v}$ depends on an intrinsic turnover rate which expresses the effect of ageing, and of water stress:

$$\left(\frac{\delta Bs}{\delta t}\right)_{\text{turnover},v} = \left(TOf_v + \lambda sTO_v \cdot \frac{TR_v}{PT_v}\right) \cdot Bs_v$$
(13)

where TOf_v is reference foliage turnover rate and λ sTO_v is a shape parameter that increases foliage decay with water stress (m⁻¹). Root biomass turnover $(\frac{\delta Br}{\delta t})_{turnover,v}$ is a constant fraction (TOr_{rv} in kg_{DW} kg⁻¹_{DW}) of root biomass:

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$$\left(\frac{\delta \mathsf{Br}}{\delta t}\right)_{\text{turnover, v, sl}} = \mathsf{TOr}_{\mathsf{v}} \cdot \mathsf{Br}_{\mathsf{v, sl}} \tag{14}$$



(12)

The model assumes that harvest index (HI: extracted biomass/cut biomass) is constant regardless of harvesting method:

$$\left(\frac{\delta \mathsf{Bs}}{\delta t}\right)_{\mathsf{harvest},\mathsf{v}} = \mathsf{HI} \cdot \left(\frac{\delta \mathsf{Bs}}{\delta t}\right)_{\mathsf{cut},\mathsf{v}}$$

The volume of cut biomass is estimated by subtracting the aboveground biomass that remains after a cut (Bi_v is derived from a vegetation specific parameter LAI_{init,v} that is the LAI of *v* immediately after emergence) from biomass volume at the time of the cut (Bs_v):

$$\left(\frac{\delta Bs}{\delta t}\right)_{cut,v} = (1.0 - Bi_v) \cdot Bs_v$$
(16)

The remaining biomass (cut but not removed) is added to the soil together with other residues:

$$\left(\frac{\delta C}{\delta t}\right)_{\text{harv_litter,v}} = \left(\frac{\delta Bs}{\delta t}\right)_{\text{cut,v}} - \left(\frac{\delta Bs}{\delta t}\right)_{\text{harvest,v}}$$
(17)

where $\left(\frac{\delta C}{\delta t}\right)_{\text{harv_litter,v}}$ are biomass residues after a harvest.

The current model structure cannot deal with grazing, which is not part of management systems applied at the Oensingen grasslands. Inclusion of grazing would require additional parameterization of cattle density and activity. We do expect however, that model performance in such setup would be lower due to spatial variability of manure additions which cannot be accounted for in a 1-D model.

2.2.4 Soil

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Input of plant litter expressed in terms of C of v that is transported to C_d (C₀ = C_{labile}, C₁ = C_{recalcitrant}) is expressed according to:

$$\left(\frac{\delta C}{\delta t}\right)_{\text{litter,d,v}} = \sum_{sl=0}^{slMax} \left(fr_{v,sl} \cdot f_d \cdot \rho Cr_v \left(\frac{\delta Br_{sl}}{\delta t}\right)_{\text{turnover,v}} \right) + f_d \cdot \rho Cs_v \left(\frac{\delta Bs}{\delta t}\right)_{\text{turnover,v}} + \left(\frac{\delta C}{\delta t}\right)_{\text{harv_litter,v}} (18)$$
1066

BGD 9, 1055-1096, 2012 **Differential long-term** effects of climate change A. M. G. De Bruijn et al. **Title Page** Introduction Abstract Conclusions References Tables **Figures** Back Close Full Screen / Esc **Printer-friendly Version** Interactive Discussion

Discussion Paper

Discussion

Paper

Discussion Paper

Discussion Paper

(15)

where $fr_{v,sl}$ is the fraction of root biomass of v in sl (derived from Eq. 12), f_d is the fraction of labile (d = 0) or recalcitrant (d = 1) constituents in turnover biomass, ρCr_v and ρCs_v are concentrations of C in root and shoot biomass ($g C g^{-1} DW$). Additions to the N pools are expressed similarly, where ρNr_v (calculated dynamically) is applied ⁵ instead of ρCr_v , ρNs_v instead of ρCs_v , $\delta N/\delta t$ instead of $\delta C/\delta t$.

The OGM user can specify manure applications as inorganic N (N_{inorg} in kg_N ha⁻¹), organic N (N_{org} in kg_N ha⁻¹), and organic C (C_{org} in kg_C ha⁻¹). Organic manure enters a C pool according to:

$$\left(\frac{\delta C}{\delta t}\right)_{\text{litter,d,sl=0}} = \text{fm}_{d} \cdot \left(\frac{\delta C}{\delta t}\right)_{\text{manure}}$$
(1

where fm_d is the fraction of a component (d = 0, 1 for labile and recalcitrant) in applied manure. Additions to N_d are calculated with a similar equation (N_d for C_d). N_{inorg} is added to Diss_{sl} in the top layer (sl = 0) of the soil:

$$\left(\frac{\delta N_{diss}}{\delta t}\right)_{litter, sl=0} = \left(\frac{\delta N}{\delta t}\right)_{manure}$$
(20)

Decomposition of C from a pool C_d is calculated according to:

where K_d is the potential decomposition rate of d, τ_{sl} and m_{sl} are temperature and moisture dependent decomposition rate reductions. Decomposition of N_d is calculated with a similar equation by replacing N_d for C_d. Temperature-dependent rate reduction (τ_{sl}) is expressed as:

20
$$\tau_{\rm sl} = Q_{10}^{(\frac{T_{\rm sl} - T_{\rm OPT}}{10})}$$

Where Q_{10} is the decomposition rate response to a 10 °C increase in temperature. T_{OPT} is the optimum decomposition temperature and T_{sl} is temperature of soil layer sl



9)

(22)

1068

calculated in the temperature submodel (Fig. 1). The decomposition rate reduction factor associated with suboptimal soil moisture (m_{sl}) is expressed as:

$$m_{\rm sl} = \left(rac{ heta_{\rm sl}}{ heta_{
m opt}}
ight)^{\lambda
m dec}$$

10

where θ_{sl} and θ_{opt} are soil water content in soil layer sl, and the optimum soil water 5 content for decomposition, respectively. λ dec is a tuning parameter.

Leaching depends on the infiltration rate of moisture according to

$$\left(\frac{\delta N_{diss}}{\delta t}\right)_{leaching,sl} = f \cdot Fw_{sl} \cdot \frac{N_{diss_{sl}}}{h_{sl}}$$
(24)

where $(\frac{\delta N_{diss}}{\delta t})_{leaching,sl}$ is N_{diss} that penetrates a deeper layer. Fw_{sl} is the rate of water infiltration in layer sl (m s⁻¹), calculated in the water cycle module (Fig. 1), and *f* is a proportionality constant that expresses the fraction of N in N_{diss,sl} that is mobile (i.e. nitrate/all species of dissolved N). Equation (24) quantifies leaching of N when sl = slMax. A constant fraction *e* of N_{diss} is lost as gaseous emission $(\frac{\delta N}{\delta t})_{emission}$.

$$\left(\frac{\delta N}{\delta t}\right)_{\text{emission sl}} = e \cdot N_{\text{diss}_{\text{sl}}}$$
(25)

Organic material slowly spreads due to bioturbation (i.e. mixing of material by soil animals). OGM assumes that the rate of transport of all litter types is equal, and decreases linearly with soil depth to 1 m:

$$\left(\frac{\delta C}{\delta t}\right)_{\text{pert,d,sl}} = c_{\text{pert}} \cdot (1.0 - \text{depth}_{\text{sl}}) \cdot C_{\text{d,sl}}$$
(26)

where C_d expresses a C decomposition pool (labile or recalcitrant). Perturbation in the N pools (N_d for $d = \{0, 1\}$) is described with a similar equation by replacing C_d by

 $_{20}$ N_d. Depth_{sl} is the distance from soil surface to the center of sl, and c_{pert} is the rate of perturbation at the surface.

(23)

2.3 Model application

2.3.1 Initialization

Soil initial conditions for the top 0–60 cm in INT and EXT were derived from site-specific measurements of soil properties. Measurements for the 4 soil parameters (bulk density, organic carbon fraction, C:N ratio and porosity) are available for the layers that represent soil depth 0–60 cm. These were used to initialize associated parameters in the model (i.e. the model was not set to equilibrium). An exponential fit was used to estimate soil properties in 60–100 cm depth from measurements in 0–60 cm depth. Uncertainty limits of vegetation and model parameters were derived from published values, and tuning parameters (notation $\lambda_{\text{specification}}$ in Sect. 2.2) were given uniform a-priori uncertainty ranges. Parameters such as altitude or heat properties of soil components remained fixed. We assumed that plant functional types (e.g. legumes and grasses) and site characteristics in INT and EXT were similar. Therefore, vegetation and model parameter values were equal.

15 2.3.2 Calibration

Uncertainty distributions were estimated for the different parameters that were previously described. In the context of this analysis, the use of a-priori knowledge was limited to estimates of minimum and maximum probable parameter values that are presented in literature. The model is applied repeatedly where parameter values are changed with each model call. Note that a model call in this context, consists of two simulations: INT and EXT. After each model call, the performance of the model was evaluated considering a suit of criteria for which information is available (e.g. soil moisture, root biomass, LAI, etc.). This performance was given a score, that is calculated as the sum of the coefficient of variation of RMSE ($CV_{RMSE} = RMSE/(x_{max} - x_{min})$) where RMSE = $\sqrt{(\Sigma(y - x)^2/n)}$, *x* = measured, *y* = modeled) over the criteria. The advantage of using CV_{RMSE} as a performance quantifier is that it is unit independent (allows a



comparison of multiple criteria). When we present optimized model results, we were using parameter values that are associated with model calls that delivered the smallest value of ΣCV_{RMSE} in an extensive series (thousands) of model calls.

2.3.3 Evaluation

⁵ The model was evaluated using graphic comparisons of modeled and measured estimates. We further show normalized root mean square error (NRMSE) and coefficient of variation (R^2). NRMSE (=RMSE/ $X_{average}$) to describe goodness-of-fit. NRMSE was used instead of CV_{RMSE}, because it is more commonly used in other literature, which allows a straightforward comparison with other models.

10 2.3.4 Climate and management scenarios

The climate change signal used to specify the scenarios was obtained from a simulation with the Climate High-Resolution Model (CHRM) (Vidale et al., 2003) completed in the framework of the PRUDENCE project (Christensen and Christensen, 2007). Corresponding changes in monthly precipitation amounts, average length of wet and dry spells, minimum and maximum temperature, temperature standard deviation and solar radiation nominally valid for the end of the 21st century already given in Lazzarotto et al. (2010) are reproduced here in Table 3 for the sake of clarity. Note that GSD was defined using only the changes in precipitation, amounts and average length of wet and dry spells from April to October.

Time series of synthetic daily weather data corresponding to the different scenarios, which were later adopted as an input to OGM, were developed using the LARSWG stochastic weather generator (Semenov, 2007). For our application, LARSWG was calibrated using 27 yr of high-quality daily weather observations spanning the period 1981–2007 from an operational weather station (Wynau, 7°47' E, 47°15' N, 422 m a.s.l.) close to our study site and provided by the Swiss Federal Office for Meteorology and



Climatology (MeteoSwiss). For each of the three scenarios, the parameters defining

the stochastic generation process were adjusted using the anomalies specified in Table 3 (for details see Semenov, 2007). These adjustments were assumed to be valid in 2100; linear interpolation in time was internally applied to infer a transient evolution of the monthly climate (Lazzarotto et al., 2010).

- Ultimately, 110 yr of synthetic weather data were generated for each scenario. In addition, a 110-yr time series was also generated without modification of the calibration parameters. This simulation provides data statistically consistent with the current climate and was used in the so-called EQUIL runs (Table 4). We further used changes in the precipitation regime during April to October (Growing Season Drought, GSD)
 or changes in precipitation, temperature and solar radiation (A2-370), both with atmospheric CO₂ concentration fixed at 370 ppm, or changes in climate and CO₂ concentration.
- spheric CO_2 concentration fixed at 370 ppm, or changes in climate and CO_2 concentrations increasing to 860 ppm by 2100 (A2-860) according to predictions of atmospheric CO_2 by the Bern-CC model for the A2 emission pathway (see Appendix I in IPCC, 2000).
- Management events were forecast for each year in the period 2010–2100, by randomly picking a year between 2001 and 2010, and assuming that the recorded harvest/manuring events in this year are repeated in the forecast year. Combining two management scenarios (INT/EXT) and four scenarios for climatic change (EQUIL/GSD/A2-370/A2-860), delivered 8 model runs (Table 4). Linear Regression
 lines were fit to the last decade of soil C to determine sequestration, where soil C at 1 January 2001 and its fitted value in 2101 were used as indicators.

3 Results

3.1 Model evaluation and performance (2002–2010)

Coefficients of determination (R^2) of soil temperature ranged from 0.97 to 0.99. Normalized root mean squared error (NRMSE) ranged from 0.05 to 0.07 °C (Table 5). Coefficients of determination (R^2) of soil moisture ranged from 0.77 at 5 cm depth to 0.89



at 10 cm depth (Table 5; Fig. 2). NRMSE indicated a similar goodness of fit across different soil depths, with the best fit at 30 cm depth (NRMSE = 0.11 %), and the least fit at 50 cm depth (NRMSE = 41 %). Dry periods in the summers were usually well captured by the model. We did find however, that the level of moisture extraction tended to be slightly underestimated in top soil, while overestimated in deeper soil (compare 5)

and 10 cm soil depth with 30 and 50 cm soil depth in Fig. 2).

Legumes contributed ~22 % to LAI in EXT (average for 100 yr), typically fluctuating between ~5 % and ~35 % (Fig. 3). With time, legumes died out in INT, in agreement with the situation in the field where clover had to be re-sown in 2006. The first harvest

- ¹⁰ in each year was commonly underestimated and subsequent cuts were slightly overestimated due to an effect of growth stage (vegetative growth vs. reproductive growth) that is not implemented in the model. Additionally, the use of a constant harvest efficiency caused inadequate prediction of the extraction with individual cuts (for a review of harvest efficiency, see Ammann et al., 2007). The introduction of seasonal variabil-
- ity in growth rates and harvest efficiency could improve model predictions here, even though such inclusion would involve estimation of several additional model parameters. Modeled root biomass approximated measured amounts in 2004 (Fig. 3; Table 5). Although not directly verified, there are indications that seasonal dynamics were plausible. For instance, Garcia-Pausas et al. (2011) measured maximum seasonal fluctu ations in grass root biomass of approximately 30 % in a Pyrenees mountain grassland
 - (compare with Fig. 3).

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Aboveground litter production was $527-585 \text{ g DW m}^{-2} \text{ yr}^{-1}$ (EXT-INT), which was high compared to data from Hitz et al. (2001) who found values of 80–400 g C m⁻² yr⁻¹ in grasslands that produce 100 to 300 g DW m⁻² with individual harvests. Note that aboveground litter here, does not include harvest remnants. Belowground litter production was 758–809 g DW m⁻² yr⁻¹ (EXT-INT).

Turnover time of grass roots was 1.4 yr, whereas Van der Krift and Berendse (2002) estimated root turnover times for some typical grass species (*Lolium perenne, Arrhen-atherum elatius, Molinia caerulea, Nardus stricta*) in the range from 0.8 to 1.11 yr.



Longer turnover times (3.3–11.5 yr) were found in sub-alpine and alpine grasslands by Hitz et al. (2001).

3.1.1 Distribution of roots and soil C (2001–2006)

Root biomass in 2004 was slightly underestimated in EXT (modeled: 0.47 kg DW m⁻²; measured 0.49 kg DW m⁻²) and in INT (modeled: 0.52 kg DW m⁻²; measured 0.58 kg DW m⁻²). It was particularly underestimation in the topsoil (0–5 cm, modeled: $5.9 \text{ mg}_{\text{DW}} \text{ g}_{\text{soil}}^{-1}$; measured 7.1 ± 5.2 mg_{DW} $\text{g}_{\text{soil}}^{-1}$), whereas root biomass density in EXT in the topsoil (0–5 cm) was slightly overestimated (modeled: $5.3 \text{ mg}_{\text{DW}} \text{ g}_{\text{soil}}^{-1}$; measured $4.0 \pm 3.3 \text{ mg}_{\text{DW}} \text{ g}_{\text{soil}}^{-1}$). Note, however, that measurement errors in root biomass typically exceed lack-of-fit of the model.

Soil organic Carbon (0–45 cm) in 2006 was slightly underestimated in INT (modeled: 14.7 kg m^{-2}); measured: $14.8 \pm 1.4 \text{ kg m}^{-2}$), and overestimated in EXT (modeled: 15.3 kg m^{-2} ; measured 14.3 kg m^{-2}).

Modeled carbon concentration in INT had increased from 3.14 to 5.85 % (EXT) and from 3.10 to 4.04 % (INT) in the upper 5 cm, from 3.15 to 3.28 % (EXT) and from 3.05 to 3.16 (INT) between 5–10 cm depth. Small decreases were modeled in deeper layers (upto 0.14 %) in both INT and EXT, modeled losses were maximum in both sites at 10– 20 cm depth. The distribution of C across depth was well captured by the model (R^2 = 0.99, RMSE = 0.13–0.21 INT/EXT). Concentrations of C increase in the top 10 cm of soil, but decreased below 10 cm during 10 yr of simulation.

3.1.2 Carbon balance (2001–2010)

The model was accurate for cumulative and inter-seasonal NEE in INT (Table 5), which indicated that the magnitude of NPP, respiration and cumulative NPP + respiration over time were simulated accurately. Cumulative CO_2 fluxes were overestimated by 25%

²⁵ in EXT. Harvests were slightly underestimated in EXT but overestimated in INT. Soil in EXT started to lose C approximately 3 yr after establishment. These losses had



not stabilized in 10 yr. Biomass reached a long-term average of 714 g DW m^{-2} in EXT (belowground biomass: 620 g DW m^{-2} ; aboveground biomass: 94 g DW m^{-2}) and 751 g DW m^{-2} in INT (belowground biomass: 664 g DW m^{-2} ; aboveground biomass: 87 g m^{-2}) after approximately 4 to 5 yr (EXT and INT). Yet, stabilization of soil C was not completed until several decades in both INT and EXT (see Sect. 3.2.).

3.2 Carbon sinks in 2001–2100

Differences in soil C between climate scenarios became evident approximately 20 yr after establishment (Fig. 5). Scenarios that involved increasing concentrations of atmospheric CO_2 , in particular A2-860, led to higher soil C than the stable climate scenario (EQUIL). Differences between GSD/A2-370 scenarios and EQUIL occurred later. In

- INT, soil C accumulated until approximately 45 yr after establishment. In EXT, losses of C were predicted to continue throughout the century and for all climate scenarios, except A2-860 for which soil C loss stopped after 50 yr and increased until the end of simulation. INT accumulated C during the first 45 yr after establishment, and soil
- ¹⁵ C remained nearly constant with all scenarios except with INT/A2-860 where C accumulated throughout the century. With the EQUIL scenario, soil C in EXT continued declining after 45 yr, but the loss slowed down after 2045.

This period of stabilization was independent of climate scenario (Fig. 5). As biomass stabilized, changes in soil C were increasingly dominated by climatic effects. Towards the end of the simulation, C dynamics were effectively dominated by vegetation responding to different climatic drivers.

Compared to EQUIL, NPP was lower in precipitation scenarios (INT/GSD: -3.4%, EXT/GSD: -4.4%). NPP increased in precipitation, temperature and radiation scenarios (INT/A2-370: 3.1%, EXT/A2-370: 3.4%) and increased in climate + atmospheric

²⁵ CO₂ scenarios as well (INT/A2-860: 19.2%, EXT/A2-860: 25.2%). Harvested biomass was lower by a similar fraction in either management system in a precipitation scenario (INT/GSD: -5.4%, EXT/GSD: -5.2%). Slightly higher harvests were predicted for



scenarios that involved warming, higher radiation and lower precipitation (INT/A2-370: 3.1%, EXT/A2-370: 3.5%). Considerable increases were found for scenarios that involved higher atmospheric CO₂ together with changed climatic conditions (INT/A2-860: 7.5%, EXT/A2-860: 14.2%).

Respiration decreased in precipitation scenarios (INT/GSD: -2.4%, EXT/GSD: -3.4%), but was higher in the other scenarios (INT/A2-370: 4.1%, EXT/A2-370: 5.1%, INT/A2-860: 7.5%, EXT/A2-860: 14%).

Net C sequestration was predicted for all of the INT scenarios (INT/EQUIL: 1.3 g C m⁻², INT/GSD: 1.2 ± 0.1 g C m⁻², INT/A2-370: 1.8 ± 0.2 g C m⁻², INT/A2860: 5.3 ± 0.3 g C m⁻²). Losses of soil C resulted for all EXT scenarios except EXT/A2-860 (EXT/EQUIL: -3.1 g C m⁻²; EXT/GSD: -3.9 ± 1.1 g C m⁻²; EXT/A2-370: -2.1 ± 0.3 g C m⁻², EXT/A2-860: 1.6 ± 0.3 g C m⁻²). Across all climate scenarios, there was a consistent and considerable difference between soil C sequestration in EXT and INT. Harvest and Respiration were tightly coupled to NPP in all the climate scenarios, the ratio of harvest/NPP (in kgC kgC⁻¹) over the total simulation period ranged from 27–30% in EXT and 29–32% in INT (Fig. 5). Similarly, respiration/NPP ranged from 71–75% in EXT and from 71–74% in INT. Low respiration/NPP and harvest/NPP ratios were typically found for A2-860 in both INT and EXT. Highs were not so consistent, with maxima for both harvest and precipitation in an A2-GSD scenario (INT), but in EQUIL for her vertical and A2 270 for respiration (EXT)

²⁰ for harvest and A2-370 for respiration (EXT).

Distribution of roots and soil C in 2001–2100

Soil C increased mainly in the top 15 cm of the soil, whereas small losses occurred from 15 to 85 cm. Losses of C in EXT/EQUIL stabilized after approximately 50 yr. Until then, the model simulated C losses to occur particularly between 15 and 80 cm depth (Fig. 4),
 summing up to ~1.5 kg C m⁻² over the entire 100-yr simulation period. Hence, with time the range of depth where soil C loss occurred shifted slightly downward (compare Fig. 4 with Fig. 6).



4 Discussion

4.1 Long-term SOC

Our simulation results indicate that SOC stabilizes in EQUIL and GSD for INT, even though C loss in EXT had not come to a halt in 2100. ΔSOC after land use conversion,
 depends particularly on the balance of litter production, manure, and decomposition rates. Litter production depends on moisture and temperature, but also on seasonal aspects such as foliage cover, root density, growth and harvest efficiency. After a land use change, we can expect that litter production changes with growth rate. Decomposition of SOC depends foremost on a-biotic conditions, quality and quantity of litter. SOC
 will therefore tend to increase or decrease depending on the new balance between littering and decomposition, until it stabilizes when the level of SOC has changed to

such extend that littering and manure input equals decomposition. The level of SOC at which saturation occurs is of importance to explain our simulation results. We found ΔSOC = 7.0 %(INT) and -14.7 %(EXT), values that are lower
than those given either by Poeplau et al. (2011) or IPCC (2000, Table 1). While Poeplau et al. (2011) and IPCC (2000) review studies of lands that are exclusively managed in arable rotations, Oensingen had been under ley-arable management. Leifeld et al. (2005) found substantially higher SOC in ley-arable managed soil. The Oensingen sites contained 18–20 kg Cm⁻² prior to conversion while IPCC (2000) assumes
SOC = 8 kg Cm⁻² for croplands and arable soils that were considered by Poeplau et al. (2011) contained merely 4.6 ± 2.1 kg Cm⁻². High SOC in ley-arable managed soil may be due particularly to high litter input in rotations of grassland and seasons in which the field remained unused. Because litter input may have been of similar quantity prior to land use change, sequestration potentials with conversion to permanent

We can also compare our results with those found by Riedo et al. (2000), who modeled 3 sites with typical characteristics: Bern (high productivity), Sion (dry), and Davos (high altitude). The PaSim model was used to estimate sequestration potentials under



different management options (cutting or grazing) and climates. Assuming a scenario comparable with our A2-860 scenario (lower precipitation, higher temperatures, radiation intensity and concentrations of atmospheric CO₂; T2pm) Riedo et al. (2000) found that soil C decreased by ~5% for Bern and ~10% for Sion, but increased ~13% for Davos, relative to a reference simulation (T0P0) that involved higher atmospheric CO₂ alone.

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Our reference climate scenario (EQUIL) assumes that atmospheric CO_2 concentrations remain constant, so we ran an additional simulation using a climate scenario in which only atmospheric CO_2 increases, but temperature, precipitation and radiation remain constant. We found 4.4 % in INT (0.8 kg C m⁻²) and 4.8 % in EXT (1.0 kg C m⁻²) lower C contents compared to the reference scenario, which is very similar to results Riedo et al. (2000) found for Bern.

Our estimate indicates a sink of 0.06 kg C m⁻² in INT based on the difference between INT and EXT after 100 yr. In comparison, Lal (2007) estimated that introducing fertilization creates a sink for C of only 0.01–0.02 kg C m⁻² yr⁻¹ on average, or conversion of arable land to pasture, a sink of 0.04–0.06 kg C m⁻² yr⁻¹. While our findings in INT are very comparable with studies reviewed in Lal (2007), we found substantially lower sequestration potentials in EXT.

If we use linear extrapolation to estimate Δ SOC in 2100, we find a loss of ~3 kg C m⁻² by 2100 in INT and a similar accumulation in EXT. Hence while Δ SOC is near to constant in EXT/EQUIL during 2001–2100, it decreases in INT. Therefore, our long-term simulations indicate that the tendency observed during the first 10 yr cannot generally be extrapolated beyond approximately 20 yr. This has implications for the interpretation of field experiments that attempt to quantify possible long-term changes in SOC stock by sampling soil profiles over shorter time intervals.

We found that C accumulation initially occurs mainly in the top 10 cm of the soil, but increases to ~15 cm in the course of 100 yr simulation. In agreement, Conant et al. (2001) found that SOC increments were observed particularly in the top 10 cm soil. It is very common that SOC is not measured beyond 30 cm. In fact, the average soil



depth in studies reviewed by Conant et al. (2001) was only 32.2 cm. However, we investigated how Δ SOC changes with soil depth (Fig. 6), and we found indications that C sequestration potentials need to consider deeper layers, as root littering increases with root depth and the density of root biomass in greater depth. The change in SOC with depth is considerable in the top 50 cm of the soil at least, and the simulations suggest C loss to occur below 40 cm depth in the EXT/EQUIL scenario, and C gains above. Hence considerable changes in C sequestration potentials can occur at levels deeper than are commonly measured, although depending on site management and

history, the potentials for C accumulation at >30 cm soil depth may be small.

10 4.2 The importance of biomass turnover and manure type

We found that C sequestration potentials differ considerably according to management intensity. In more detail, two processes are particularly important: biomass turnover and manure application.

The assumption that vegetation characteristics for a cohort (grass or clover) are
the same regardless of management was inevitable because vegetation developments in INT and EXT would be equally well explained by plant characteristics (e.g. water use efficiency, biomass growth response to soil N) as by abiotic conditions (soil water content, dissolved N in the soil) if vegetation parameters had been allowed to vary freely. However inevitable, this assumption introduces some uncertainties. The seed
mixture that was used in EXT for example, contained different and more species of grasses than the mixture that was used in INT, and also contained herbs.

The use of equal biomass turnover rates in INT and EXT in particular, may lead to an overestimation of biomass senescence, and SOC, in EXT for which measured cumulative NEE was \sim 25 % higher than modeled NEE (Table 5: compare overestimation

²⁵ in EXT: NEE with underestimation in EXT: harvest). This overestimation is related to a considerable difference in "Sequestration efficiency" ($S_e = 1.0 - harvest/NEE$). between INT and EXT. Measurements indicate that S_e is considerably lower in EXT (0.15) than in INT (0.44), whereas this ratio is near to constant in the simulations (EXT: 0.37, INT:



0.40). This difference is consistent with a slight underestimation $(0.1 \text{ kg C m}^{-2})$ of soil C in 2006 in INT, and a considerable overestimation $(1.0 \text{ kg C m}^{-2})$ of modeled SOC in 2006 in EXT. Hence it is unlikely that this lack of fit is related to measurement uncertainty.

- This finding is unexpected because litter in unfertilized (nitrogen poor) grassland is 5 generally thought to decompose slower (Aerts et al., 2003). Instead a converse effect seems to dominate in EXT. For example, higher aboveground allocation could be sustained due to lower (belowground) senescence. There are two known plant adaptations to nutrient poor conditions that lead to reduced senescence in nutrient poor conditions
- (Chapin, 1980; Loualt et al, 2005). One response is instantaneous: senescence of 10 both root and shoot increases with protein concentration in the plant tissues. Moreover, root longevity may be extended due to mycorrhizal symbiosis that is stronger in nutrient poor conditions. A second response is genetic: slow-growing species are better capable to compete in nutrient poor conditions by increased longevity of biomass

(Chapin, 1980). 15

> Manure application increases soil C indirectly, via higher plant assimilation and litter production, as well as directly through manure-C amendment (Leifeld and Fuhrer, 2010; Jones et al., 2006). We tested how these two mechanisms contribute to the difference that we found with four slightly different model applications. Excluding manure-

- derived C from our INT/EQUIL simulation (Table 4; i.e. manure-N is spread among soil 20 deposition pools according to Eq. 18) would lead to a 1.0 kg Cm^{-2} lower soil C after 100 yr (i.e. it reduces C increment from 1.1 to 0.1 kg C m^{-2}). A similar difference is found when all manure-bound N is applied with inorganic fertilizer ($\Delta SOC = \sim 0.0$). The results indicate that ~60% of the manure effect on soil C over a 100-yr simulation can
- be attributed to import of C.

	BGD 9, 1055–1096, 2012							
	Differential long-term effects of climate change A. M. G. De Bruijn et al.							
	Title	Page						
D T	Abstract	Introduction						
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5 Conclusions

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We have analyzed how management and global warming interact in two grassland systems established on former cropland in Central Switzerland. The aim was to investigate the long-term relationship between climate, soil C storage and management during a

- 5 100-yr simulation period following establishment in 2002. The simulation results lead to the following conclusions:
 - 1. Intensive management (i.e. fertilization) dominates the SOC stock until ~45 yr after sowing, while climate change dominates soil C in the longer term.
 - 2. Previous arable land use has to be specified exactly to estimate potential seques-
 - tration of C is low. Prior to conversion, Oensingen grasslandse had high SOC due to the use of ley-arable rotations as compared to an exclusively arable cropping system.
 - 3. A larger fraction of the increase in soil organic C in fertilized plots originates from applied manure, compared to the input from increased amounts of plant litter.
- After establishment, soil C increases mainly in the top 10 cm of soil, but in the course of 100 yr, soil C increments are observed down to 15 cm.
 - 5. Comparing the Oensingen site with conditions that are dominant in Switzerland, C sequestration potentials may be lower at warm, low precipitation sites, but higher at cooler and wet high-altitude sites.
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	BGD 9, 1055–1096, 2012						
	Differential long-term effects of climate change						
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	Abstract	Introduction					
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	Full Scre	en / Esc					
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Table 1. Literature estimates of Δ SOC with land use conversions fi management intensivation in terms of manure applications and plough

	Author	ΔSOC	Period	Remark
Arable soil to pasture	IPCC, 2000	+100 %	long term	Static estimates of stable C in different land use types: 8 kg C m^{-2} in arable soil, 23 kg C m^{-2} in grassland
	Poeplau et al. (2011)	+39.8 ± 11 %	20 yr	Based on 24 studies/89 datapoints
		+128 ± 23 %	100 yr	Based on 24 studies/89 datapoints
	Lal (2007)	+400–600 kg ha ⁻¹	1 yr	
	Conant et al. (2001)	1010 kg ha ⁻¹	1 yr	Conversion: cultivation to pasture (23 datapoints)
	Ammann et al. (2007)	$1470 \pm 1300 \text{kg} \text{ha}^{-1}$	1 yr	Intensive management (INT) as in this manuscript
		–570 (+1300/–1100) kg ha ⁻¹	1 yr	Extensive management (EXT) as in this manuscript
Intensification	Lal (2007)	100–200 kg ha ⁻¹	1 yr	West and Post (2002) in Lal (2007)
	Conant et al. (2001)	300 kg ha ⁻¹	1 yr	Fertilization (42 datapoints)

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Table 2. Measurements taken in the context of the Oensingen experiments, used in this study(Ammann et al., 2007, 2009).

Measurement	Time span	Management
Air temperature	1981–2010	INT+EXT
Precipitation	1981–2010	INT+EXT
Soil temperature	2002–2010	INT
Soil moisture	2002–2010	INT
Root biomass	2004	INT+EXT
Leaf area index (LAI)	2003–2010	INT+EXT
Soil C/N ratio, bulk density, porosity, organic C	2002	INT+EXT
Soil-atmosphere CO ₂ exchange	2002–2010	INT+EXT
Manure application	2002–2010	INT
Cut biomass	2002–2009	INT+EXT
Harvested biomass	2002–2009	INT+EXT

Table 3. Changes (Δ) in monthly climate statistics between 2071–2100 and 1961–1990 simulated by the Climate High Resolution Model for the Swiss Plateau under the assumption of an A2 emissions scenario. Changes in mean precipitation rate (*P*), duration of wet (τ_{wet}) and dry (τ_{dry}) spells, global radiation (GR) and interannual standard deviation of air temperature (σ *T*) are relative; changes in daily maximum (T_{max}) and minimum (T_{min}) air temperature are absolute.

	ΔP	$\Delta au_{ m wet}$	$\Delta au_{ m dry}$	$\Delta T_{\rm max}$	$\Delta T_{\rm min}$	ΔσΤ	ΔGR
Month				(C)	(C)		
Jan	1.1	0.91	0.65	3.51	3.07	0.8	1.07
Feb	1.44	1.19	0.73	2.57	2.11	0.79	0.98
Mar	1.26	1.01	0.7	1.93	1.38	0.96	1
Apr	0.99	0.86	1.11	2.99	2.15	1.18	1.14
May	0.77	0.53	1.23	3.58	2.49	1.11	1.16
Jun	0.72	0.72	1.75	4.07	2.89	1.33	1.13
Jul	0.53	0.77	2.21	5.64	3.49	1.23	1.14
Aug	0.69	0.75	1.79	7.05	4.28	1.13	1.17
Sep	0.72	0.86	1.34	5.95	4	1	1.12
Oct	0.98	0.81	1.08	4.4	3	1.11	1.16
Nov	0.66	0.82	1.34	3.39	1.64	0.96	1.32
Dec	1.06	1.15	0.92	3.37	2.58	0.79	1.23



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Table 4. Climate scenarios (reps. for randomized realizations of a climate scenario).

#	Scenario	Climate scenario	Period	Reps
1	EQUIL	Climate equilibrium	2010–2100	1
2	GSD	Growing season drought	2010–2100	5
3	A2-370	Full A2 climate scenario, but with CO_2 concentration kept constant at 370 ppm	2010–2100	5
4	A2-860	Full A2 climate scenario, with CO_2 concentration reaching 860 ppm by the end of the century	2010–2100	5

Table 5. Model performance on soil temperature, soil moisture, biomass and \triangle SOC. Note that only pairs of modeled and measured values are included in cumulative and average values to facilitate comparisons. Sums of measured NEE, gap-filled with annual averages are shown in brackets. Criteria for goodness of fit are given when n > 1.

Variable		Aver	age	Cumu	lative	Good	ness of fit
		measured	modeled	measured	modeled	R^2	NRMSE
Temperature 2 cm (°C)	INT	10.6	10.6	_	-	0.97	0.06
Temperature 5 cm (°C)	INT	10.6	10.6	-	-	0.98	0.05
Temperature 10 cm (°C)	INT	10.6	10.6	-	-	0.98	0.05
Temperature 30 cm (°C)	INT	10.7	10.7	-	_	0.98	0.05
Temperature 50 cm (°C)	INT	10.6	10.7	-	-	0.97	0.07
Moisture 5 cm (%VOL)	INT	38.6	42.4	-	-	0.77	0.16
Moisture 10 cm (%VOL)	INT	40.9	42.1	-	-	0.89	0.12
Moisture 30 cm (%VOL)	INT	43	42.7	-	_	0.87	0.11
Moisture 50 cm (%VOL)	INT	44.1	41.9	-	-	0.82	0.41
LAI (m ² m ⁻²)	INT	2.06 ± 0.45	2.15	_	_	0.35	0.26
	EXT	2.03 ± 0.61	1.98	_	_	0.61	0.19
Abg biom at harvest	INT						
g DW m ⁻²	EXT	253.9 ± 166.7	243.8 ± 91.6				
Long-term clover	INT	-	0%	-	_	_	-
dominance	EXT	-	22 %	-	_	_	-
Root mass profile 2004	INT	1.55 ± 1.01	1.28	-	-	0.99	0.57
$(mgg^{-1}DW)$	EXT	1.01 ± 0.76	1.14	_	_	0.99	0.54
Root biomass 2004	INT	0.58 ± 0.26	0.52	_	_	-	-
(kg DW m^{-2})	EXT	0.49 ± 0.29	0.47	_	-	-	-
Soil C profile 2006	INT	2.93 ± 0.35	2.98	_	_	0.99	0.13
	EXT	2.74 ± 0.32	2.86	-	_	0.99	0.21
NEE (g C m ^{-2} d ^{-1})	INT	1.06	0.98	2.3(4.1)	2.1(3.8)	0.68	0.13
	EXT	0.66	0.84	1.4(2.5)	1.8(3.2)	0.58	0.11
Harvest (kg DW m ⁻²)	INT	0.19	0.19	5.3	5.4	0.54	0.22
,	EXT	0.23	0.20	4.8	4.3	0.49	0.26





Fig. 1. Overview of the Oensingen Grassland Model. The 4 solid-lined boxes are the main modules. The vegetation module can contain multiple plant functional types (here: grass and legumes in dotted boxes). The soil contains two decomposition pools, expressed in terms of C and N (dotted boxes). Arrows denote relationships between the modules. They can refer either to mass or information fluxes.





Fig. 2. Soil water content (SWC) expressed in %VOL in increasing soil depth.













Fig. 4. Root density (left) and soil carbon (right) for EXT (upper pane) and INT (lower pane). Measurements are given \pm se.



Fig. 5. Simulations of soil organic C (in gCm^{-2}) between 2001–2100. Top panel: C budget, 100 yr after establishment of grassland. Bottom panel: temporal C dynamics during between 2001–2100 (inset: simulations of SOC between 2051–2052 for INT, upper and EXT, bottom. Management activities are shown as H = harvest; M_i and M_{i+o} = inorganic and organic plus inorganic manure application, respectively). Legend entries: NPP = Net Primary Productivity, Harvest = extracted biomass, Resp: heterotrophic respiration, Bal: C balance (soil+biomass).







