

The status and challenge of global fire modelling

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48 **Abstract.** Biomass burning impacts vegetation dynamics, biogeochemical cycling, atmospheric chemistry, and
49 climate, with sometimes deleterious socio-economic impacts. Under future climate projections it is often expected
50 that the risk of wildfires will increase. Our ability to predict the magnitude and geographic pattern of future fire
51 impacts rests on our ability to model fire regimes, either using well-founded empirical relationships or process-based
52 models with good predictive skill. While a large variety of models exist today, it is still unclear which type of model
53 or degree of complexity is required to model fire adequately at regional to global scales. This is the central question
54 underpinning the creation of the Fire Model Intercomparison Project - FireMIP, an international initiative to compare
55 and evaluate existing global fire models against benchmark data sets for present-day and historical conditions. In this
56 paper we review how fires have been represented in fire-enabled DGVMs and give an overview of the current state-
57 of-the-art in fire regime modelling. We indicate which challenges still remain in global fire modelling and stress the
58 need for a comprehensive model evaluation and outline what lessons may be learned from FireMIP.

59

60 1. Introduction

61 Each year, about 4% of the global vegetated area is burned (Giglio et al., 2013; Randerson et al., 2012). Fire is the
62 most important type of disturbance and as such is a key driver of vegetation dynamics (Bond et al., 2005), both in
63 terms of succession and in maintaining fire-adapted ecosystems (Furley et al., 2008; Staver et al., 2011; Hirota et al.,
64 2011; Rogers et al., 2015). Fires play an essential role in ecosystem functioning, species diversity, plant community
65 structure and carbon storage. The impact fire has on the ecosystem depends on the local fire regime, which includes a
66 range of important characteristics such as fire frequency, intensity, seasonality, etc. Fire is also important through its
67 effect on radiative forcing, biogeochemical cycling and biogeophysical effects (Bond-Lamberty et al., 2007;
68 Bowman et al., 2009; Ward et al., 2012, Yue et al., 2015).

69 Global carbon dioxide emissions from biomass burning are estimated to be about 2 PgC ($P = 10^{15}$) per year of which
70 approximately 0.6 PgC/yr comes from tropical deforestation and peat fires (van der Werf et al., 2010). This is
71 equivalent to ca 25% of those from fossil fuel combustion (Boden et al., 2013; Ciais et al., 2014), although in the
72 absence of climate and/or land use change, nearly all of these emissions are taken up during vegetation regrowth
73 after fire. Together, fire significantly decreases the net carbon gain of global terrestrial ecosystems by 1.0 Pg C yr⁻¹
74 averaged across the 20th century (Li et al., 2014). Fire emissions are also an important driver of inter-annual
75 variability in the atmospheric growth rate of CO₂ (van der Werf et al., 2004; van der Werf et al., 2010; Prentice et al.,
76 2011; Guerlet et al., 2013) and a significant contribution to the atmospheric budgets of CH₄, CO, N₂O and many
77 other atmospheric constituents. As a source of aerosol (including black carbon) and ozone precursors (Voulgarakis
78 and Field, 2015), emissions from fires contribute directly and indirectly to radiative forcing (Myhre et al., 2013;
79 Ward et al., 2012), reducing net shortwave radiation at the surface and warming the lower atmosphere, thus affecting
80 regional temperature, clouds, and precipitation (Tosca et al., 2010; Tosca et al., 2014; Ten Hoeve et al., 2012;
81 Boucher et al., 2014) and regional to large-scale atmospheric circulation patterns (Tosca et al., 2013; Zhang et al.,
82 2009). Through their impacts on ozone, and as a source of CO and volatile organic compounds, fires also affect the

83 atmospheric abundance of the OH radical, which determines the atmospheric lifetime of the greenhouse gas methane
84 (Bousquet et al., 2006). In addition, ozone produced from fires is directly harmful to plants, reducing photosynthesis
85 (Pacifico et al., 2015) and fire-emitted aerosol can shift the balance between diffuse and direct radiation (Mercado et
86 al., 2009; Cirino et al., 2014). Deposition of fire produced N- (Chen et al., 2010) and P-aerosols (Wang et al., 2015)
87 can enhance productivity in nutrient limited ecosystems.

88 Fire also has direct effects on human society: more than 5 million people globally were affected by the 300 major
89 fire events in the past 30 years, with economic losses of more than US\$ 50 billion (EM-DAT; <http://www.emdat.be>).
90 Air quality is regionally affected by the occurrence of fire due to increases in aerosol and ozone that are harmful to
91 human health. At a regional scale, hospitalisations and human deaths increase in major fire years (Marlier et al.,
92 2013). The degradation of air quality caused by fire is estimated to result in 260,000 to 600,000 premature deaths
93 globally each year (Johnston et al., 2012).

94 Given that fire impacts so many aspects of the earth system, there is considerable concern about what might happen
95 to fire regimes in response to projected climate changes in the 21st century. However, as the IPCC Fifth Assessment
96 Report (AR5) made clear, “There is low agreement on whether climate change will cause fires to become more or
97 less frequent in individual locations” (Settele et al., 2014). This is in large part due to the complexity of the
98 interactions and feedbacks between vegetation, people, fire and other elements of the earth system (Fig. 1), which is
99 not well represented in current Earth System Models. Fire, vegetation and climate are intimately linked: changes in
100 climate drive changes in fire as well as changes in vegetation that provides the fuels for fire, and in return fire alters
101 vegetation structure and composition, with feedbacks to climate through changing surface albedo, ecosystem
102 properties, transpiration, and as a source of CO₂, other trace gases, and aerosols, altering atmospheric composition
103 and chemistry (Ward et al., 2012). Human activities strongly affect fire regimes (Bowman et al., 2011; Archibald et
104 al., 2013) due to the use of fire for land management, while the use of fire as a tool in the deforestation process is still
105 occurring in the tropics (e.g. Morton et al., 2008). Humans may also suppress fire directly or indirectly through land-
106 use change (Bistinas et al., 2014; Knorr et al., 2014; Andela and van der Werf, 2014). Grazing herbivores (the
107 densities of which are also often controlled by humans) can also decrease fire occurrence by reducing fuel loads
108 (Pachzelt et al. 2015).

109 Statistical models have been used to examine the potential trajectory of changes in fire during the 21st century (e.g.
110 Moritz et al., 2012; Settele et al., 2014). Such models essentially assess the possibility of fire occurring given climate
111 conditions and fuel availability (fire risk or fire danger) based on modern day relationships between climate, fuel and
112 some aspect of the fire regime such as burnt area. However, changes in fire risk/danger will not necessarily be
113 closely coupled to changes in fire regime in the future given the direct impacts of CO₂ on water-use efficiency,
114 productivity, vegetation density and ultimately vegetation composition and distribution. This limits the utility of
115 statistically-based models for the investigation of feedbacks to climate through fire-driven changes of land-surface
116 properties, vegetation structure or atmospheric composition – feedbacks which have the potential to exacerbate or
117 ameliorate the effects of future climate change on ecosystems, as well as influence the security and well-being of
118 people.

119 In contrast to statistical models, fire-enabled dynamic global vegetation models (DGVMs) and terrestrial ecosystem
120 models (TEMs) can address some of the feedbacks between fire and vegetation. Coupling fire-enabled DGVMs with
121 climate and atmospheric chemistry models in an Earth System Model (ESM) framework allows the feedbacks
122 between fire and climate to be examined. There has been a rapid development of fire-enabled DGVMs in the past
123 two decades with many DGVM's currently including fire as a standard process. Four out of the 15 carbon-cycle
124 models in the MsTMIP (Multi-scale Synthesis and Terrestrial Model) intercomparison project (Huntzinger et al., in
125 press), five out of 10 carbon-cycle models in TRENDY (Trends in net land-atmosphere carbon exchange over the
126 period 1980–2010; <http://dgvn.ceh.ac.uk/>), and 9 ESMs in CMIP5 (fifth phase of the Coupled Model
127 Intercomparison Project; <https://pcmdi.llnl.gov/search/esgf-llnl/>) provide fire-related outputs. The complexity of the
128 fire component of these models varies enormously—from simple empirically-based schemes to predict burnt area,
129 through models that explicitly simulate the process of ignition and fire spread, to models that incorporate fire
130 adaptations and their impact on the vegetation response to fire. However, to date there has been no systematic
131 comparison and evaluation of these models, and thus there is no consensus about the level of complexity required to
132 model fire and fire-related feedbacks realistically.

133 The Fire Model Intercomparison Project (FireMIP), initiated in 2014, is a collaboration between fire modelling
134 groups worldwide to address this issue. Modelling groups participating in FireMIP will run a set of common
135 experiments to examine fire under present-day and past climate scenarios, and will conduct systematic data-model
136 comparisons and diagnosis of these simulations with the aim of providing an assessment of the reliability of future
137 projections of changes in fire occurrence and characteristics. There has been no previous attempt to compare fire
138 models across a suite of standardised experiments (model-model comparison) or to systematically evaluate model
139 performance using a wide range of different benchmarks (data-model comparison).

140 The main objective of the current manuscript is to present an overview of the current state-of-the-art fire-enabled
141 DGVMs as a background to the FireMIP initiative. We first present an overview of the current state of knowledge
142 about the drivers of global fire occurrence. We indicate how these have been treated over time in different fire
143 models and describe the variety in state-of-the-art fire-enabled DGVMs. Finally, we give a short overview of the
144 plans for FireMIP and the overall philosophy behind the model benchmarking and evaluation.

145

146 **2. The controls on fire**

147 Fire is driven by complex interactions between climate, vegetation and people (Fig. 1), which vary in time and space.
148 On meteorological time scales (i.e. minutes to days) and limited spatial scales (i.e. metres to kilometres), atmospheric
149 circulation patterns and moisture advection determine the location, incidence and intensity of lightning storms that
150 produce fire ignitions. Weather and vegetation state also determine surface wind speeds and vapour-pressure
151 gradients, and hence the rates of fuel drying, which in turn affect the probability of combustion as well as fire spread.
152 However, topography also affects the spread of fire: fire fronts travel faster uphill because of upward convection of
153 heat while rivers, lakes, and rocky outcrops can act as natural barriers to fire fronts.

154 On longer time scales (i.e. seasons to years) and larger spatial scales (i.e. regional to continental), temperature and
155 precipitation exert a major effect on fire because these climate variables influence net primary productivity (NPP),
156 vegetation type and the abundance, composition, moisture content, and structure of fuels. Burnt area tends to be
157 lowest in very wet or very dry environments, and highest where the water balance is intermediate between these two
158 states. Related to this, burnt area is greatest at intermediate levels of NPP and decreases with both increases and
159 decreases in productivity. These unimodal patterns along precipitation or productivity gradients emerge due to the
160 interaction between moisture availability and productivity: dry areas have low NPP which limits fuel availability and
161 continuity, while NPP and hence fuel loads are high in wet areas but the available fuel is generally too wet to burn.
162 Temperature exerts an influence on the rate of fuel drying in addition to its influence on NPP. Seasonality in water
163 availability also plays a role here: for any given total amount of precipitation, fire is more prevalent in seasonal
164 climates because fuel accumulates rapidly during the wet season and subsequently dries out. While the vegetation
165 and fuel exert an important control on fire occurrence, fire impacts vegetation distribution and structure, causing
166 important vegetation-fire feedbacks. At a local scale fires create spatial heterogeneity in fuel amount, influencing
167 subsequent fire spread and limiting fire growth.

168 While natural factors are important drivers of global fire occurrence, human influences are also pervasive. People
169 start fires, either accidentally or with a purpose, for example for forest clearance, agricultural waste burning, pasture
170 management, or fire management. People can also affect fire regimes through land conversion from less flammable
171 (forest) vegetation to more flammable (grassy) vegetation. The introduction of flammable invasive species is another
172 cause of changing fire occurrence. Changes in land use can also reduce fuel loads through crop harvesting, grazing
173 and forestry. Human activities lead to fragmentation of natural vegetation which affects fire spread and fires are also
174 actively suppressed. There is a unimodal statistical relationship between burnt area and population density. At
175 extremely low population densities, increasing population is associated with an increase in fire numbers and burnt
176 area. At high population densities, increasing population is associated with a decrease in burnt area. However, in
177 general when climate and vegetation factors are accounted for, there is a monotonic negative relationship between
178 burnt area and human population, i.e. burned area decreases with increasing human presence (Bistinas et al., 2014;
179 Knorr et al., 2014). The unimodal statistical relationship of burnt area with population density (and other socio-
180 economic variables such as gross domestic product, GDP, that are linked to population density) results from the co-
181 variance of population density with vegetation production and moisture (Bistinas et al., 2014). Low population
182 densities are found in very dry or cold climates where vegetation productivity and fuel loads are also minimal. High
183 population densities are (generally) found in moist environments with high vegetation productivity but where moist
184 conditions limit fire spread.

185

186 **3. History and current status of global fire modelling**

187 While not explicitly representing fire occurrence, early vegetation models often included a generic treatment of
188 disturbance on plant mortality. There are two basic types of fire models that are applied in global vegetation models

189 (Fig. 2): (a) top-down “empirical models” based on statistical relationships between key variables (climate,
190 population density) and some aspect of the fire regime, usually burnt area; and (b) bottom-up “process-based
191 models” which represent small-scale fire dynamics (i.e. by simulating individual fires), before scaling up to calculate
192 fire metrics for an entire grid cell. The boundaries between these two types are not rigid, however, and some models
193 combine features of both. Fire models have developed in parallel, and there have been differences as well as some
194 overlap between the approaches taken by different models to representing key processes. Our goal here is therefore
195 not to describe every single fire model in detail, but rather to outline the major approaches to key processes and in
196 particular to focus on models when they introduced fundamentally new approaches.

197 **3.1 Empirical global fire models**

198 The absence of global-scale fire information before remotely sensed burnt area products became available was a
199 common challenge to the development of fire models and hindered testing and parameterisation of empirical
200 algorithms. The GLOBal FIRE Model (Glob-FIRM) (Thonicke et al., 2001) was the first global fire model, based on
201 the notion that once there is sufficient combustible material burned area depends on the length of the fire season. The
202 fire season length is calculated as the summed daily “probability of fire” which is a function of the fuel moisture
203 (approximated by the moisture in the upper soil layer), and the moisture of extinction. The functions relating
204 moisture content, fire season length, and burnt area were calibrated using site-based observations. In addition, Glob-
205 FIRM has a threshold value of 200 gC/m^2 to represent the point at which fuel becomes discontinuous and the
206 probability of fire occurring is zero. Glob-FIRM was initially developed for inclusion in the Lund-Potsdam-Jena
207 (LPJ) DGVM (Sitch et al., 2003), but has since been coupled into several other DGVMs (with some modifications),
208 including the Common Land Model (Dai et al., 2003), the Community Land Model (CLM) (Levis et al., 2004), the
209 ORganizing Carbon and Hydrology In Dynamic Ecosystems (ORCHIDEE) (Krinner et al., 2005), the Lund-
210 Potsdam-Jena General Ecosystem Simulator (LPJ-GUESS) (Smith et al., 2001), the Biosphere Energy-Transfer
211 Hydrology model (BETHY) (Kaminski et al., 2013), and the Institute of Atmospheric Physics, Russian Academy of
212 Sciences Climate Model (IAP RAS CM) (Eliseev et al., 2014). A simple fire model with a similar structure to Glob-
213 FIRM, has also been included in the Jena Scheme for Biosphere-Atmosphere Coupling in Hamburg (JSBACH)
214 global vegetation model (Reick et al., 2013).

215 Some empirical models include human impacts on fire occurrence. Typically, algorithms are used that link fire
216 probability/frequency to both an estimate of lightning ignition and to human population density. Pechony and
217 Shindell (2009) proposed an algorithm whereby the number of fires increases with population, levelling off at
218 intermediate population densities and then decreasing to mimic fire suppression under high population densities
219 (Table 1). The simulated number of fire counts is then converted into burnt area using an “expected fire size” scaling
220 algorithm (Pechony and Shindell, 2009). The human ignition and suppression relationships described by Pechony
221 and Shindell (2009) have been adopted by several other, both empirical and process based fire-vegetation models
222 (Table 1). INteractive Fires and Emissions algoRithm for Natural enviroNments (INFERNO) (Mangeon et al., 2016)
223 is an integrated fire and emission model for JULES and HadGEM (the UK Met Office’s coupled climate model)
224 based on the Pechony & Shindell (2009) approach, but water vapour pressure deficit is used as one of the main

225 indicators of flammability in the model, while an inverse exponential relationship is used to relate flammability to
226 soil moisture. In an alternative approach, Knorr et al. (2014) used a combination of weather information (to account
227 for fire risk) with remotely-sensed data of vegetation properties that are linked to fire-spread and information on
228 global population density to derive burned area in a multiple-regression approach. This model has been coupled to
229 LPJ-GUESS DGVM (Knorr et al., 2016).

230

231 **3.2 Process-based global fire models**

232 MC-FIRE (Lenihan et al., 1998; Lenihan and Bachelet 2015) was the first attempt to simulate fire via an explicit,
233 process-based, Rate of Spread (RoS) model. MC-FIRE calculates whether a fire occurs in a grid cell on a given day,
234 based on whether the grid cell is experiencing drought conditions and that the “probability of ignition and spread,” as
235 jointly determined by the moisture of the fine fuel class and the simulated rate of spread, is greater than 50%. The
236 rate of spread is calculated based on equations by Rothermel (1972), which represent the energy flux from a flaming
237 front based on fuel size, moisture, and compaction. Canopy fires are initiated using the van Wagner (1993)
238 equations. All of the grid cell is assumed to burn if a fire occurs, i.e. the original MC-FIRE was designed to simulate
239 large, intense fires. Later work introduced functions to suppress area burned by low-intensity and/or slow-moving
240 fires (Rogers et al., 2011). MC-FIRE inspired the development of several process-based RoS based models, and
241 many fire-enabled DGVMs still use a similar basic framework (Table 1).

242 The Regional Fire Model (Reg-FIRM: Venevsky et al., 2002) introduced a new approach in fire modelling by
243 simulating burned area as the product of number of fires and average fire size. Reg-FIRM assumes a constant global
244 lightning ignition rate, and includes human ignitions depending on population density. It then uses the Nesterov
245 Index, an empirical relationship between weather and fire, to determine the fraction of ignitions that start fires. Every
246 fire occurring during a given day in a given grid cell is assumed to have the same properties and thus to be the same
247 size. Reg-FIRM uses a simplified form of the Rothermel (1972) equations to calculate rate of spread; these
248 effectively depend only on wind speed, fuel moisture (as approximated by near-surface soil moisture), and PFT-
249 dependent fuel bulk density. Fire duration is determined stochastically from an exponential distribution with a mean
250 of 24 hours, to account for the fact that less frequent large fires account for a disproportionate amount of the total
251 area burned. The RoS equations are used to estimate the burned surface by approximating the shape of the fire as an
252 ellipse, as suggested by van Wagner (1969).

253 The fire module in the Canadian Terrestrial Ecosystem Model (CTEM: Arora & Boer, 2005; Melton and Arora,
254 2016), uses a variant on the Reg-FIRM scheme where the pre-defined FDI approach is replaced by an explicit
255 calculation of susceptibility, which is the product of the probabilities associated with fuel, moisture, and ignition
256 constraints on fire (Table 1). Ignitions are either caused by lightning, the incidence of which varies spatially, or
257 anthropogenic. Anthropogenic ignition is constant in CTEMv1 (Arora & Boer, 2005) but varies with population
258 density in CTEMv2 (Melton and Arora, 2016). As in Reg-FIRM, fire duration is determined in such a way as to
259 incorporate the disproportionate area burned by long-lasting fires, but CTEM does this deterministically rather than

260 stochastically. CTEM includes fire suppression via a “fire extinguishing” probability to account for suppression by
261 natural and man-made barriers, as well as deliberate human suppression of fires. The fire model development in
262 CLM (Kloster et al. 2010, and Li et al., 2012; 2013) is based on the CTEM work but introduced anthropogenic
263 ignitions and suppression on fire occurrence as functions of population density. Li et al. (2013) set anthropogenic
264 ignitions and suppression also as functions gross domestic production (GDP), and introduced human suppression on
265 fire spread.

266 The SPread and InTensity of FIRE (SPITFIRE) model (Table 1) (Thonicke et al., 2010) is a RoS-based fire model
267 developed within the Lund-Potsdam-Jena (LPJ) DGVM. It is a further development of the Reg-FIRM approach, but
268 SPITFIRE uses a more complete set of physical representations to calculate both rate of spread and fire intensity.
269 However, maximum fire duration is limited to four hours. Anthropogenic ignitions are a function of population
270 density as in REGFirm, although the function is regionally tuned in SPITFIRE. Fire is excluded from agricultural
271 areas but SPITFIRE effectively includes human fire suppression on other lands because human ignitions first
272 increase and then decrease with increasing population density. The SPITFIRE model has been implemented with
273 modifications in other DGVMs, including ORCHIDEE (Yue et al., 2014), JSBACH (Lasslop et al., 2014), LPJ-
274 GUESS (Lehsten et al., 2009), and CLM(ED) (Fisher et al., 2015).

275 Some fire models based on SPITFIRE, such as the Land surface Processes and eXchanges model (LPX) (Prentice et
276 al., 2011; Kelley et al., 2014) and the Lausanne-Mainz fire model (LMfire) (Pfeiffer et al., 2013), have introduced
277 further changes to the ignitions scheme. Natural ignition rates in both models are derived from a monthly lightning
278 climatology, as in SPITFIRE, but LPX preferentially allocates lightning to days with precipitation (which precludes
279 burning) such that only a realistic number of days have ignition events. Similarly to LPX, LMfire limits lightning
280 strikes to rain days, and also estimates interannual variability in lightning ignitions by scaling a lightning climatology
281 using long-term time-series of convective available potential energy (CAPE) produced by atmosphere models.
282 LMfire further reduces lightning ignitions based on the fraction of land already burnt, since lightning tends to strike
283 repeatedly in the same parts of the landscape while being rare in others. LPX and LMfire also modified the treatment
284 of anthropogenic burning relative to the original SPITFIRE. LMfire specified that the number of anthropogenic
285 ignitions differs amongst livelihoods by distinguishing human populations into three basic categories: hunter-
286 gatherers, pastoralists, and farmers. Each of these populations has different behaviour with respect to burning based
287 on assumptions regarding land management goals. LPX, on the other hand, does not include human ignitions on the
288 grounds that the supposed positive relationship of population density to fire activity is an artefact, as discussed
289 above. Finally, LMfire accounts for the constraint on fire spread imposed by fragmentation of the burnable landscape
290 by human land use (as well as topography) while individual fires are allowed to burn across multiple days, and fires
291 occurring simultaneously within the same grid cell can effectively coalesce as they grow larger. Like LMfire, the
292 HESFIRE model (Le Page et al., 2015) also focuses on the constraints on fire spread – using landscape
293 fragmentation (due to human activities, topography, or past fire events) to determine the probability of extinction of a
294 fire that is ignited.

295 Schemes to simulate anthropogenic fire associated explicitly with land-use change have also been developed. Kloster
296 et al. (2010) include burning associated with land-use change by assuming that some fraction of cleared biomass is
297 burned. This fraction depends on the probability of fire as mediated by moisture, such that the combusted fraction is
298 low in wet regions (e.g. northern Europe) and high in dry regions (e.g. central Africa). Li et al. (2013) proposed an
299 alternative scheme to model fires caused by deforestation in the tropical closed forests, in which fires depended on
300 deforestation rate and weather/climate conditions, and were allowed to spread beyond land-type conversion regions
301 when weather/climate conditions are favourable. When the scheme was used in their global fire model, fires due to
302 human and lightning ignitions described in Li et al. (2012) were not used in the tropical closed forests. Li et al.
303 (2013) also include cropland management fires, prescribing seasonal timing based on satellite observations but
304 allowing the amount of burning to depend on the amount of post-harvest waste, population density, and gross
305 domestic product, and fires in peatlands, depending on a prescribed area fraction of peatland distribution, climate and
306 area fraction of soil exposed to air. The Li et al. scheme has been the basis for the fire development in the Dynamic
307 Land Ecosystem Model (DLEM) (Yang et al., 2015). A simple representation of peat fires is also present in the IAP
308 RAS CM (Eliseev et al., 2014).

309

310 **3.3 Modelling the impact of fire on vegetation and emissions**

311 The impact of fire on vegetation operates through combustion of available fuel, plant mortality, and triggering of
312 post-fire regeneration. There is more similarity in the treatment of fire impacts between models than many other
313 aspects of fire.

314 Glob-FIRM assumes that all the aboveground litter/biomass is burnt, while subsequent models assume that only a
315 fraction of the available fuel is burnt. In CTEM, the completeness of combustion varies by fuel class and PFT (Arora
316 and Boer, 2005) while models such as MC-FIRE and SPITFIRE include a dynamic scheme for completeness of
317 combustion which depends on fire characteristics and the moisture content of each fuel class (Thonicke et al., 2010;
318 Lenihan et al., 1998).

319 Post-fire vegetation mortality is generally represented in a relatively simple way in fire-enabled DGVMs (Table 2).
320 Glob-FIRM, CTEM, Reg-FIRM, and the models described by Li et al. (2012) and Kloster et al. (2010) use PFT-
321 specific parameters for fractional mortality. MC-FIRE has a more explicit treatment of mortality, in which fire
322 intensity and residence time influence tree mortality from ground fires via crown scorching and cambial damage.
323 Canopy height relative to flame height (which is a function of fire intensity) determines the extent of crown
324 scorching. Bark thickness, which scales with tree diameter, protects against damage to the trunk, such that thicker-
325 barked trees have more chance of surviving a fire of a given residence time. LPJ-SPITFIRE uses a similar approach
326 except that bark thickness scales with tree diameter, which, together with canopy height depends on woody biomass.
327 LMfire includes a simple representation of size cohorts within each PFT, with the bark thickness scalar being defined
328 explicitly for each size cohort. In contrast, gap-based vegetation-fire models such as LPJ-GUESS-
329 SPITFIRE/SIMFIRE (Lehsten et al. 2009; Knorr et al. 2016) and CLM(ED) (Fisher et al. 2015), explicitly simulate

330 size cohorts within patches characterised by differential fire-disturbance histories. LPX-Mv1 (Kelley et al., 2014)
331 incorporates an adaptive bark thickness scheme, in which a range of bark thicknesses is defined for each PFT. Since
332 thinner-barked trees are more likely to be killed by fire, the distribution of bark thickness within a population
333 changes in response to fire frequency and intensity.

334 LPX-Mv1 (Kelley et al., 2014) is the only model to date to incorporate an explicit fire-triggered regeneration
335 process, through creating resprouting variants of the temperate broad-leaved and tropical broad-leaved tree PFTs.
336 Resprouting trees are penalised by having low recruitment rates into gaps caused by fire and other disturbances.
337 However, resprouting is only one part of the syndrome of vegetation responses to fire which include e.g. obligate
338 seeding, serotiny, and clonal reproduction (e.g. Pausas and Keeley, 2014).

339

340 **4. Objective and organization of FireMIP**

341 Existing fire models have very different levels of complexity, both with respect to different aspects of the fire regime
342 within a single model and with respect to different families of models. It is not clear what level of complexity is
343 appropriate to simulate fire regimes globally. Given the increasing use of fire-enabled DGVMs to project the impacts
344 of future climate changes on fire regimes and estimate fire-related climate feedbacks (e.g. Knorr et al., 2016; Kelley
345 and Harrison, 2014; Kloster et al., 2012; Pechony and Shindell, 2010), it is important to address this question.

346 Coordinated experiments using identical forcings allow comparisons focusing on differences in performance driven
347 by structural differences between models. The baseline FireMIP simulation will use prescribed climate, CO₂,
348 lightning, population density, and land use forcings from 1700 through 2013. Examination of the simulated
349 vegetation and fire during the 20th century will allow differences between models to be quantified, and any
350 systematic differences between types of models or with model complexity to be identified.

351 However, a single experiment of this type is unlikely to be sufficient to diagnose which processes cause the
352 differences between models. Various approaches can be used for this purpose, including sensitivity experiments and
353 parameter-substitution techniques. Similarly, the effect of model complexity can be examined by switching off
354 specific processes. In FireMIP, experiments will be performed to study the impact of lightning, pre-industrial burned
355 area, CO₂, nitrogen, and fire itself, between different models.

356 Many model intercomparison projects have shown that model predictions may show reasonably good agreement for
357 the recent period but then diverge strongly when forced with a projected future climate scenario (e.g. Flato et al.,
358 2014; Friedlingstein et al., 2014; Harrison et al., 2015). “Out-of-sample” evaluation is one way of identifying
359 whether good performance under modern conditions is due to the concatenation of process tuning. Within FireMIP,
360 we will use simulations of fire regimes for different climate conditions in the past (i.e., outside the observational era
361 used for parameterisation and/or parameter tuning) as a further way of evaluating model performance and the causes
362 of model-model differences.

364 5. Benchmarking and evaluation in FireMIP

365 Evaluation is integral to the development of models. Most studies describing vegetation-model development provide
366 some assessment of the model's predictive ability by comparison with observations (e.g. Sitch et al., 2003;
367 Woodward and Lomas, 2004; Prentice et al., 2007). However, these comparisons often focus on the novel aspects of
368 the model and are largely based on qualitative measures of agreement such as map comparison (e.g. Gerten et al.,
369 2004; Arora and Boer, 2005; Thonicke et al., 2010; Prentice et al., 2011). However, they often do not track
370 improvements or degradations in overall model performance caused by these new developments. The concept of
371 model benchmarking, promoted by the International Land Model Benchmarking Project (ILAMB: <http://www.ilamb.org>),
372 is based on the idea of a comprehensive evaluation of multiple aspects of model performance against a standard
373 set of targets using quantitative metrics. Model benchmarking has multiple functions, including (a) showing whether
374 processes are represented correctly, (b) discriminating between models and determining which perform better for
375 specific processes, and (c) making sure that improvements in one part of a model do not compromise performance in
376 another (Randerson et al., 2009; Luo et al., 2012; Kelley et al., 2013). Since fire affects many inter-related aspects of
377 ecosystem dynamics and the Earth system, with many interactions being non-linear, the latter is particularly
378 important for fire modelling.

379 Kelley et al. (2013) have proposed the most comprehensive vegetation-model benchmarking system to date. This
380 system provides a quantitative evaluation of multiple simulated vegetation properties, including primary production,
381 seasonal net ecosystem production, vegetation cover, composition and height, fire regime and runoff. The
382 benchmarks are derived from remotely sensed gridded datasets with global coverage, and site-based observations
383 with sufficient coverage to sample a range of biomes on each continent. Data sets derived using a modelling
384 approach that involves calculation of vegetation properties from the same driving variables as the models to be
385 benchmarked are explicitly excluded. The target datasets in the Kelley et al. (2013) scheme allow comparisons of
386 annual average conditions, seasonal and inter-annual variability. They also allow the impact of spatial and temporal
387 biases in means and variability to be separately assessed. Specifically designed metrics quantify model performance
388 for each process, and are compared to scores based on the temporal or spatial mean value of the observations and to
389 both a "mean" and "random" model produced by bootstrap resampling of the observations. The Kelley et al. (2013)
390 scheme will be used for model evaluation and benchmarking in FireMIP. It has been shown that spatial resolution
391 has no significant impact on the metric scores for any of the targets (Harrison and Kelley, unpublished data);
392 nevertheless, model outputs will be interpolated to the 0.5° common grid of the data sets for convenience.

393 The Kelley et al. (2013) scheme does not address key aspects of the coupled vegetation-fire system including the
394 amount of above-ground biomass and/or carbon, fuel load, soil moisture, fuel moisture, the number of fire starts, fire
395 intensity, the amount of biomass consumed in individual fires, and fire-related emissions. Global datasets describing
396 some of these properties are now available, and will be included in the FireMIP benchmarking scheme. These data
397 sets include above-ground biomass both derived from vegetation optical depth (Liu et al., 2015) and ICESAT-GLAS

398 LiDAR data (Saatchi et al., 2011), the European Space Agency Climate Change Initiative Soil Moisture product
399 (Dorigo et al., 2010), the Global Fire Assimilation System biomass burning fuel consumption product, fire radiative
400 power, and biomass-burning emissions (Kaiser et al., 2012), and fuel consumption (van Leeuwen et al., 2014). The
401 selection of new data sets is partly opportunistic, but reflects the need both to evaluate all aspects of the coupled
402 vegetation-fire system and the importance of using data sets that are derived independently of any vegetation model
403 that uses the same driving variables as the coupled vegetation-fire models being benchmarked. The goal is to provide
404 a sufficient and robust benchmarking scheme for evaluation of fire while ensuring that other aspects of the vegetation
405 model can also be evaluated, and to this end new data sets will be incorporated into the FireMIP benchmarking
406 scheme as they become available during the project.

407 The FireMIP benchmarking system will represent a substantial step forward in model evaluation. Nevertheless there
408 are a number of issues that will need to be addressed as the project develops, specifically how to deal with the
409 existence of multiple data sets for the same variable, how to exploit process understanding in model evaluation, and
410 how to ensure that models which are tuned for modern conditions can respond to large changes in forcing. The
411 answers to these questions remain unclear, but here we provide insights into the nature of the problem and suggest
412 some potential ways forward.

413 The selection of target data sets, in particular how to deal with differences between products and uncertainties, is an
414 important issue in benchmarking. There are, for example, multiple burnt area products (e.g. GFED4, L3JRC,
415 MCD45, and Fire_cci: see Table 3). In addition to the fact that all of these products systematically underestimate
416 burnt area because of difficulties in detecting small fires (Randerson et al., 2012, Padilla et al., 2015), they differ
417 from one another. Although all four products show a similar spatial pattern with more burnt area in the tropical
418 savannas and less in temperate and boreal regions, L3JRC and MCD45 have a higher total burnt area than MERIS or
419 GFED4 (Table 3). Differences between products are lower (though still substantial) in the tropical savannas than
420 elsewhere; extra-tropical regions are the major source of uncertainty between products (Fig. 3a). The same is true for
421 interannual variability (Fig. 3b), where differences between products are higher in regions where total burnt area is
422 low. Most products show an increase in burnt area between 2001 and 2007 in extra-tropical regions, but there are
423 disagreements even for the sign of regional changes (Fig. 3c). These types of uncertainties, which are also
424 characteristic of other data sets, need to be taken into account in model benchmarking—either by focusing on regions
425 or features which are robust across multiple products or by explicitly incorporating data uncertainties in the
426 benchmark scores (see e.g. Hargreaves et al., 2013).

427 Process analyses can provide an alternative approach to model evaluation. The idea here is to identify relationships
428 between key aspects of a system and potential drivers, based on analysis of observations, and then to determine
429 whether the model reproduces these relationships (see e.g. Lasslop et al., 2014; Li et al., 2014). It is important to use
430 techniques that isolate the independent role of each potential driving variable because relationships between assumed
431 drivers are not necessarily causally related to the response. Bistinas et al (2014) showed, for example, that burnt area
432 increases as net primary productivity (NPP) increases and decreases as fuel moisture increases. Given that increasing
433 precipitation increases both NPP and fuel moisture this results in a peak in fire at intermediate levels of NPP and

434 precipitation. Population density is also strongly influenced by NPP (i.e. the capacity of the land to provide
435 ecosystem services) and thus the apparent unimodal relationship between burnt area and population density (see e.g.
436 Aldersley et al., 2011) is an artefact of the relationship between population density and NPP. However, when
437 appropriate techniques are used to isolate causal relationships, the ability to reproduce these relationships establishes
438 that the model is simulating the correct response for the right reason. Thus, process-evaluation goes a step beyond
439 benchmarking and assesses the realism of model behaviour rather than simply model response, a very necessary step
440 in establishing confidence in the ability of a model to perform well under substantially different conditions from
441 present.

442 One goal of FireMIP is to develop modelling capacity to predict the trajectory of fire-regime changes in response to
443 projected future climate and land-use changes. It has been repeatedly shown that vegetation and carbon-cycle models
444 that reproduce modern conditions equally well produce very different responses to future climate change (e.g. Sitch
445 et al., 2008; Friedlingstein et al., 2014). The interval for which we have direct observations is short and does not
446 encompass the range of climate variability expected for the next century. Benchmarking using modern observations
447 does not provide an assessment of whether model performance is likely to be realistic under radically different
448 climate conditions. The climate-modelling community use records of the pre-observational era to assess how well
449 models simulate climates significantly different from the present (Braconnot et al., 2012; Flato et al., 2014; Harrison
450 et al., 2014; Schmidt et al., 2014; Harrison et al., 2015). FireMIP will extend this approach to the evaluation of fire-
451 enabled vegetation models, building on the work of Brücher et al. (2014). Many data sources provide information
452 about past fire regimes. Charcoal records from lake and mire sediments provide information about local changes in
453 fire regimes through time (Power et al., 2010) and have been used to document spatially coherent changes in biomass
454 burnt (Daniau et al., 2012; Marlon et al., 2008; Marlon et al., 2013). Hemispherically-integrated records of
455 vegetation and fire changes can be obtained from records of trace gases (e.g. carbon monoxide), and markers of
456 terrestrial productivity and biomass burning (e.g. carbonyl sulphide, ammonium ion, black carbon, levoglucosan,
457 vanillic acid) in polar ice cores (e.g. Wang et al., 2010; Kawamura et al., 2012; Wang et al., 2012; Asaf et al., 2013;
458 Petrenko et al., 2013; Zennaro et al., 2014). Both hemispherically-integrated and spatially-explicit records of past
459 changes in fire will be used for model evaluation in FireMIP.

460

461 **6. Conclusions and Next Steps**

462 Fire has profound impacts on many aspects of the Earth system. We therefore need to be able to predict how fire
463 regimes will change in the future. Projections based on statistical relationships are not adequate for projections of
464 longer-term changes in fire regimes because they neglect potential changes in the interactions between climate,
465 vegetation and fire. While mechanistic modelling of the coupled vegetation-fire system should provide a way
466 forward, it is still necessary to demonstrate that they are sufficiently mature to provide reliable projections. This is a
467 major goal of the FireMIP initiative.

468 There has been enormous progress in global fire modelling over the past 10–15 years. Knowledge about the drivers
469 of fire has improved, and understanding of fire feedbacks to climate and the response of vegetation is improving.
470 Global fire models have developed from simulating burnt area only to representing most of the key aspects of the fire
471 regime. However, there are large and to some extent arbitrary differences in the representation of key processes in
472 process-based fire models and little is known about the consequences for model performance. While the
473 development of fire models has been towards increasing complexity, it is still not clear whether a global fire model
474 *needs* to represent ignition, spread, and extinction explicitly or whether it would be sufficient to just represent the
475 emergent properties of these processes (burnt area, or fire size, season, intensity, and fire number) in models with
476 fewer uncertain parameters. The answer to this question may depend on whether the goal is to characterize the role
477 of fire in the climate system or to understand the interaction between fire and vegetation. Burnt area and biomass are
478 the key outputs needed to quantify fire frequency and carbon, aerosol and reactive trace gas emissions and changes in
479 albedo required by climate and/or atmospheric chemistry models. Empirical models may be adequate to estimate
480 such changes. Other aspects of the fire regime are important factors with respect to the vegetation response to fire
481 and thus may require a more explicit simulation of e.g. fire intensity and crown fires. FireMIP will address these
482 issues by systematically evaluating the performance of models that use different approaches and have different levels
483 of complexity in the treatment of processes, in order to establish whether there are aspects of simulating modern
484 and/or future fire regimes that require complex models. Systematic evaluation will also help guide future
485 development of individual models and potentially the further development of vegetation-fire models in general.

486 FireMIP is a non-funded initiative of the fire-modelling community. Participation in the development of
487 benchmarking data sets and analytical tools, as well as in the running and analysis of the model experiments, is open
488 to all fire scientists. We hope that will maximise exchange of information between modelling groups and facilitate
489 rapid progress in this area of science.

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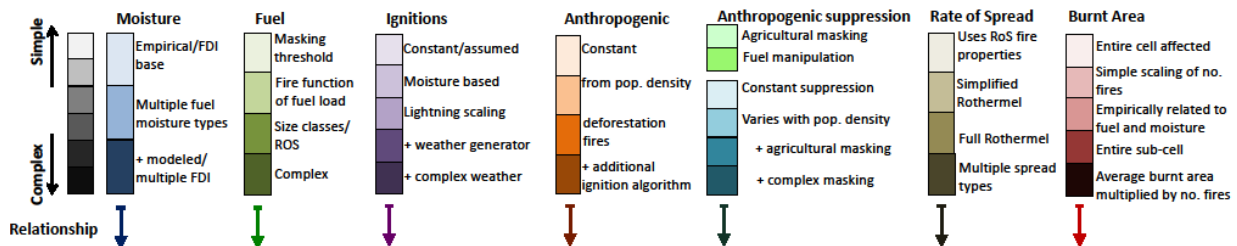
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850 **Tables**

851 Table 1: Representation of fire processes in fire-enabled DGVM. The intensity of the colour represents the
852 complexity of the description of the process. Shades of grey describe the complexity of the model as a whole: light
853 grey being the simplest; black being the most complex. Blue represents the complexity of description of moisture
854 control on fire susceptibility ranging from: simple statistical relationships/ fire danger indices (FDIs) of fuel as a
855 whole (light blue); description of moisture in multiple fuel size classes; fully modelled or specifically chosen FDIs
856 for specific fuel moisture (dark blue). Green represents the complexity of fuel controlled fire susceptibility: simple
857 masking at a specified fuel threshold (light green); fuel structure effects on ignition probability and rate of spread;
858 and complex modelling of fuel bulk density (dark green). Purple shows complexity of natural ignition schemes: no
859 specified/ assumed ignitions (white); constant ignition source (light purple); simple relationship with fuel moisture;
860 prescribed ignitions - normally through lightning climatology inputs; prescribed lightning with additional scaling for
861 e.g. latitude dependent cloud-ground lightning (CG); daily distributed lightning via a weather generator; and with
862 additional complex ignition simulation (dark purple). Orange represents anthropogenic ignitions: none (white);
863 constant background ignition source (light orange); human population density varying ignitions based on a 'human
864 ignition potential' (HIP) and/or gross domestic product (GDP); inclusion of additional, complex human ignition
865 schemes such as pre-historic human behaviour (dark orange). Cyan and lime green represent inclusion of human
866 ignitions suppression and agriculture: none (white); constant suppression (light cyan); increasing suppression with
867 population (medium cyan); simple agricultural masking of fire (light lime green); fuel load manipulation from
868 agriculture (lime green); a mix of agricultural and ignition suppression (dark cyan). Italicize text under 'human
869 ignitions' and 'human suppression' denote models where the combined influence of human ignitions and suppression
870 result in a unimodal description of fire relative to population density. Brown shows complexity of the calculation of
871 fire sizes, typically through a rate of spread model (RoS): None (white); simplified RoS model to obtain fire
872 properties (light brown); simplified RoS to model individual fires; full Rothermel RoS; multiple RoS models (dark
873 brown). Red show complexity of the calculation of the overall burnt area: the entire cell is affected by fire (light red);
874 constant scaling of the number of fires to burnt area depending on vegetation type; scaling based on moisture and
875 fuel type; entirety of a sub-cell affected; and scaling of number of fires by fire size calculated by RoS model. Arrows
876 demonstrate the exchange of components between models. Arrows start in the model containing the original process
877 description.

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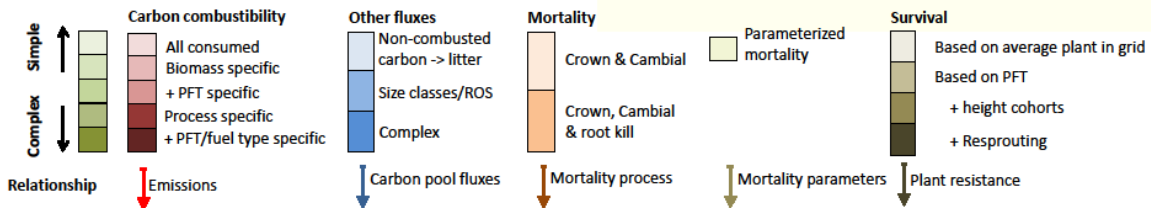
| Model | Fuel Moisture | Fuel Load | Fire starts from lightning Ignitions | Anthropogenic Ignitions | Anthropogenic Suppression | Rate of Spread (ROS) | Burnt Area | |
|-----------------------|---|--|---|---|---|---|--|--|
| CASA/GFED | None. Fire translated to burnt area from satellite fire counts. | | | | | | Proportional to no. of fires, with more burnt area to fire in sparse vegetation (van der Werf, 2003) | |
| GLOBFIRM | Moisture of extinction, above which fire does not occur (Thonicke et al. 2001) Increased fire occurrence with decrease moisture (Thonicke et al. 2001) | Discontinuity fuel load threshold, below which fire does not occur (Thonicke et al. 2001) Reduced fuel from grazing (Krinner et al. 2005) | | | Suppression from Reduced fuel from grazing (Krinner et al. 2005) | | Increases exponentially with annual (Thonicke et al. 2001) or monthly (Krinner et al. 2005) summed fire occurrence. | |
| SIMFIRE | Maximum possible burnt area a function of FDI (Knorr et al. 2014) | Maximum possible fire as a function of fAPAR as proxy for fuel load (Knorr et al. 2014) | | | Increases exponentially with population (Knorr et al. 2014; Knorr et al. 2016) | | Multiplication of maximum fire functions for fuel, moisture & suppression (Knorr et al. 2014). | |
| P&S | Function of VPD (proxy for ambient atmospheric conditions) (Pechony & Shindell, 2009) | Fire scaled by vegetation density based on LAI (Pechony & Shindell, 2009) | Observed lightning flash count, scaled for cloud-to-ground (CG) ratio (Pechony & Shindell, 2009) | | Increases with population (Pechony & Shindell, 2009) | | | |
| Rate of Spread Models | | | | | | | | |
| MC-FIRE | Calculated from fuel size classes and live fuel component (Lenihan et al. 1998) Effects fire start (Lenihan et al. 1998) and RoS (Rothermel 1972) | Size ratios effects RoS (Rothermel 1972) | Fire only occur when 1000hr hour fuel content drops below threshold and rate of spread is above a threshold (Lenihan et al. 1998) | | | Capped burnt area for low intensity or slow spread rate fires in populated areas (Rogers et al. 2011) | Fire behaviour scaled by fuel load and moisture based Fire Danger Index (FDI) based rate of spread for ground (Rothermel 1972; Lenihan et al. 1998) and crown (Van Wanger, 1993) fires | Entire grid cell affected by fire during fire occurrence (Lenihan et al. 1998) |
| CTEM | Represented by soil moisture (Arora & Boer 2005; Melton & Arora 2016) | Linear increase fire occurrence between discontinuity and saturated fuel thresholds (Arora & Boer 2005) | Probability of fire occurrence a multiple of probabilities from fuel, moisture & ignitions (Arora & Boer 2005) Latitude dependant CG scaling for lightning (Kloster et al. 2012) | Deforestation fire (Kloster et al. 2012) | | No. of days fire burnt suppressed at higher population density (Melton & Arora 2016) | No FDI (Arora & Boer 2005) Affected by differing fuel types (Arora & Boer 2005) | Maximum of 1 fire per sub-grid cell unit. Overall burnt area in grid cell is multiplication of probability of fire by number of units by average fire size per unit (Arora & Boer 2005; Melton & Arora 2016) |
| Li et al. | Represented by soil moisture & relative humidity (Li et al. 2012) | | Ignitions & limitation from fuel and moisture (Li et al., 2012) | Deforestation & degradation fires in tropical closed forests (Li et al. 2013) | | Suppression increases with GDP (Li et al. 2013) | | |
| REGFIRM | Fire occurrence from moisture based FDI (Venesky et al. 2002) | | Number of fires instead of probability of fire (Venesky et al. 2002) | 'Human ignition potential' (HIP) (Venesky et al. 2002) | | Variable wind speed affects rate of spread and fire oval shape (Venesky et al. 2002) | Number of fire multiplied by average area burnt per fire (Venesky et al. 2002) | |
| SPITFIRE/ LPX/Lmfire | | | CG distributed between wet and dry lightning (Prentice et al. 2011) "Storm days" (Kelley et al. 2014) Inter-annual lightning from atmospheric conditions (Pfeiffer et al. 2013) | HIP varying with socio-economic development (Thonicke et al. 2010) Different human-fire relation for hunter-gatherers, pastoralists and farmers (Pfeiffer et al. 2013) | Cropland fire masking (Thonicke et al. 2010) Additional ignition suppression term (Thonicke et al. 2010) Explicit cropland fragmentation algorithm (Pfeiffer et al. 2013) | Multi-day fires (Pfeiffer et al. 2013) Different RoS for different vegetation type (Pfeiffer et al. 2013) Terrain impediment to spread (Pfeiffer et al. 2013) Reduced rate of spread at high wind speeds (Lasslop et al. 2014) | | |



880 Table 2: Representation of the impacts of fire in fire-enabled DGVMs. Intensity of colour indicates the complexity of
881 the description of the component. Green indicates complexity of the representation of fire impacts. Red describes the
882 complexity of the description of atmospheric fluxes from fire: flux is equivalent to all consumed biomass (light red);
883 consumption based on biomass specific combustion parameters; inclusion of PFT combustion parameters; process
884 based; biomass/PFT parameterized process-based (dark red). Blue represents the complexity of carbon fluxes to
885 other carbon pools: no additional fluxes (white); non-combusted dead carbon flux (light blue); carbon fluxes based
886 on fire spread properties; fire-adapted vegetation carbon retention (dark blue). Orange represents complexity of
887 simulated mortality processes: parameterized mortality (yellow); mortality from crown and cambial damage (light
888 orange); additional root damage mortality (dark orange). Brown represents complexity of plant adaptation to fire
889 when mortality processes are included: mortality based on a grid cell's `average plant' properties of fire resistant
890 traits (light brown); PFT based average traits; inclusion and height cohorts; inclusion of dynamic/complex adaptations
891 such as resprouting (RS) (dark brown). Arrows demonstrate the exchange of components between models, starting
892 in the model containing the original description.

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| Model (main citation) | Carbon Emission | Other carbon feedbacks | Plant mortality type | Plant resistance |
|-------------------------|---|--|--|--|
| CASA/GFED | Combustibility dependent on fuel type (leaf, stem and root, dead) and life-form (wood or grass) (Potter & Klooster, 1999) | Killed but not consumed plant material enters litter pool. (Potter & Klooster, 1999) | Fraction of woody plants killed dependent on % woody to grass cover. In high wood cover, most trees are killed. Low tree and high grass cover, few trees are killed. (Potter & Klooster, 1999) | All above-ground grass biomass killed; 90% belowground grass biomass survive (Potter & Klooster, 1999) |
| GLOBFIRM | All aboveground litter & living biomass consumed and released to atmosphere (Sitch et al. 2003) | Includes 'Black carbon' (i.e. inert carbon for 1,000s years). (Krimmer et al. 2005) | PFT based mortality parameter (Thonicke et al. 2001) | |
| Rate of Spread Models | | | | |
| MC-FIRE | All canopy carbon is released to atmosphere during crown fires (Lenihan et al. 1998) | Scorched woodmass enters litter pool. (Lenihan et al. 1998) | Crown scorch mortality based on 'lethal scorch height' of fire and canopy height (Peterson & Ryan, 2009) | Complete mortality in crown fires (Lenihan et al. 1998) |
| | Scorched canopy leafmass from high ground fires released to atmosphere (Lenihan et al. 1998) | | Cambial mortality based on fire residence time and plant bark thickness (Lenihan et al. 1998) | Crown/Cambial damage mortality from ground fire follow Peterson & Ryan (1986). All vegetation represented by average crown height and bark thickness, based on simple allometric equations (Lenihan et al. 1998) |
| | Atmospheric release of consumed dead biomass is calculated from fuel amount and fuel moisture (Lenihan et al. 1998) | | Root damage (Lenihan et al. 1998) | 'Depth of lethal heating' for roots based on Steward et al. 1990 |
| CTEM | PFT based combustion parameters for different woody components (Arora & Boer 2005) | | PFT specific parameters relating carbon consumption to plant mortality (Arora & Boer 2005) or PFT-specific mortality factor (Li et al. 2012) | |
| REGFIRM | | | | |
| SPITFIRE/ LPX/Lmfire | Fuel load combustion split into PFTs (Thonicke et al. 2010). | Carbon retained by surviving resprouting PFTs (Kelley et al. 2014) | | Scorch height and bark thickness calculated per PFT, using PFT-specific allometric parameters (Thonicke et al. 2010). |
| | | | | Within PFT height cohorts affect bark thickness and height-based survival (Pfeiffer et al. 2013) |
| | | | | Within PFT bark thickness competition (Kelley et al. 2014) |
| | | | | Resprouting PFTs that resprout from reduced above-ground biomass rather than killed (Kelley et al. 2014) |

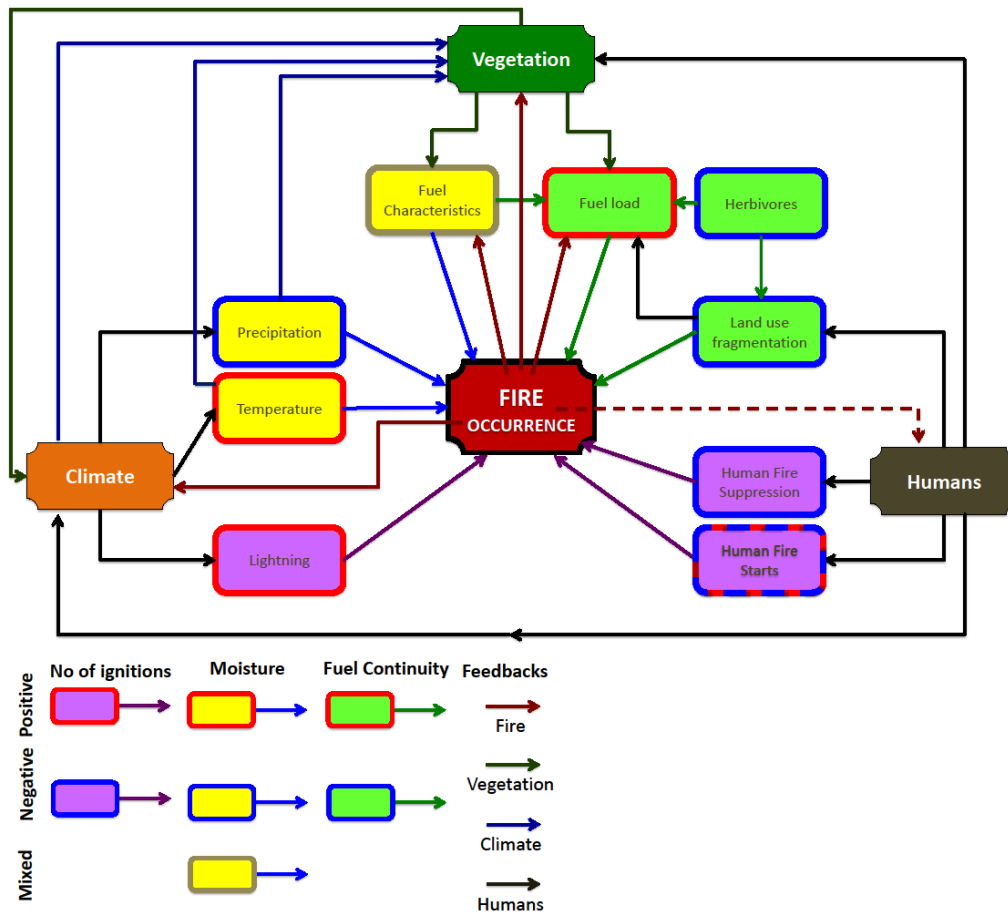


895 Table 3: Overview of the burnt area (BA) products used for the intercomparison and their characteristics.

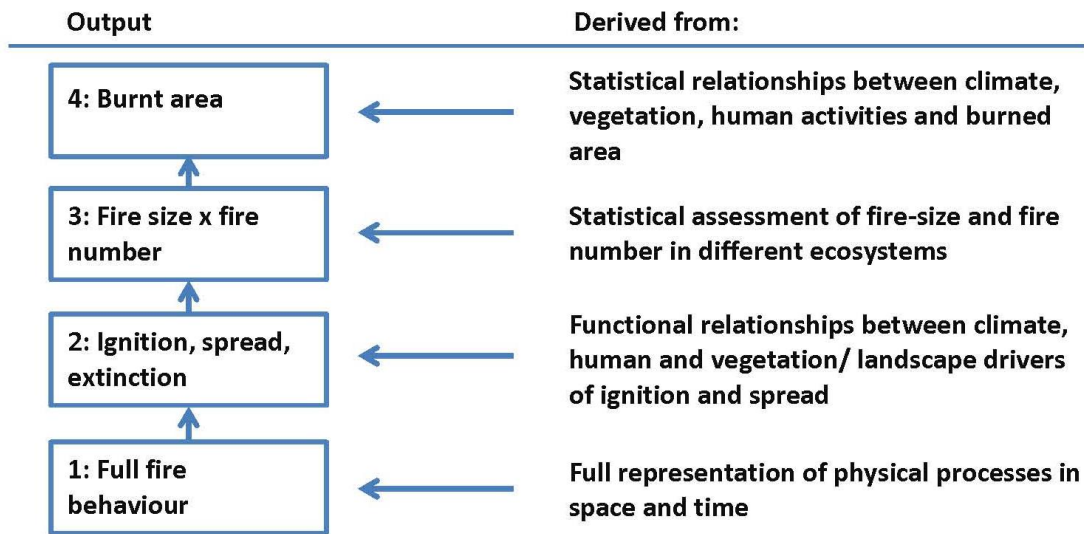
| | GFED4 | L3JRC | MCD45A1 | Fire_cci |
|---------------------|------------------------|----------------------|-------------------|----------------------------------|
| Temporal Resolution | Daily (2001 - present) | Burn date (day) | Burn date (day) | Burn date (day) |
| Spatial Resolution | 0.25° | 1km | 500m | ±300m |
| Period covered | 1997-present | 2001-2006 | 2001-present | 2006-2008 |
| Mean BA (Mha) | 346.8 | 398.9 | 360.4 | 368.3 |
| Reference | Giglio et al. (2013) | Tansey et al. (2008) | Roy et al. (2008) | Alonso-Canas and Chuvieco (2015) |

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902 Fig. 1: Summary of the interactions between the controls on fire occurrence on coarse scales. Green filled boxes
 903 show controls influencing fuel; blue influencing moisture; and purple influencing ignitions. Red outlined box
 904 indicates positive influence on fire; blue a negative influence, and brown a mixed response. Brown arrows indicate
 905 interactions between people and other controls; dark green between vegetation and other controls; dark blue from
 906 climate; black arrows show direct effects and red arrows show feedback from fire. The arrow from fragmentation to
 907 fuel load indicates its effect on fuel continuity.

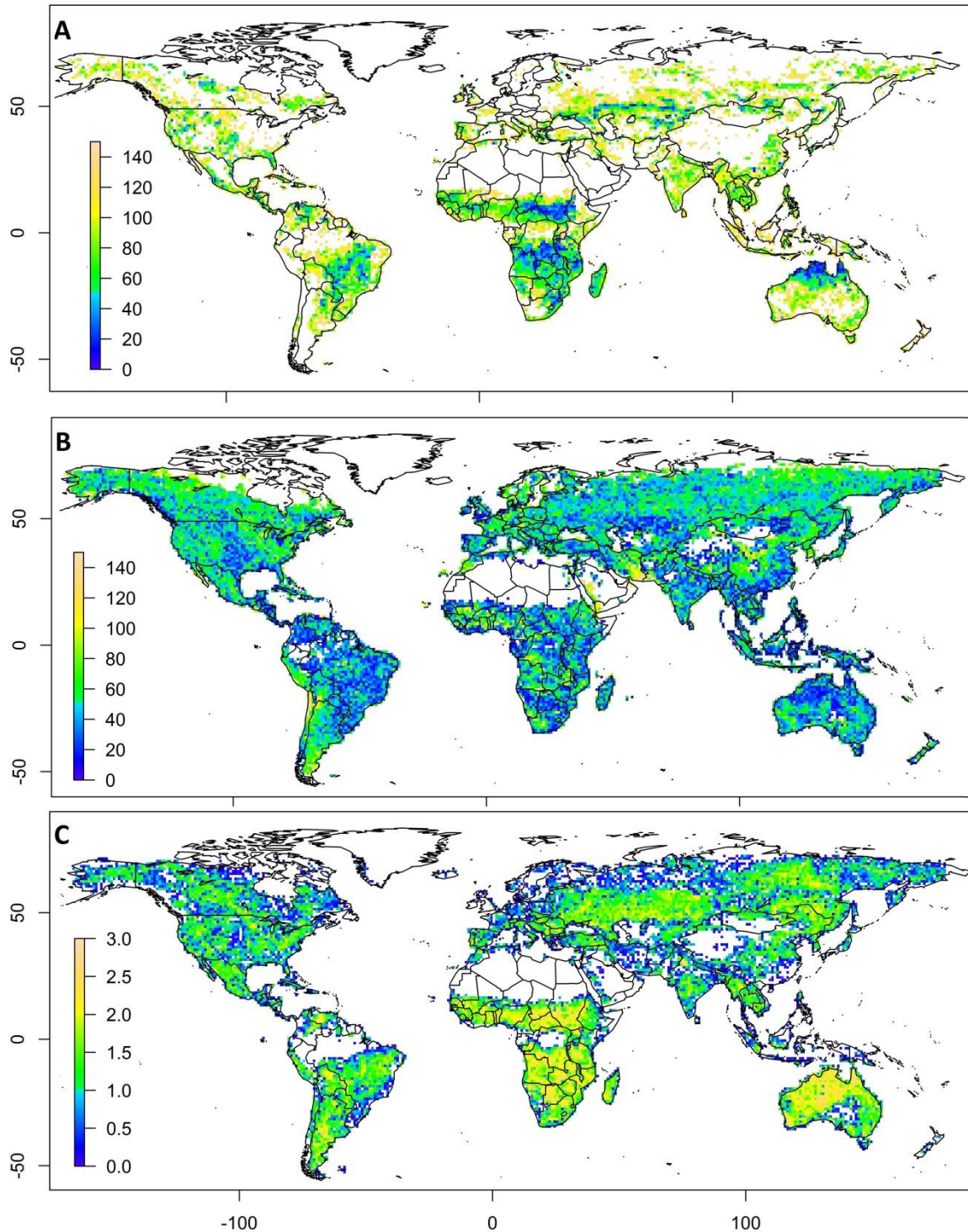


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911 Fig. 2: Summarising the levels of model complexity required to derive different aspects of global fire regimes.
 912 Outputs from models functioning at level 1 can be used to derive higher-level outputs, but it is not possible to work
 913 backwards (i.e. empirical relationships between burnt area and environmental drivers will not allow for assessment
 914 of changes in fire number and fire size). Currently there are fire routines in global DGVMs that represent all of these
 915 levels of complexity (see Table 1).

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920 Fig. 3: Coefficient of variation (%) characterizing a) inter-product variability in mean burnt area; b) the inter product
 921 variability of the interannual variability in burned area; and c) the interproduct variability of the slope of temporal
 922 trends (2001-2007). Plots a) and b) are based on all four burnt area products (GFED4, MCD45, L3JRC, Fire_cci)
 923 whereas plot c) is based on three products and does not include the MERIS data because it is currently only available
 924 for 3 years, see Table 3.