

1 **Tree-grass phenology information improves light use** 2 **efficiency modelling of gross primary productivity for an** 3 **Australian tropical savanna**

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14 15 **Abstract**

16 The coexistence of trees and grasses in savanna ecosystems results in marked phenological dynamics
17 that vary spatially and temporally with climate. Australian savannas comprise a complex variety of
18 life forms and phenologies, from evergreen trees to annual/perennial grasses, producing a boom-bust
19 seasonal pattern of productivity that follows the wet-dry seasonal rainfall cycle. As the climate
20 changes into the 21st Century, modification to rainfall and temperature regimes in savannas is highly
21 likely. There is a need to link phenology cycles of different species with productivity to understand
22 how the tree-grass relationship may shift in response to climate change. This study investigated the
23 relationship between productivity and phenology for trees and grasses in an Australian tropical
24 savanna. Productivity, estimated from overstory (tree) and understory (grass) eddy covariance flux
25 tower estimates of gross primary productivity (GPP), was compared against two years of repeat time-
26 lapse digital photography (phenocams). We explored the phenology-productivity relationship at the
27 ecosystem scale using moderate resolution imaging spectroradiometer (MODIS) vegetation indices
28 and flux tower GPP. These data were obtained from the Howard Springs OzFlux/Fluxnet site (AU-
29 How) in northern Australia. Two greenness indices were calculated from the phenocam images; the
30 green chromatic coordinate (GCC) and excess green index (ExG). These indices captured the
31 temporal dynamics of the understory (grass) and overstory (trees) phenology, and were well
32 correlated with tower GPP for understory ($r^2 = 0.65$ to 0.72) and but less so for the overstory ($r^2 =$
33 0.14 to 0.23). The MODIS enhanced vegetation index (EVI) correlated well with GPP at the

1 ecosystem scale ($r^2 = 0.70$). Lastly, we used GCC and EVI to parameterise a light use efficiency (LUE)
2 model and found it to improve the estimates of GPP for the overstory, understory and ecosystem. We
3 conclude that phenology is an important parameter to consider in estimating GPP from LUE models
4 in savannas and that phenocams can provide important insights into the phenological variability of
5 trees and grasses.

6 **Key Words**

7 Eddy covariance, phenocam, leaf area index, photosynthetically active radiation, light use efficiency,
8 MODIS, OzFlux

9 **1 Introduction**

10 Savanna ecosystems are defined by the coexistence of trees and grasses, and have evolved to
11 dominate one fifth of the terrestrial land surface (Scholes and Archer, 1997; Grace et al., 2006). In
12 tropical savanna, trees utilise the C_3 photosynthetic pathway, whereas the grasses more commonly use
13 the C_4 pathway, being more efficient at taking up carbon in hot environments with limited water and
14 nutrient availability (Sage, 2004; Osborne and Beerling, 2006). Savannas are typically found in
15 wet/dry climates that over time have shaped the tree-grass structure and phenology seen today. Fire
16 also plays a role in shaping savanna phenology and structure, with recurrences often every 1-5 years
17 (Hoffmann et al., 2012; Beringer et al., 2015). Fire consumes cured grass biomass in the dry season
18 and suppresses growth of juvenile overstory species, resulting in a range of plant phenology responses
19 to deal with it (Bond, 2008; Murphy et al., 2010; Werner and Franklin, 2010). Herbivory, drought and
20 land-use change are additional disturbances that commonly occur in savannas (Hutley and Beringer,
21 2011). These complex interactions are believed to be the primary reason for the co-dominance of trees
22 and grasses in savanna ecosystems, as well as for the phenological variability displayed (Bond et al.,
23 2003; Van Langevelde et al., 2003; Bond, 2008; Hanan and Lehmann, 2010; Lehmann et al., 2014).

24 The climate and disturbance regime in savannas plays an important role in shaping plant phenology.
25 C_4 savanna grasses typically follow a boom-bust phenological cycle, where they rapidly produce
26 biomass in the wet season and display an annual or perennial die-back phenology in the dry season
27 (Bond, 2008; Ratnam et al., 2011). C_3 savanna trees, in contrast, can range from having a fully
28 deciduous phenology to remaining evergreen throughout the dry season. In Australian savannas, the
29 understory is dominated by C_4 annual grasses with a small portion represented by juvenile overstory
30 species (Werner and Franklin, 2010; Werner and Prior, 2013) and perennial grasses. Evergreen
31 eucalypt species make up the bulk (~ 80 %) of the overstory in Australian savannas (Hutley et al.,
32 2011), however, semi-, brevi- and fully deciduous species are found to a lesser degree throughout
33 (Williams et al., 1997) and contribute to the seasonal fluctuation of canopy leaf area (O'Grady et al.,
34 2000; Whitley et al., 2011). Tree-grass ratios are driven by annual rainfall, and in Australia there is a

1 strong rainfall gradient from the coast inland (Rogers and Beringer, 2016), resulting in northern high
2 rainfall (mesic) regions supporting higher tree-grass ratios and drier southern (xeric) regions
3 supporting higher grass-tree ratios (Hutley et al., 2011;Ma et al., 2013).

4 The monitoring of savanna phenology can inform how savannas might respond to climate change. At
5 the regional scale, the timing of phenological events varies widely for savannas due to variability in
6 the occurrence and duration of rainfall events (Ma et al., 2013). Phenology, in turn, influences the
7 productivity and growth (carbon cycle) of an ecosystem, as well as its water and nutrient cycles
8 (Noormets, 2009;Richardson et al., 2013). The savanna region of Australia is projected to experience
9 warming and increased rainfall (variability and amount) under climate change (Reisinger et al., 2014),
10 which is likely to impact savanna phenology and its interactions with the carbon, nutrient and water
11 cycles (Kanniah et al., 2010;Scheiter et al., 2015). There is a need for better understanding of what
12 governs savanna phenology in order to predict how it may be affected by climate change (Beringer et
13 al., 2016a).

14 Due to the large extent and spatial variation of savannas, satellite remote sensing provides a useful
15 tool (Broich et al., 2015) for examining the interactions of savanna phenology with productivity.
16 Vegetation indices such as the normalised difference vegetation index (NDVI) (Tucker, 1979) and
17 enhanced vegetation index (EVI) (Huete et al., 2002) provide valuable measures of savanna
18 phenological variability from the landscape to global scale (Ma et al., 2013;Ma et al., 2014). Likewise,
19 the MODIS gross primary productivity (GPP) product (MOD17 A2/A3, Running and Zhao, 2015) is a
20 widely-used means of estimating large scale savanna productivity (Grace et al., 2006;Ryu et al., 2011),
21 but has been shown to underestimate savanna GPP, particularly during the transition between the wet
22 and dry seasons (Kanniah et al., 2009;Whitley et al., 2011;Ma et al., 2014). The remoteness of
23 satellite sensors from the ecosystems they measure, along with the effects of cloud contamination on
24 daily data collection, and the need to aggregate imagery spatially and temporally for contiguous
25 scenes, results in coarse temporal resolution (i.e. 8 or 16 day) satellite data products that can be
26 problematic for identifying change in seasonally cloudy tropical environments (Eberhardt et al., 2016)
27 where rapid (i.e. 1-2 weeks) phenological change is common (Williams et al., 1997;Moore et al.,
28 2016b).

29 A novel approach to alleviate some of the limitations of satellite remote sensing is to use *in situ*
30 automated time-lapse cameras (phenocams) that can collect high temporal resolution (hourly to daily)
31 images of vegetation within and above an ecosystem (Richardson et al., 2007;Hufkens et al.,
32 2012;Sonnentag et al., 2012;Moore et al., 2016b). The proximity of these cameras to ecosystem
33 vegetation allows them to capture important information about vegetation cover change, particularly
34 that of leaf emergence and senescence (Richardson et al., 2007;Richardson et al., 2009a;Wingate et
35 al., 2015) that can be linked with measures of ecosystem GPP (Toomey et al., 2015;Richardson et al.,

1 2010;Filippa et al., 2016). Phenocam data have also been used for parameterising light use efficiency
2 (LUE) models (in a similar way to MODIS GPP) that describe ecosystem GPP using absorbed
3 photosynthetically active radiation (APAR) and plant LUE (Migliavacca et al., 2011).

4 In this study, we aim to contribute a detailed assessment of phenological change, and its relationship
5 with productivity, for a mesic tropical savanna in northern Australia over 2 years. Our objectives are
6 to (i) determine the utility of phenocams for identifying change in overstory and understory vegetation
7 greenness; (ii) quantify the relationship between savanna overstory and understory phenology and
8 productivity on seasonal and annual timescales; (iii) test if phenocam indices can be used as a proxy
9 for improvement of a LUE model that is widely used to estimate GPP; and (iv) test the applicability of
10 MODIS EVI for improving estimates of ecosystem scale GPP. To do this we utilise one of the first
11 phenocam datasets obtained in Australian ecosystems, along with MODIS EVI, and couple them with
12 previously collected ecosystem, overstory and understory eddy covariance data (Moore et al., 2016a)
13 to tease apart the tree and grass phenology-productivity relationship in Australian savanna.

14 **2 Methods**

15 **2.1 Site Description**

16 This study was conducted at the Howard Springs OzFlux (www.ozflux.org.au/) and Fluxnet (AU-
17 How) site (Beringer et al., 2016a) near Darwin in the Northern Territory, Australia. A record of
18 carbon, water and energy flux, as well as meteorological and soil measurements, was first established
19 at Howard Springs in 1997 (Eamus et al., 2001). As such, many detailed site descriptions exist
20 (Beringer et al., 2007;Hutley et al., 2013;Beringer et al., 2015;Moore et al., 2016a). In brief, annual
21 rainfall at Howard Springs is 1732 mm (\pm 44 SE) mm, (Australian Bureau of Meteorology (BoM),
22 station ID: 014015, www.bom.gov.au/), of which 90-95 % falls within the wet season months of
23 October to April. As such, we defined the wet season as a 6 month period from October 15th to April
24 15th and the dry season as April 16th to October 14th, based on the work of Cook and Heerdegen
25 (2001). Mean daily maximum air temperature varies annually between 30.6 to 33.3 °C and mean daily
26 minimum air temperature ranges from 19.3 to 25.3 °C (Australian Bureau of Meteorology,
27 www.bom.gov.au/). Howard Springs is a mesic savanna as it receives >1200 mm rainfall annually
28 (Hutley et al., 2011) and is classified as ‘open forest savanna’ based on its canopy cover fraction (50-
29 60 %) after Specht (1972). Soils are mostly red Kandosols (Isbell, 1996) that are sandy-loamy, well
30 weathered and nutrient poor.

31 Vegetation consists of a C₃ woody overstory dominated by evergreen *Eucalyptus miniata* (Darwin
32 woollybutt) and *E. tetradonta* (Darwin stringybark). A smaller portion of the woody overstory is
33 made up of semi-, brevi- and fully deciduous species such as *Erythrophleum chlorostachys* (Ironwood)
34 and *Terminalia ferdinandiana* (Kakadu plum) (Williams et al., 1997;Hutley et al., 2011). Mean

1 canopy height is 18 m (Hutley et al., 2011). The understory is dominated by the annual C₄ grass
2 *Sorghum intrans* (spear grass) and perennial C₄ grasses *Heteropogon triticeous* and *S. plumosum*.
3 Sharing the understory with the grasses are saplings (juveniles) of overstory species, the shrub
4 *Buchanania obovata* and the cycad *Cycas armstrongii*. Due to the frequent occurrence of fire in
5 Australian savanna (Beringer et al., 2015), control burning was performed at the beginning of each
6 dry season to protect the monitoring equipment at the site.

7 **2.2 Productivity measurements**

8 To estimate productivity from the savanna ecosystem and partition it into tree (overstory) and grass
9 (understory) GPP, we used the eddy covariance technique (Baldocchi et al., 2001) as detailed for
10 Howard Springs by Moore et al. (2016a). Two eddy covariance towers were in operation at Howard
11 Springs to measure the fluxes of carbon, water and energy from both the understory (within tree
12 canopy tower at 5 m) and the ecosystem (above tree canopy tower at 23 m) from the 12th December
13 2012 through to 14th October 2014. Overstory fluxes are simply the difference between ecosystem and
14 understory fluxes, which represent the above ground tree fluxes. Instrumentation, validation of the
15 understory tower, data quality assurance and quality control (QA/QC) and flux partitioning
16 information is also provided in Moore et al. (2016a), so a summary is provided here.

17 Core eddy covariance instruments on each tower consisted of a 3D sonic anemometer (CSAT3,
18 Campbell Scientific, Logan UT) and an infra-red gas analyser (LI-7500, Li-COR Biosciences, Lincoln,
19 NE). These instruments sampled at a rate of 10 Hz and provided 30-min flux averages. Soil heat flux
20 (HFT3, Campbell Scientific, Logan, UT) and net/short/long wave radiation components were also
21 recorded on the ecosystem tower (CNR4, Kipp and Zonen, Delft, NL). The raw 30-minute data were
22 QA/QC'd to level 3 standard using the OzFluxQC (v2.9.4) python scripts. Energy balance closure
23 analysis of the ecosystem tower, based on daily data (Silva et al., 2011), gave a slope of 0.89 and an r²
24 of 0.92. The understory tower primarily recorded vertical transfer during turbulent conditions, which
25 was validated via co-spectral analysis (Moore et al., 2016a) that followed idealised curves for
26 vegetated canopies (Kaimal and Finnigan, 1994). Level 3 data were then gap filled and used to
27 partition net ecosystem exchange (NEE) into respiration and GPP using the Dynamic INtegrated Gap
28 filling and partitioning for OzFlux (DINGO, (Beringer et al., 2016b)) package. This package applied a
29 u* filter and artificial neural network approach, with soil temperature, air temperature and EVI as the
30 main model drivers, to determine respiration, assuming all night-time NEE was respiration. This was
31 extrapolated to the daytime and GPP was calculated as the difference between NEE and respiration
32 (Beringer et al., 2016b).

33 **2.3 Phenology and light use efficiency (LUE) measurements**

34 Alongside tower estimates of tree and grass productivity (12th December 2012 to 14th October 2014),
35 we recorded incident, reflected and absorbed PAR, and vegetation cover change. While the understory

1 is largely homogenous in species distribution at the flux tower footprint scale (i.e. >50 m), variation
2 does exist at the smaller scale (i.e. < 5 m) due to its vegetation composition. To obtain a rigorous time
3 series, spatial replicate measurements of vegetation cover change and PAR variability were recorded
4 at five locations (on 5 tall mini towers) within a 50 m pentagon shape of the main ecosystem flux
5 tower (Fig. 1).

6 PAR components for the overstory and understory were measured from PAR sensors on each of the
7 mini towers (SQ-Series, Apogee, Logan, UT). A data logger (CR800, Campbell Scientific, Logan UT)
8 and multiplexor (AM25T, Campbell Scientific, Logan, UT) were used to collect and store data and to
9 operate the phenocams. The systems were powered using a 20 W solar panel, 12 V regulator and 12 V
10 gel cell battery. To provide a complete accounting of savanna PAR, two additional sensors (LI-190
11 Quantum Series, Li-COR Biosciences, Lincoln, NE) were installed on the 23 m flux tower for
12 collection of incoming PAR and outgoing PAR reflected from the savanna ecosystem.

13 Changes in savanna overstory and understory vegetation greenness were assessed using consumer-
14 grade point-and-shoot cameras (Canon Powershot A810). Each mini tower supported two cameras,
15 one collecting upward facing images of the tree canopy (FOV ~ 8 x 5 m) and one collecting
16 downward facing images of the understory (FOV ~ 4 x 2 m, 10 cameras total). The cameras' settings
17 included automatic exposure in aperture priority mode, with a low f/stop (focal point) value of 2.8 to
18 ensure the entire image was used to respond to ambient light levels (Richardson et al., 2007;Ryu et al.,
19 2012;Sonntag et al., 2012). Automatic white balance was also used as we did not have a grey
20 reference panel to correct for white balance manually. Images were stored in a compressed JPEG file
21 format and each camera was housed in a make-shift waterproof case (Fig. 2, a & d).

22 Following the concept of Ryu et al. (2012), power was delivered to the cameras through wires
23 soldered to the battery terminals and a brief pulse delivered to wires soldered to the camera 'on-button'
24 allowed them to turn on when prompted. The Canon Hack Development Kit
25 (<http://chdk.wikia.com/wiki/CHDK>) was used to automate image capture when the camera was turned
26 on, which was administered via a u-Basic script saved on the memory card. Each mini tower logger
27 was programmed to operate the cameras twice daily, once at 11:30 ACST (~ MODIS Terra overpass)
28 and once at 13:00 ACST (~ solar noon). Each camera was installed at an angle of 57.5 ° from zenith,
29 to minimise the effects of leaf inclination angle when calculating LAI (Weiss et al., 2004;Baret et al.,
30 2010).

31 **2.4 Phenocam image processing**

32 Phenocam images were visually checked for field of view (FOV) shifts and major obstructions (i.e.
33 water in image) as a first step in the image QA/QC process. Images with obstructions were removed,
34 which accounted for between 3 - 13 % of images for each camera. However, three out of ten cameras
35 were completely omitted from analysis due to severe FOV shifts or where an individual camera had

1 greater than 50% of images lost, leaving a total of four cameras for understory analysis (5031 images
 2 total) and three for the overstory (4255 images total). All remaining cameras ($n = 7$) experienced
 3 slight FOV shifts as a result of manual data download. However, a Student t-test of 686 analysed
 4 images, for a camera with a large visible FOV shift, revealed no significant effect on the extracted
 5 results ($t_{686} = 0.13$, $p = 0.90$). The time series from each camera were then gap filled using the best
 6 regression relationship against another camera, most of which had an $r^2 > 0.8$.

7 Images were analysed in date/time succession using a region of interest (ROI) that encompassed as
 8 much of the vegetation as feasible. As a result, the ROI varied depending on the vegetation available
 9 in the overstory FOV and was the same for all understory cameras, except for a separate analysis of
 10 grass and woody green vegetation (Fig. 2). In addition, we analysed a separate sky-only ROI for each
 11 overstory camera and used the sky data to filter out sky-pixel information from the calculation of each
 12 index (Fig. 2, and supplementary material). Each camera collected 8-bit depth red-green-blue (RGB)
 13 colour channel information, stored as digital numbers (DN), at a resolution of 4608 x 3456 pixels.
 14 These DN's provide a measure of colour intensity based on irradiance, so they can vary when scene
 15 illumination changes (Ide and Oguma, 2010; Sonnentag et al., 2012). To reduce the effects of scene
 16 illumination, the DN's are typically used to calculate the green (GCC) chromatic coordinate, a
 17 normalised ratio of the green channel to all channels, as Eq. (1) (Gillespie et al., 1987; Woebbecke et
 18 al., 1995):

$$19 \quad G_{CC} = G_{DN} / (R_{DN} + G_{DN} + B_{DN}) \quad (1)$$

20 where DN is the digital number that corresponds with the green (G), red (R) and blue (B) channels.
 21 The red (RCC) and blue (BCC) chromatic coordinates were calculated in the same way as GCC.
 22 Chromatic coordinate values were calculated for each pixel within the ROI and then averaged to give
 23 an overall GCC, RCC and BCC value for each image. We also calculated the excess green (ExG), red
 24 (ExR) and blue (ExB) indices to compare which colour index performed best at capturing savanna
 25 phenological change. The excess index is an enhancement of the respective colour channel
 26 information against the other channels and is calculated as Eq. (2) (Woebbecke et al., 1995):

$$27 \quad ExG = 2G_{DN} - (R_{DN} + B_{DN}) \quad (2)$$

28 **2.5 Radiation data processing**

29 The amount of light absorbed by vegetation over time is directly correlated with productivity
 30 (Monteith, 1972). Using mini tower PAR data, we calculated fPAR for the overstory (OS) Eq. (3),
 31 understory (US) Eq. (4) and ecosystem (ECO) Eq. (5) as:

$$32 \quad fPAR_{OS} = (PAR_{AED} - PAR_{AEU} - PAR_{AGD}) / PAR_{AED}$$

33 (3)

$$fPAR_{US} = (PAR_{AGD} - PAR_{AGU} - PAR_{BGD})/PAR_{AGD}$$

(4)

$$fPAR_{ECO} = (PAR_{AED} - PAR_{AEU} - PAR_{BGD})/PAR_{AED}$$

(5)

where AED and AEU are the above ecosystem down-welling and up-welling PAR, AGD and AGU are the above grass down-welling and up-welling PAR, and BGD is the below grass down-welling PAR. Using fPAR, APAR was calculated for overstory, understory and ecosystem by multiplying the respective fPAR with available incoming PAR (note: this was PAR_{AGD} for the understory).

2.6 Leaf area index and biomass measurements

Variability of vegetation LAI and biomass over time is a direct result of phenology and productivity. We collected overstory LAI on each site visit (6 total) using digital hemispheric photography from a Canon digital single lens reflex (DSLR) camera (Rebel T1i) with a 185 ° super fisheye FOV (f/5.6) lens. The images were taken around a one-hectare plot (n = 36, Fig. 1) and analysed using WinScanopy (v2014a). A clumping coefficient was calculated to account for foliage clumping in the LAI estimate, which was verified using a Tracing Radiation and Architecture of Canopies (TRAC) instrument. These techniques agreed within 10-15 % of each other (0.82 to 0.94 in the wet season, 0.61 to 0.67 in the dry season). Understory biomass below 2 m in height was collected from 20 replicate 1 x 1 m quadrats along a N-S and E-W 100 m transect (10 samples each, every 5 m) over a full growing season (Dec-Apr, 4 total). Samples were separated into grass and other green biomass, weighed, then oven dried at 80 °C for 3 days to obtain dry weight. Following Chen et al. (2003), we converted the dry weight biomass into carbon content assuming it to be 43 % of grass biomass and 49 % of other green biomass.

2.7 Light use efficiency (LUE) models and incorporation of phenology

An alternative to estimating GPP from flux towers is to use a LUE model, where GPP is approximated by relating plant productivity to the amount of light they absorb over a growing season (Monteith, 1972). The MODIS GPP product (MOD17 A2.055) is calculated using a LUE model (Eq. (6), Running and Zhao, 2015), which we use in this study, as it has been validated for Australian savannas (Kanniah et al., 2009):

$$GPP = APAR \times LUE_p \times T_{MIN}^{scalar} \times VPD^{scalar}$$

(6)

where GPP is in $g\ C\ m^{-2}\ d^{-1}$, APAR is in $MJ\ d^{-1}$ and LUE_{max} is the general maximum light use efficiency during the wet season in $g\ C\ MJ^{-1}\ PAR^{-1}$. Because C_3 (trees) and C_4 (grasses) plants have different maximum LUE rates (Zhu et al., 2008), we calculated overstory and understory LUE_{max} separately following a similar approach to Kanniah et al. (2009) and Coops et al. (2007), where LUE is firstly calculated as $GPP/APAR$ and is then binned by month to obtain monthly LUE. We chose to

1 use the months of Dec-Mar (inclusive) to provide an estimate of LUE_{max} for the overstory and
 2 understory, as these months ($n = 8$, across two years) have the least environmental constraints to
 3 productivity and should be close to the maximum. This gave us a LUE_{max} value of 1.58 ± 0.06 g C
 4 $MJ^{-1} PAR^{-1}$ for the ecosystem, 1.43 ± 0.06 g C $MJ^{-1} PAR^{-1}$ for the overstory and 3.45 ± 0.41 g C MJ^{-1}
 5 PAR^{-1} for the understory (Fig. 3). In the LUE model the LUE_{max} values are then down regulated on a
 6 daily basis using the VPD_{scalar} Eq. (7) and $T_{MINscalar}$ (values between 0 and 1) Eq. (8) (Running
 7 and Zhao, 2015):

$$8 \quad VPD_{scalar} = (VPD_{max} - VPD_d) / (VPD_{max} - VPD_{min}) \quad (7)$$

$$9 \quad T_{MINscalar} = (T_{MIN} - T_{MINmin}) / (T_{MINmax} - T_{MINmin}) \quad (8)$$

10 where T_{MIN} is the minimum daily temperature for a given day, T_{MINmax} is the minimum daily
 11 temperature when LUE is at maximum and T_{MINmin} is the minimum daily temperature when LUE is 0,
 12 all of which are output in °C. Likewise, VPD_d is the mean daytime VPD, VPD_{max} is the maximum
 13 VPD when LUE is 0, and VPD_{min} is the minimum VPD when LUE is at maximum, all output in Pa.
 14 These scalar values range between 0 and 1. The MOD17 GPP algorithm uses values of -8 °C for
 15 T_{MINmin} , 11.39 °C for T_{MINmax} , 650 Pa for VPD_{min} and 3500 Pa for VPD_{max} for savannas (Running and
 16 Zhao, 2015). These values were validated for Howard Springs by Kanniah et al. (2009), so we used
 17 them in our study.

18 The use of a soil moisture term, evaporative fraction (EF), has been argued to represent plant
 19 available moisture more reliably than VPD (Gentine et al., 2007; Yuan et al., 2007; Kanniah et al.,
 20 2009). This term is simply a fractional estimate of latent heat (LE) divided by the sum of sensible heat
 21 (H) and LE (i.e. $LE / (LE + H)$). We also used EF in this study to test if it improved the estimation of
 22 overstory, understory and ecosystem GPP. For the overstory and ecosystem, we calculated EF using
 23 the ecosystem flux tower, whereas for the understory we calculated EF using the understory flux
 24 tower.

25 Another technique we tested for improving GPP estimates from the LUE model was to input
 26 phenocam greenness indices, as they have been found to correlate with ecosystem productivity in
 27 northern hemisphere forests and grasslands (Richardson et al., 2009b; Migliavacca et al.,
 28 2011; Toomey et al., 2015). We hypothesised that inclusion of GCC in the LUE model would improve
 29 the model's ability to predict savanna overstory and understory GPP, particularly given the strong
 30 phenology cycles displayed in savannas. As GCC is a fractional measure, like that of fPAR, we
 31 substituted GCC as a proxy for fPAR using the coefficients of a regression to normalise it, a similar
 32 approach to that used by Migliavacca et al. (2011). As a result, Eq. 6 was transformed to include
 33 $PAR \cdot (mGCC + c)$ in place of APAR, where m and c are the linear regression coefficients.

1 We repeated the above technique using MODIS EVI (Huete et al., 2002), to test if satellite indices
2 could be used to improve estimates of ecosystem scale GPP. We chose the EVI product
3 (MOD13Q1.005) as it has been shown to function well for identifying broad-scale phenology in
4 Australian savannas (Ma et al., 2013; Ma et al., 2014). A 3 x 3 pixel cut out of EVI data surrounding
5 the Howard Springs site, at 16-day and 250 m resolution, was processed in DINGO accepting the
6 quality flags 00 (highest overall quality) and 01 (good quality) only. The 16-day data were then
7 interpolated and smoothed, using a Savitzky-Golay technique (Savitzky and Golay, 1964) in DINGO,
8 to create a daily time series of EVI (Beringer et al., 2016c). Daily EVI were regressed against site-
9 based daily ecosystem fPAR and the regression was used along with incoming PAR to replace APAR
10 in Eq. (6).

11 Finally, to test the performance of each model against tower GPP estimates, we used a Pearson
12 correlation to provide a closeness of fit estimate (Corr) and test if the relationship was statistically
13 significant ($p < 0.05$). We also calculated the root mean squared error (RMSE) to provide a measure of
14 the difference between the two datasets (tower and model) and the relative predictive error (RPE) to
15 represent the percentage difference and degree of over- (+) or under- (-) estimation of the model.

16 **3 Results & Discussion**

17 **3.1 Phenological insights from phenocams**

18 The phenocam indexes revealed expected patterns from overstory and understory vegetation over time,
19 showing the cameras functioned well as phenology monitors of vegetation at the ecosystem and
20 species level (Fig. 4, 5 & 6). Not surprisingly, both GCC and ExG were highest in the understory
21 during the wet season and lowest by the late dry season (i.e. September, Fig. 4). The RCC and ExR
22 indices showed an inverse relationship to GCC and ExG, which is symptomatic of increased red
23 pigmentation from senescing leaves and chlorophyll loss (Hoch et al., 2001; Lee et al., 2003; Wingate
24 et al., 2015). This relationship is shown by the red-green index crossover in the understory that
25 coincides with grass senescence and signals the end of the wet season (i.e. Mar/Apr, see Fig. 4), along
26 with an increase in the red kandosol soil background showing through with the loss of understory
27 biomass. At the beginning of the wet season (Oct to Nov), the red-green crossover takes longer to
28 occur than at the end of the wet season (Fig. 4). Several rainfall events in November (Fig. 4, Fig. 5 for
29 rainfall) are required to reach the crossover, which is indicative of the vegetation response to the onset
30 of the rainy season (i.e. grasses need time to germinate). Peak GCC and ExG are not reached until
31 February (Fig. 4), the period of highest productivity for total understory biomass (Table 1).

32 The understory is a mix of annual (*S. intrans*) and perennial (*S. plumosum* & *H. triticeous*) grasses,
33 overstory (*E. tetradonta* & *E. miniata*) and mid-story (*E. chlorosyachys*, *T. ferdinandiana* & *B.*
34 *obovata*) saplings, and cycads (*C. armstrongii*), that all have differing phenologies (Bowman and

1 Prior, 2005). The dynamic nature of these phenological guilds is reflected in the temporal patterns of
2 GCC and ExG between grasses and the non-grass woody elements (herein ‘woody green’, Fig. 5).
3 While grasses are the most abundant understory species in terms of biomass (Table 1) and LAI at
4 Howard Springs (Hutley et al., 2000), they are only active during the wet season (Andrew and Mott,
5 1983;Scott et al., 2010). During the early wet (October/November) and dry (April/May) seasons, the
6 woody green species take advantage of the lack of grass to gain biomass (Werner and Franklin,
7 2010;Werner and Prior, 2013).

8 Annual grasses typically germinate after the first 15 mm or more of rainfall, with further rainfall
9 events required to drive leaf growth (Andrew and Mott, 1983;Cook et al., 2002). Pre-monsoonal
10 rainfall is highly variable in its timing and amount, therefore this phenological strategy may minimise
11 grass mortality if dry periods proceed an initial early wet season rainfall event (Moore et al., 2016a).
12 In Fig. 5, this delay in grass greening is evident, with rapid increases in GCC occurring one month
13 after the first rainfall event (Fig. 5, Oct-Dec 2013). Phenocam data can therefore tease apart
14 composite greening signals to better understand phenological dynamics and fluxes in these
15 ecosystems (Fig. 5 & 7). Understory biomass data also support the GCC results, revealing that as the
16 wet season progressed, the grasses increased in dominance to account for 77 % of understory biomass
17 by the end of the wet season (Table 1). While the grasses are the primary driver of understory biomass
18 and productivity, the woody green species also make important contributions throughout the year and
19 are likely the reason why understory GPP does not completely cease in the dry season (Moore et al.,
20 2016a).

21 In contrast to the understory, overstory GCC and ExG did not fluctuate much when compared to the
22 red and blue channel indices (Fig. 6, a). This is mostly due to the high portion of blue sky and cloud
23 within the ROI’s for the overstory images (Fig. 2, e & f), which vary depending on daily weather
24 conditions. However, application of a sky threshold, calculated from a sky-only ROI, improved the
25 seasonal pattern seen in overstory GCC (see supplementary material) and contributed to removing the
26 influence of sky pixels on the GCC calculation. These values also agreed with changes in overstory
27 LAI (Fig. 6, b). A larger ROI was necessary for the overstory analysis due to the daily movement of
28 trees. While there is inherent uncertainty in both the phenocam imagery (i.e. FOV, scene illumination)
29 and LAI (i.e. leaf projection and orientation, clumping, gaps, see Ryu et al. (2010)) estimates in this
30 study, the savanna overstory is known to experience seasonal fluctuations in LAI with the highest
31 values in the wet season and lowest values in the late dry season (Williams et al., 1997;O’Grady et al.,
32 2000). The same pattern is displayed in Fig. 6, giving us confidence that the phenocams were able to
33 detect overstory cover change.

1 **3.2 Phenocam and MODIS phenology in relation to GPP**

2 The seasonality of GPP in these savannas has been found to differ between that of the overstory and
3 understory, with understory GPP tied more closely to the duration of the wet season than that of the
4 overstory (Moore et al., 2016a). The GCC and ExG time series appeared to capture the overstory and
5 understory GPP estimates (Fig. 7), so we hypothesised that they could be useful for independently
6 predicting overstory and understory GPP. Simple linear regressions of GCC against flux tower GPP
7 quantified the relationship between the two variables, with understory GPP ($r^2 = 0.65$) revealing a
8 closer fit with GCC than overstory GPP ($r^2 = 0.23$, Fig. 7). The ExG index did not perform so well
9 compared with GCC for the overstory ($r^2 = 0.14$) but improved the relationship slightly against GCC
10 for the understory ($r^2 = 0.72$, Fig. 7). ExG was originally developed for identifying green vegetation
11 from images with a soil background (Woebbecke et al., 1995). This is a likely reason for why the
12 relationship between ExG and GPP was slightly closer to 1:1 than that of GCC for the understory.

13 While the relationship between overstory greenness (ExG/GCC) and GPP is not as strong as that of
14 the understory, the phenocams were still able to detect seasonality in greenness that followed GPP
15 over time (Fig. 7). The trees have a deeper rooting structure than the grasses, allowing them to access
16 a larger volume of soil moisture (Eamus et al., 2002; Kelley et al., 2007) and thus maintain constant
17 overstory transpiration throughout the year (O'Grady et al., 1999; Hutley et al., 2000). While the tree
18 canopy is largely evergreen, the LAI will drop up to 30-40 % in order to account for the dry season
19 water deficit (O'Grady et al., 2000; Whitley et al., 2011), which is also apparent from both our
20 overstory LAI and GCC results (Fig. 6). Tree productivity, in contrast to transpiration, is known to
21 decrease into the dry season (Eamus et al., 1999), and most carbon uptake is directed toward
22 maintenance respiration rather than growth (Chen et al., 2002; Prior et al., 2004; Cernusak et al., 2006).
23 However, the occurrence of late wet season rainfall events may benefit the productive capacity of the
24 trees by boosting soil moisture stores, thereby supporting higher rates of productivity for longer in the
25 dry season (Moore et al., 2016a). This effect is apparent in our overstory GCC time series, where after
26 late April to early May rainfall events (see Fig. 5 for daily rainfall), GCC spikes in June indicate a
27 flushing of the foliage in the dry season (Fig. 6, b).

28 At the ecosystem scale, the interaction of the overstory and understory with the wet and dry seasons
29 drives variability in productivity. The MODIS greenness index, EVI, mostly captures this variability,
30 albeit at coarser temporal resolution (Fig. 7, e) when compared with the phenocams. While the broad
31 scale variability in savanna phenology change is captured by EVI, such as seasonality (Ma et al.,
32 2013), it is not able to capture the finer scale details that the site based phenocams can. MODIS
33 indices, such as EVI, do not currently have the ability to identify individual plant scale phenology
34 patterns (Brown et al., 2016; Moore et al., 2016b), which is another advantage of the phenocam (Fig.
35 5). The phenocam data also provides a useful means of validating the MODIS data in that both are
36 able to track the seasonality of savanna GPP, which is driven by a complex interaction of both

1 meteorology and phenology (Kanniah et al., 2011;Whitley et al., 2011;Ma et al., 2013;Ma et al.,
2 2014).

3 **3.3 Integrating phenocam and MODIS phenology with a LUE model**

4 To use greenness phenology information for predicting GPP from the LUE model, an estimate of
5 maximal LUE was calculated, which was higher for the understory ($3.45 \pm 0.41 \text{ g C MJ}^{-1} \text{ PAR}^{-1}$)
6 compared to the overstory ($1.43 \pm 0.06 \text{ g C MJ}^{-1} \text{ PAR}^{-1}$, Fig. 3). The higher LUE_{max} for the understory
7 is largely due to the dominance of C_4 grasses in the understory (Table 1), as their C_4 photosynthetic
8 pathway is more energy efficient (Sage, 2004;Osborne and Beerling, 2006;Zhu et al., 2008). Our
9 values fell within the range of LUE_{max} reported for African savannas, which have varied from as low
10 as $0.33 \text{ g C MJ}^{-1} \text{ PAR}^{-1}$ up to $3.5 \text{ g C MJ}^{-1} \text{ PAR}^{-1}$ depending on the vegetation and season (Sjöström et
11 al., 2013;Tagesson et al., 2015). Recent work has shown the importance of correctly applying LUE_{max}
12 values to C_3 and C_4 plants when using LUE models to calculate GPP (Yan et al., 2015). Therefore, to
13 account for the C_3 : C_4 differences, we applied these site and trait specific values to the LUE model
14 used to estimate GPP.

15 The next step in our parameterisation of the LUE model was to test it in its traditional form; using the
16 meteorological inputs of T_{MIN} and VPD that constrain LUE_{max} , along with APAR (Eq. 6). We found
17 the model captured most of the seasonality of overstory GPP but underestimated the magnitude of
18 GPP in the dry season and overestimated GPP in the wet season (Table 2, Fig. 8, a). For the
19 understory, the LUE model appeared to overestimate and lag flux tower GPP consistently by 1-2
20 months (Table 2, Fig. 9, a). This resulted in a strong dry season over estimate of understory GPP
21 (165 %, Table 2). For the ecosystem, the LUE model consistently overestimated GPP (Table 2, Fig.
22 10, a). Kanniah et al. (2009) also found the LUE model performed poorly for the Howard Springs
23 ecosystem, so they replaced the standard VPD parameterisation with an EF term and found this to
24 improve the relationship, which we implemented next.

25 The EF value improved model predictions of overstory GPP in the dry season but overestimated GPP
26 in the wet season, causing an over prediction of annual GPP by 18 % overall (Table 2, Fig. 8, a vs. b).
27 In contrast, the inclusion of EF in the understory LUE model slightly improved the prediction of
28 annual GPP, with better correlation (0.69 vs 0.56), lower RMSE (2.00 vs. 2.66 g C m^{-2}) and lower
29 RPE (38.58 vs. 79.62 %). However, the understory model still lagged tower GPP and was still
30 particularly poor at capturing the seasonal transitions (Fig. 9 a & b). For the ecosystem, the inclusion
31 of EF enhanced the overestimation of GPP from 15 to 26 %, particularly in the wet season (Table 2,
32 Fig. 10, a vs. b). EF provides a proxy measure of soil moisture as it includes a water flux component
33 (LE) that is tightly linked with soil moisture availability (Gentine et al., 2007;Kanniah et al., 2009). In
34 Australian savannas, soil moisture is highly seasonal and a major driver of productivity (Kanniah et
35 al., 2010). This makes EF a useful index in the dry season, when latent heat largely comes from

1 transpiration and is therefore tightly coupled with GPP. However, in the wet season, soil evaporation
2 contributes a large amount to latent heat, which is not tightly coupled to GPP (Kanniah et al., 2009).
3 This explains why EF is able to constrain the LUE model in the dry season and why it performs
4 poorly in the wet season and transition periods.

5 Despite the improvements of EF, the model still performed poorly at capturing the wet-dry-wet season
6 transition periods. We believed this was due to APAR, which failed to capture the same degree of
7 seasonality as the phenocam indexes (see supplementary material). The incorporation of phenocam
8 GCC into the LUE model improved the estimate of understory GPP substantially (Table 2, Fig. 9, c &
9 d). This was most apparent with the combined use of GCC and EF in the LUE model, which produced
10 the best correlation ($r = 0.86$), lowest RMSE (1.42 g C m^{-2}) and lowest RPE (39.59 %, Table 2, Fig. 9).
11 These results show that while EF is an important factor for GPP, greenness phenology is also key for
12 estimating understory productivity. In further support of this, the inclusion of GCC also eliminated the
13 lag in model estimated GPP, bringing the estimate closer in line with seasonal variability from the
14 flux tower, as evidenced by the large decrease in RMSE and RPE (Table 2, Fig. 9). As previously
15 discussed, the understory grasses (annual species in particular) die off at the cessation of the wet
16 season and do not contribute to the small fraction of understory GPP in the dry season (Moore et al.,
17 2016a). This is a plant phenology response, rather than a response to meteorological conditions, as
18 factors such as soil moisture remain high enough in the early dry season to support plant growth
19 (Eamus et al., 2002; Kelley et al., 2007; Moore et al., 2016a). Given that these grasses dominate
20 understory biomass at Howard Springs, it is not surprising that including greenness phenology
21 information in the LUE model improves its output relative to the flux tower.

22 The inclusion of greenness indices in the LUE model for the overstory (GCC) and ecosystem (EVI)
23 also improved the estimate of GPP. For the overstory, the combination of EF and GCC performed
24 slightly better in the dry season than GCC alone, but was not able to capture the wet season well
25 (Table 2, Fig. 8 d). This resulted in the incorporation of GCC into the LUE model producing the best
26 overall result, despite the slightly lower correlation value (0.60 vs 0.72) when compared with GCC
27 and EF combined (Table 2). For the ecosystem, the inclusion of EVI into the LUE model performed
28 the best at predicting GPP, which was supported by the lowest values for RMSE (2.12 g C m^{-2}) and
29 RPE (15.49 %, Table 2).

30 The greenness information clearly fills an important gap in relation to changes in overstory,
31 understory and ecosystem greenness. The general improvement in LUE model output for overstory,
32 understory and ecosystem with the inclusion of greenness phenology information highlights the
33 importance of accounting for phenological variability when estimating GPP in savannas. A similar
34 result was found for a subalpine grassland in Italy, where phenocam greenness indices improved the
35 ability of the same LUE model to predict grassland GPP (Migliavacca et al., 2011). Likewise, in an

1 evergreen Amazonian rainforest, Wu et al. (2016) linked phenological changes in leaf development
2 and demography to seasonality in GPP, showing the importance of phenology as a driver of
3 ecosystem productivity. For Australian savannas, the effect of phenology is most evident at the end of
4 the wet season (Apr-May), where in the understory, growth ceases due to annual grass senescence
5 even though meteorological conditions (temperature, VPD and/or EF) are still sufficient to support
6 growth (Fig. 9 a&b vs. c&d). The original LUE model over-predicts GPP as a result of this, which is
7 due to APAR remaining high despite the lack of green vegetation (see supplementary material). This
8 effect is substantially reduced by the inclusion of greenness phenology indices that likely represents a
9 type of 'green APAR' that more closely tracks the vegetation productivity over time.

10 **3.4 Limitations, impacts and further work**

11 While phenocams have consistently proven to be a useful tool for phenological and productivity
12 research (Richardson et al., 2009b;Migliavacca et al., 2011;Toomey et al., 2015;Wu et al., 2016),
13 there still remain several limitations that require further investigation to improve their utility. Issues
14 related to camera choice and image collection have been shown to be less problematic for simple
15 identification of phenological transition dates and seasonal variation than first thought (Sonnentag et
16 al., 2012), however, maintaining similar protocols for cross site comparisons remains preferable
17 (Moore et al., 2016b). Scene illumination variability is probably the most problematic limitation of
18 phenocams, which can be reduced by using chromatic coordinates or excess values, as well as by
19 setting the white balance to a fixed level (Richardson et al., 2009a;Ide and Oguma, 2010;Migliavacca
20 et al., 2011). Although white balance was not fixed for this study, we found that the GCC and ExG
21 time series matched well with GPP estimates regardless and provided added value to that gained from
22 using just APAR alone in the LUE model. We suspect this is due to the highly dynamic nature of the
23 savanna vegetation, which allows the phenology signals to be identified despite the potential for
24 variable white balance.

25 The wet season influence on scene illumination adds daily noise to the time series, but the indices are
26 still useful for informing seasonal productivity estimates. This same relationship will likely not stand
27 for other, less dynamic ecosystems in Australia (Restrepo-Coupe et al., 2015;Moore et al., 2016b), so
28 we recommend the fixing of white balance where appropriate. The use of a grey reference panel for
29 normalising phenocam images has also been proposed (Richardson et al., 2009a), however, this
30 technique has issues related to panel orientation and illumination conditions that can be different to
31 those experienced by the phenocams (Migliavacca et al., 2011). Despite these limitations, phenocams
32 are still an important tool for both species and plot scale phenology monitoring and with further
33 developments, will continue to provide valuable insight into Australian vegetation phenology (Moore
34 et al., 2016b).

1 In addition to the phenocam issues, the light use efficiency model used in this study is also subject to
2 limitations. This model relies on the input of meteorological information to generate an estimate of
3 ecosystem GPP. It is often found that these models overestimate GPP in the transition periods from
4 wet-dry or dry-wet in savanna ecosystems (Kanniah et al., 2009). The primary reason for this is that
5 savanna GPP is not driven solely by meteorology, that plant phenology also plays an important role,
6 as shown in our analysis. The technique for estimating LUE_{max} , used in the LUE model (Eq. 5), also
7 involves a degree of uncertainty that is centred around the input parameters of LUE and APAR, as
8 well as the scalars used to constrain it (De Bie et al., 1998;Sjöström et al., 2013).

9 The MODIS MOD17 A2 GPP product uses a LUE_{max} value of 1.21 g C MJ^{-1} for savannas and 1.24 g
10 C MJ^{-1} for woody savannas (Zhao and Running, 2010). While these values are close to the number we
11 calculated for the overstory ($1.43 \pm 0.06 \text{ g C MJ}^{-1} \text{ PAR}^{-1}$), we found the understory LUE_{max} to be much
12 larger ($3.45 \pm 0.41 \text{ g C MJ}^{-1} \text{ PAR}^{-1}$). Similarly, for African savannas, LUE_{max} has been found to reach
13 up to $3.50 \text{ g C MJ}^{-1} \text{ PAR}^{-1}$ in the wet (growing) season (Sjöström et al., 2013;Tagesson et al., 2015).
14 These LUE_{max} values are much larger than that used in the MOD17 A2 algorithm, which suggests that
15 tree-grass (C_3 vs. C_4) ratios need to be better accounted for in the LUE model. Recent work from Yan
16 et al. (2015) has shown this to be the case, where the application of different LUE_{max} values to C_3 (1.8
17 $\text{g C MJ}^{-1} \text{ PAR}^{-1}$) and C_4 ($2.76 \text{ g C MJ}^{-1} \text{ PAR}^{-1}$) plants improved global model estimates of GPP.

18 Finally, the flux tower estimates of GPP are not without their own limitations, as the towers measure
19 NEE that is then partitioned into GPP and respiration most commonly by using a friction velocity (u^*)
20 threshold at night and upscaling method for the daytime (Reichstein et al., 2005;Bowman, 2000;Keith
21 et al., 2012). Use of the u^* technique has been shown to be problematic at sites with complex terrain
22 (van Gorsel et al., 2009), where drainage flows result in horizontal loss of carbon from an ecosystem
23 that is not accounted for by the flux instruments. While Howard Springs is a relatively flat site (slope
24 $< 1^\circ$) that should prevent issues with using the u^* technique, the flux tower estimates from this site
25 should still be considered with an amount of uncertainty as well (Moore et al., 2016a;R Core Team,
26 2013). However, these issues have been addressed by previous work at this site (Moore et al., 2016a)
27 so we have confidence in the fluxes used for this study. Despite these limitations, we were able to
28 show that the input of phenological information into LUE models can provide a useful constraint for
29 estimating GPP within the uncertainty limits of tower derived estimates, a similar conclusion to that
30 found over a subalpine grassland in the Italian Alps (Migliavacca et al., 2011).

31 **4 Conclusion**

32 We have shown the utility of phenocams for the monitoring of tree and grass phenology in savannas
33 and how this data can improve the quantification of productivity. Phenocams offer the ability to
34 decipher species level phenological signals, as shown by our time series analysis of understory grasses

1 and woody green species, as well as in the tracking of seasonal overstory leaf area change. Phenocams
2 have also shown to be useful for improving LUE models that have traditionally failed to capture the
3 wet-dry season transition periods well in savannas, which are characterised by phenology changes in
4 the understory that are out of sync with meteorological variability. This approach needs to be tested in
5 more ecosystems to determine its applicability for a wider range of ecosystem types, but promises
6 improved results for better understanding of ecosystem GPP and phenology. Phenological information
7 offers an important link for our understanding of ecosystem function as it provides a more accurate
8 means of independently verifying tower derived GPP estimates in savannas. We have demonstrated
9 that phenocams can be used in conjunction with eddy covariance flux towers to improve current
10 knowledge of savanna productivity and phenology, which will assist in our understanding of how the
11 tree-grass relationship in savannas may alter in the future.

12 **Author Contributions**

13 Field work and experimental design was executed by C. Moore, J. Beringer, L. Hutley and B. Evans.
14 Data analysis was chiefly carried out by C. Moore, with some coding assistance from B. Evans. The
15 manuscript was prepared by C. Moore with contributions from all co-authors.

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Table 1: Understory biomass harvest information for Howard Springs savanna collected across the wet seasons from 2012 to 2014.

Period	Grass biomass (t ha ⁻¹)	Other biomass (t ha ⁻¹)	Grass biomass (%)	Other biomass (%)
Start Wet – Dec	0.46	0.96	33	67
Mid Wet – Feb	1.34	1.77	43	57
Peak Wet – Mar	1.55	1.09	59	41
End Wet - Apr	1.31	0.38	77	23

Table 2: Summary of model performances against flux tower estimated GPP for overstory and understory at Howard Springs. Statistics include the Pearson Correlation coefficient (Corr), the root mean square error (RMSE, $\text{g C m}^{-2} \text{d}^{-1}$) and the relative predictive error (RPE, %) for the light use efficiency model (LUE), LUE with evaporative fraction (LUE_EF), LUE with green chromatic coordinates (LUE_GCC) and LUE with EF and GCC (LUE_EF_GCC). The * highlights that the MODIS enhanced vegetation index (EVI) is used instead of GCC for the Ecosystem analysis. Pearson p values are not included as all were significant with $P < 0.001$.

Model		Overstory			Understory			Ecosystem*		
		Corr	RMSE	RPE	Corr	RMSE	RPE	Corr	RMSE	RPE
All years	LUE	0.64	1.64	7.50	0.56	2.66	79.62	0.80	2.18	14.82
	LUE_EF	0.73	1.80	18.33	0.69	2.00	38.58	0.79	2.79	26.39
	LUE_GCC/EVI*	0.60	1.56	6.39	0.81	1.86	80.21	0.81	2.12	15.49
	LUE_EF_GCC/EVI*	0.72	1.60	16.38	0.86	1.42	39.59	0.83	2.52	26.22
Wet Season (15 Oct - 15 Apr)	LUE	0.61	2.00	24.51	0.31	3.20	52.00	0.72	2.54	16.97
	LUE_EF	0.68	2.37	34.93	0.39	2.73	41.09	0.66	3.32	26.83
	LUE_GCC/EVI*	0.61	1.78	22.52	0.63	2.16	53.83	0.74	2.46	19.63
	LUE_EF_GCC/EVI*	0.69	2.06	32.40	0.67	1.97	45.18	0.71	3.13	29.12
Dry Season (16 Apr - 14 Oct)	LUE	0.40	1.26	-10.75	0.56	2.09	165.76	0.57	1.83	11.71
	LUE_EF	0.64	1.12	0.51	0.52	1.05	30.77	0.72	2.26	25.75
	LUE_GCC/EVI*	0.23	1.34	-10.91	0.45	1.55	162.43	0.39	1.77	9.51
	LUE_EF_GCC/EVI*	0.56	1.06	-0.81	0.35	0.69	22.17	0.63	1.86	22.01

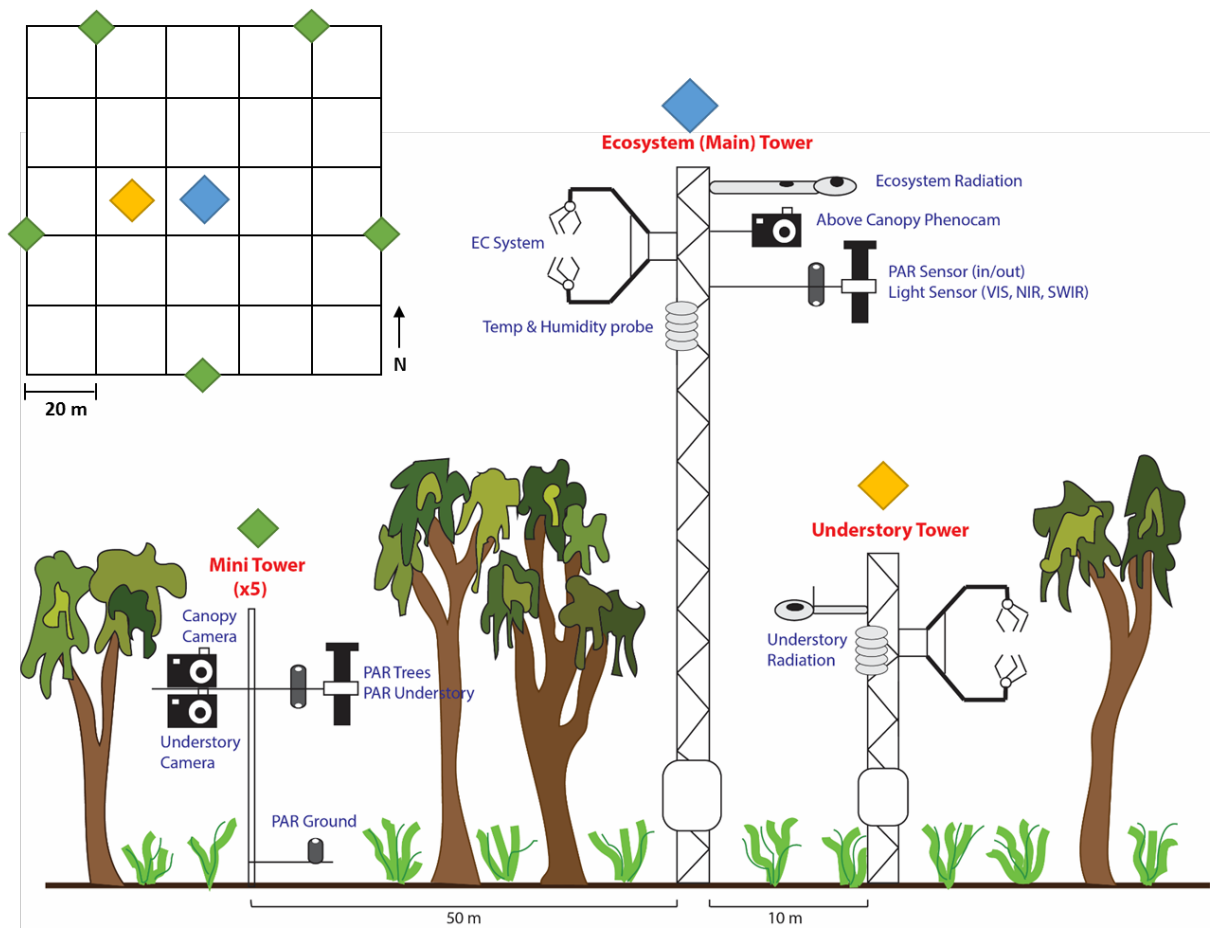


Figure 1: Diagram showing the core instrumentation supported by each flux tower and mini tower at the Howard Springs OzFlux site, as well as the layout of the monitoring plot.

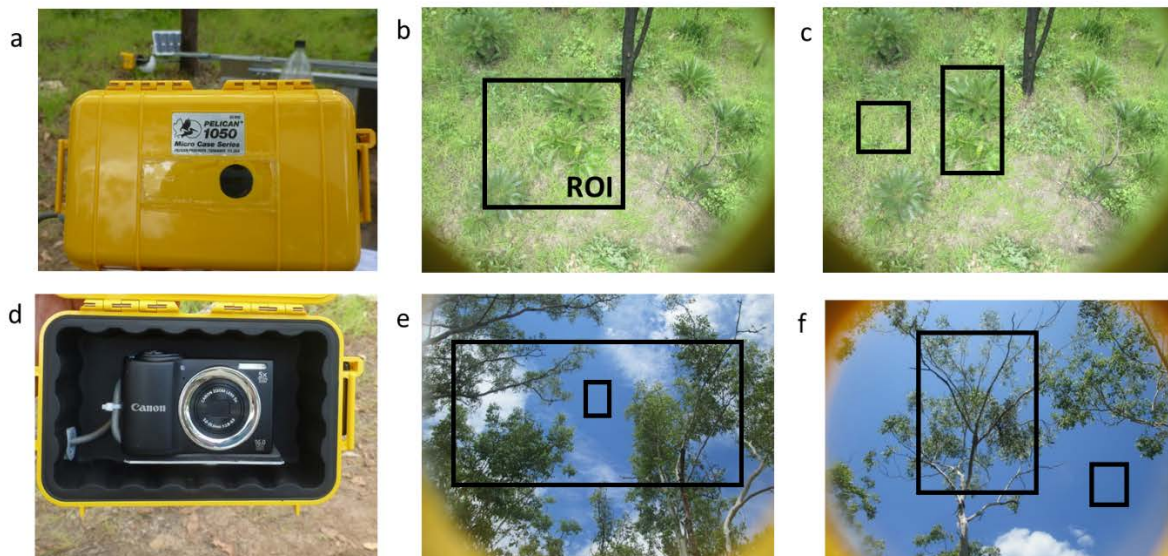


Figure 2: Camera setup (a & d) and examples of understory (b & c) and overstory (e & f) regions of interest (ROI, black box) used from phenocam images collected at the Howard Springs OzFlux site.

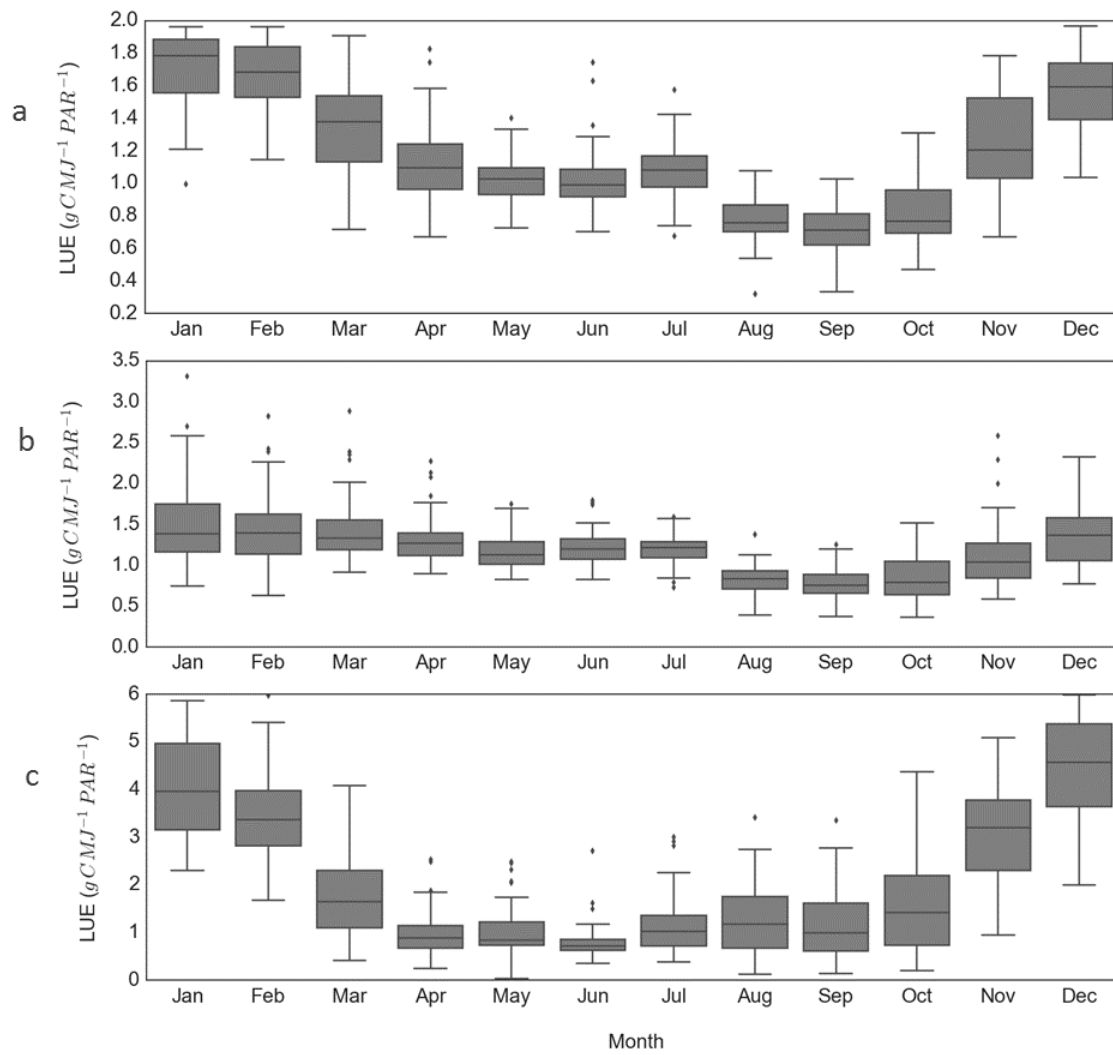


Figure 3: Monthly mean light use efficiency (LUE) \pm SE (boxes) with 95 % confidence (whiskers) for the Howard Springs OzFlux site ecosystem (a), overstory (b) and understory (c) from December 2012 to October 2014. Individual dots represent outlier values for each respective month.

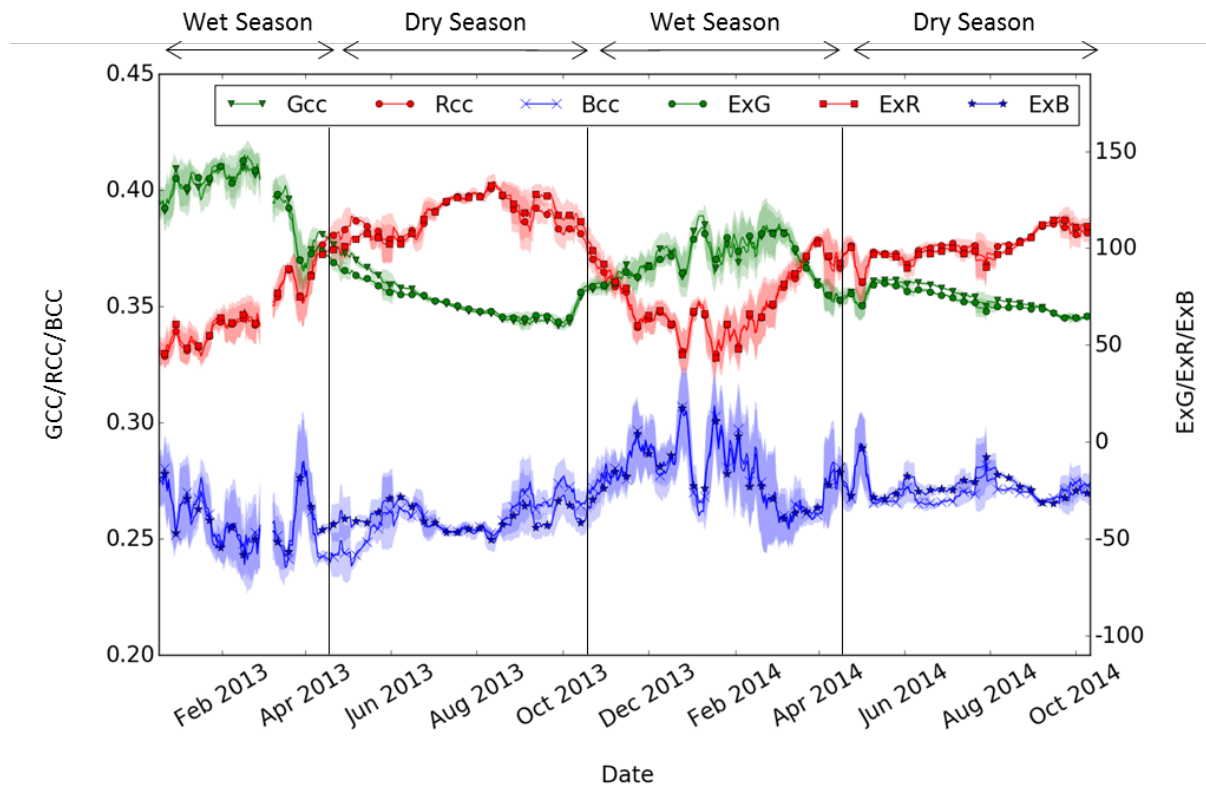


Figure 4: Daily green, red and blue chromatic coordinates (GCC/RCC/BCC) and excess indices (ExG/ExR/ExB) for the Howard Springs OzFlux site understory from December 2012 to October 2014. Daily data are shown with an 8-day centred running mean (marked every 8 days for visualisation) applied. The standard error of the mean is given by the shading.

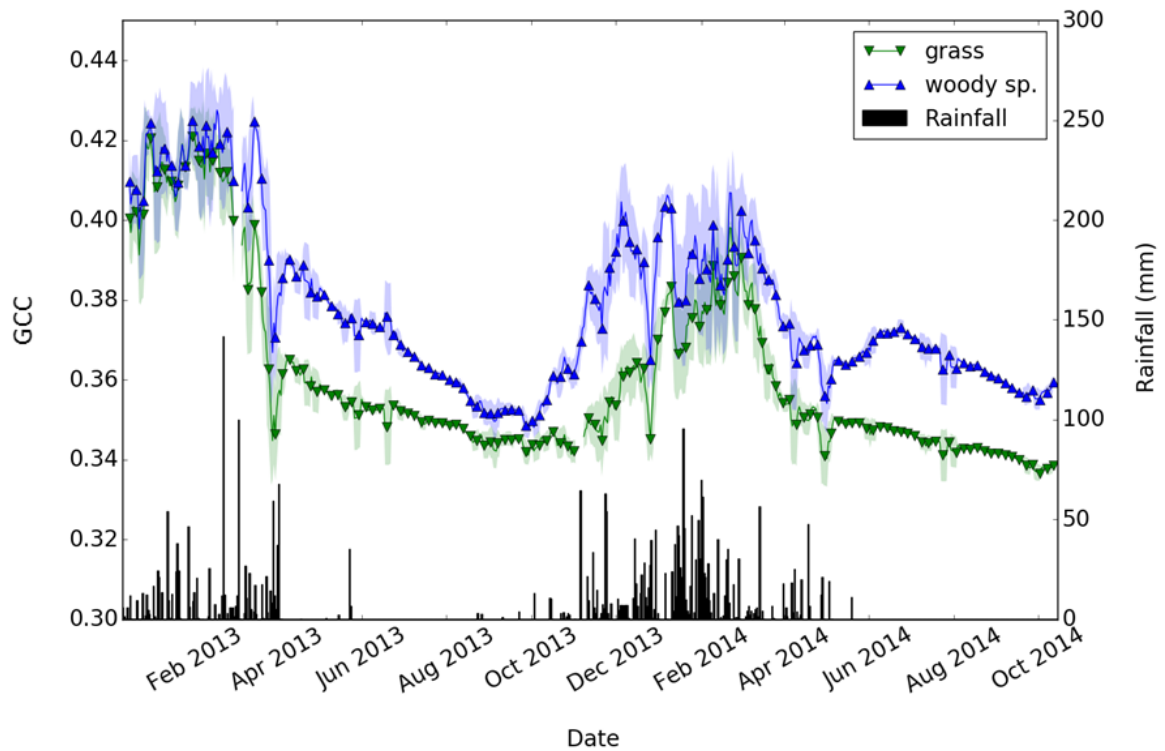


Figure 5: Daily rainfall (mm) and green chromatic coordinate (GCC) time series for grass and other woody green species (woody sp.) found in the savanna understory at the Howard Springs OzFlux site from December 2012 to October 2014. The GCC daily data are shown with an 8-day centred running mean (marked every 8 days for visualisation) applied. The standard error of the mean is given by the shading. The GCC time series represent the change in relative greenness of grass and woody species, not the absolute sum of grass versus woody species biomass in the understory.

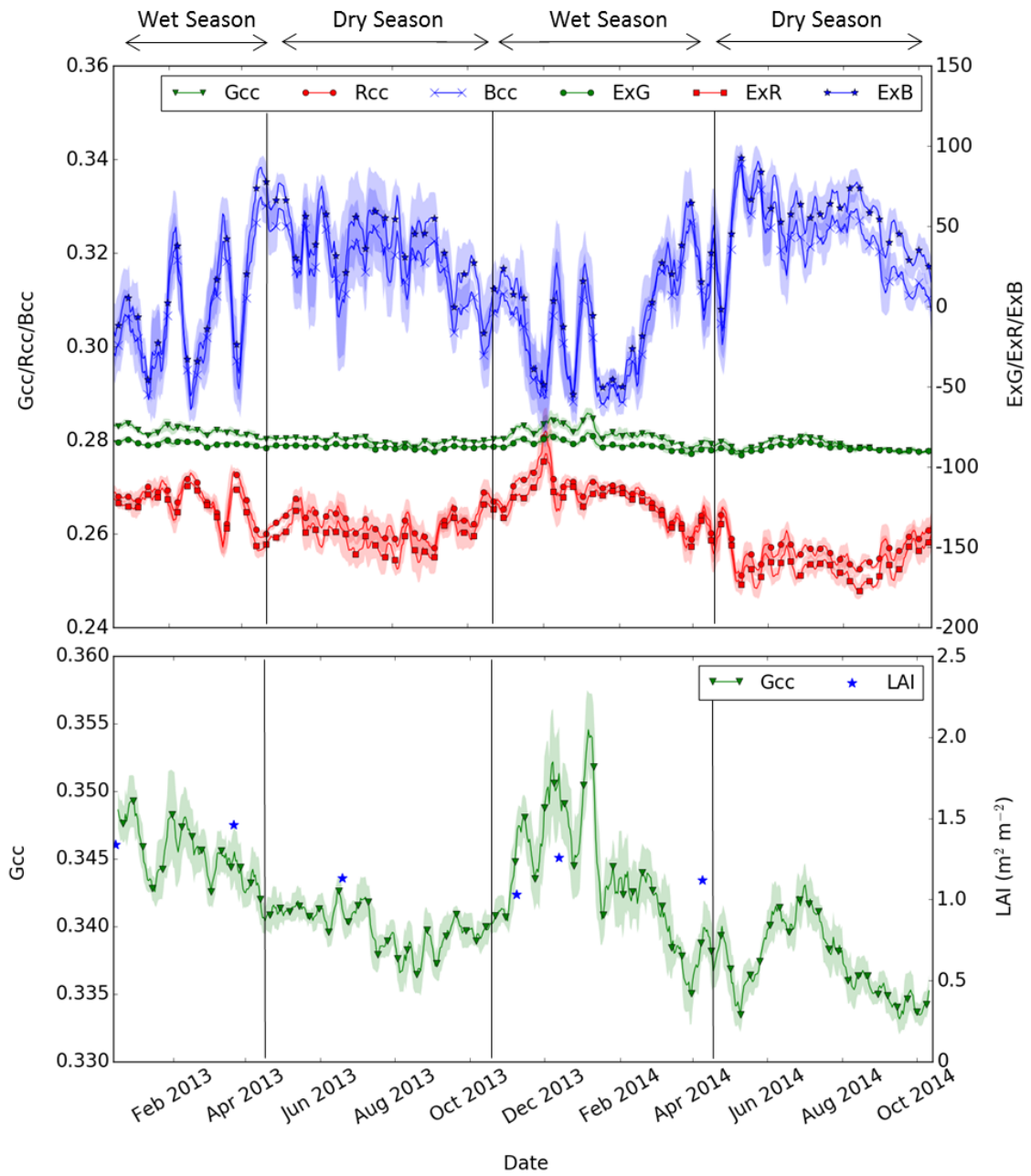


Figure 6: Daily green, red and blue chromatic coordinates (GCC/RCC/BCC) and excess indices (ExG/ExR/ExB) for the Howard Springs OzFlux site overstory (a), plus GCC and leaf area index (LAI) for the overstory (b) from December 2012 to October 2014. Daily data are shown with an 8-day centred running mean (marked every 8 days for visualisation) applied. The standard error of the mean is given by the shading.

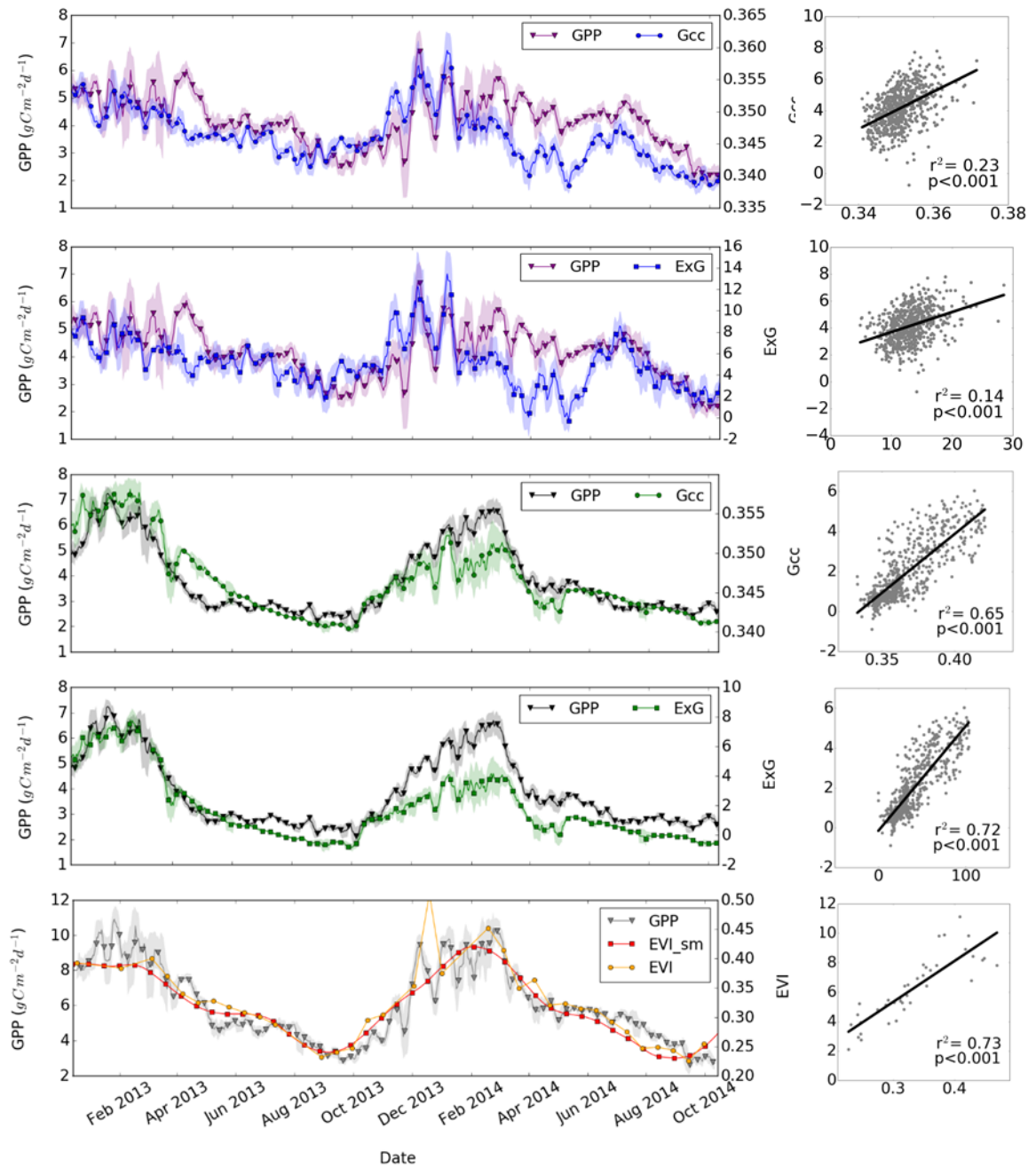


Figure 7: Overstory (a & b) and understory (c & d) flux tower GPP with green chromatic coordinate (GCC) and excess green (ExG) indices, as well as ecosystem flux tower GPP with MODIS enhanced vegetation index (EVI), from December 2012 to October 2014 at the Howard Springs OzFlux site. Daily data are shown with an 8-day running mean (marked every 8 days for visualisation) applied. The standard error of the mean is given by the shading. Included for each time series are the respective regression plots showing r^2 and p values for GCC/ExG/EVI (x) against flux tower GPP (y). For MODIS EVI (e) the time series plot includes raw 16 day values (EVI) and a Savitzky-Golay smoothed daily EVI product (EVI_sm), with the regression plot showing the raw 16 day EVI and the corresponding GPP for that day.

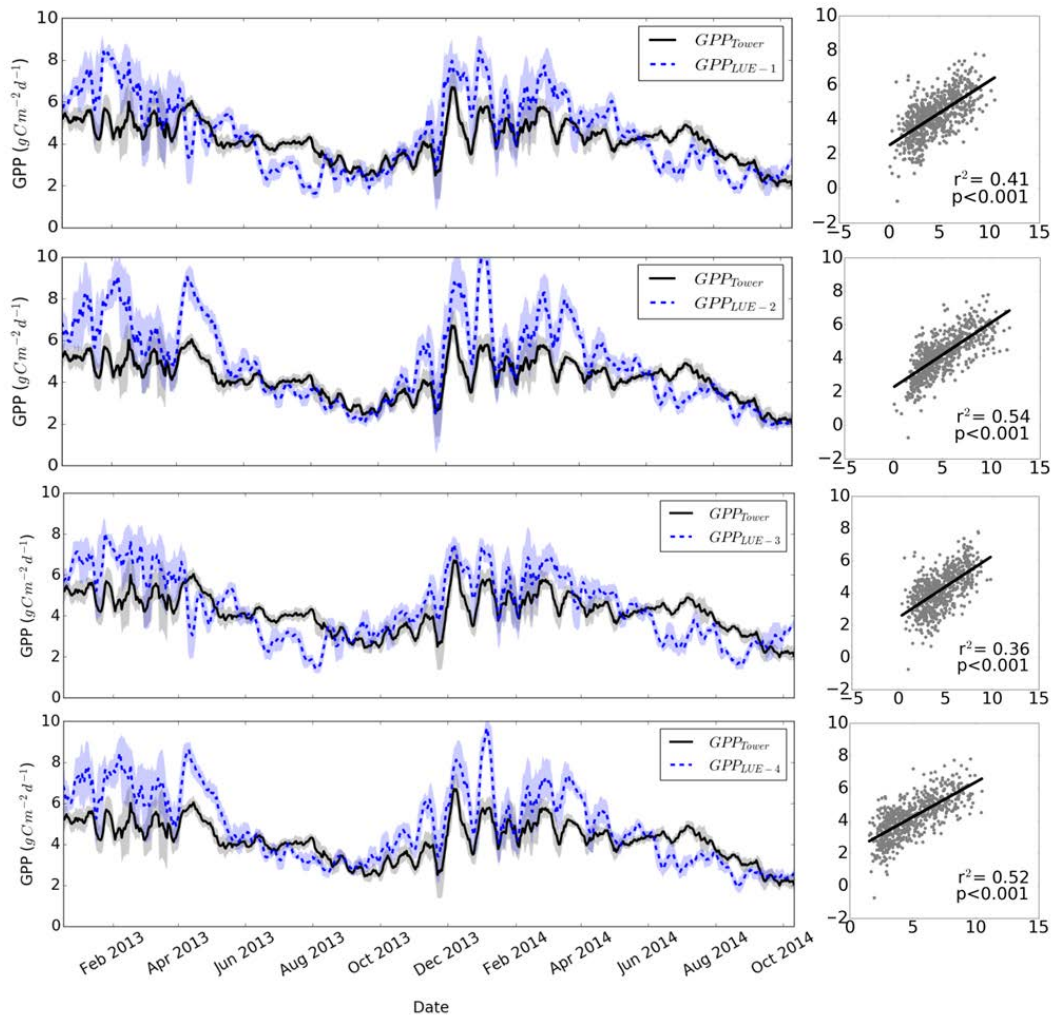


Figure 8: Overstory flux tower estimated GPP with model predicted GPP for the Howard Springs OzFlux site. Models shown are a) light use efficiency (LUE-1), b) LUE with evaporative fraction (LUE-2), c) LUE with green chromatic coordinates (LUE-3), d) and LUE with EF and GCC (LUE-4).

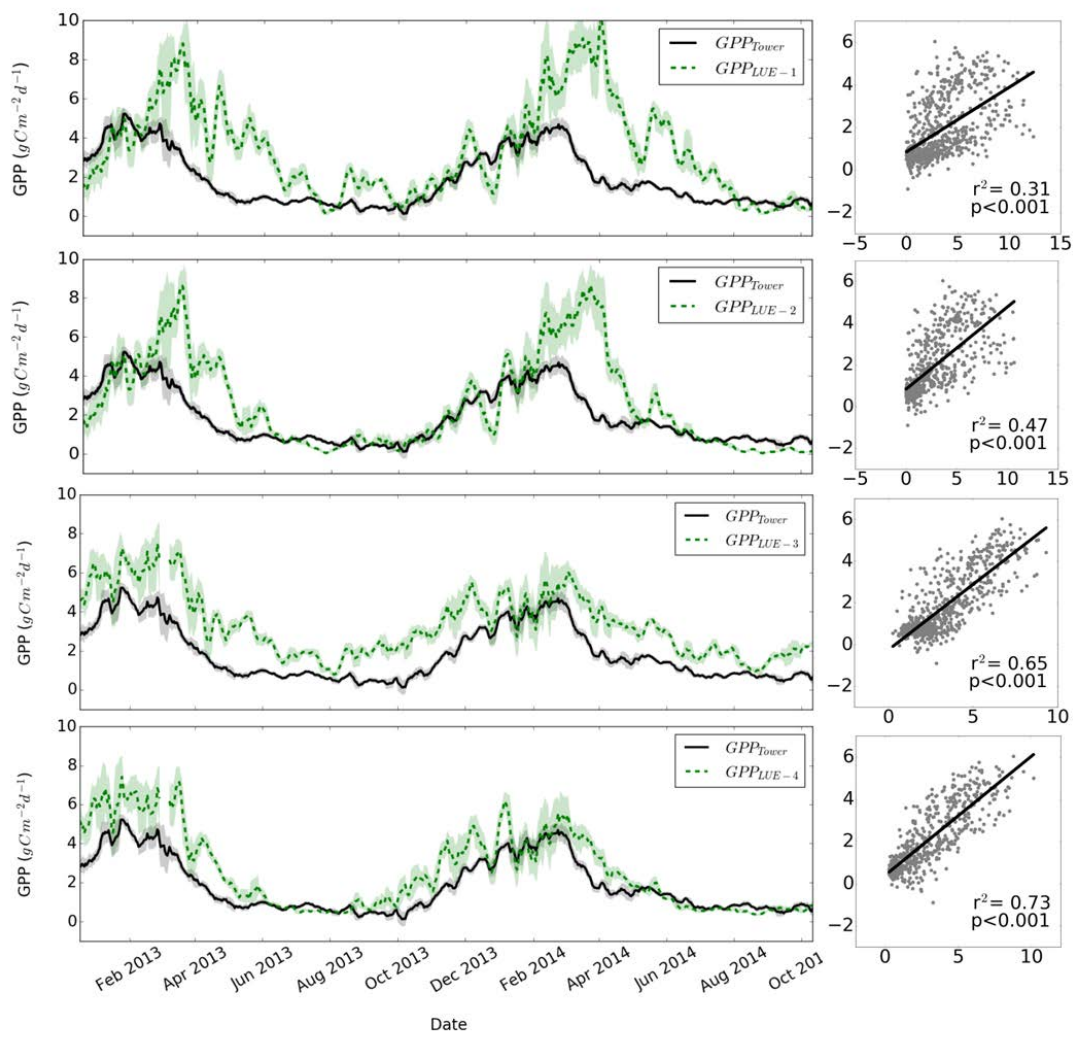


Figure 9: Understory flux tower estimated GPP with model predicted GPP for the Howard Springs OzFlux site. Models shown are a) light use efficiency (LUE-1), b) LUE with evaporative fraction (LUE-2), c) LUE with green chromatic coordinates (LUE-3), d) and LUE with EF and GCC (LUE-4).

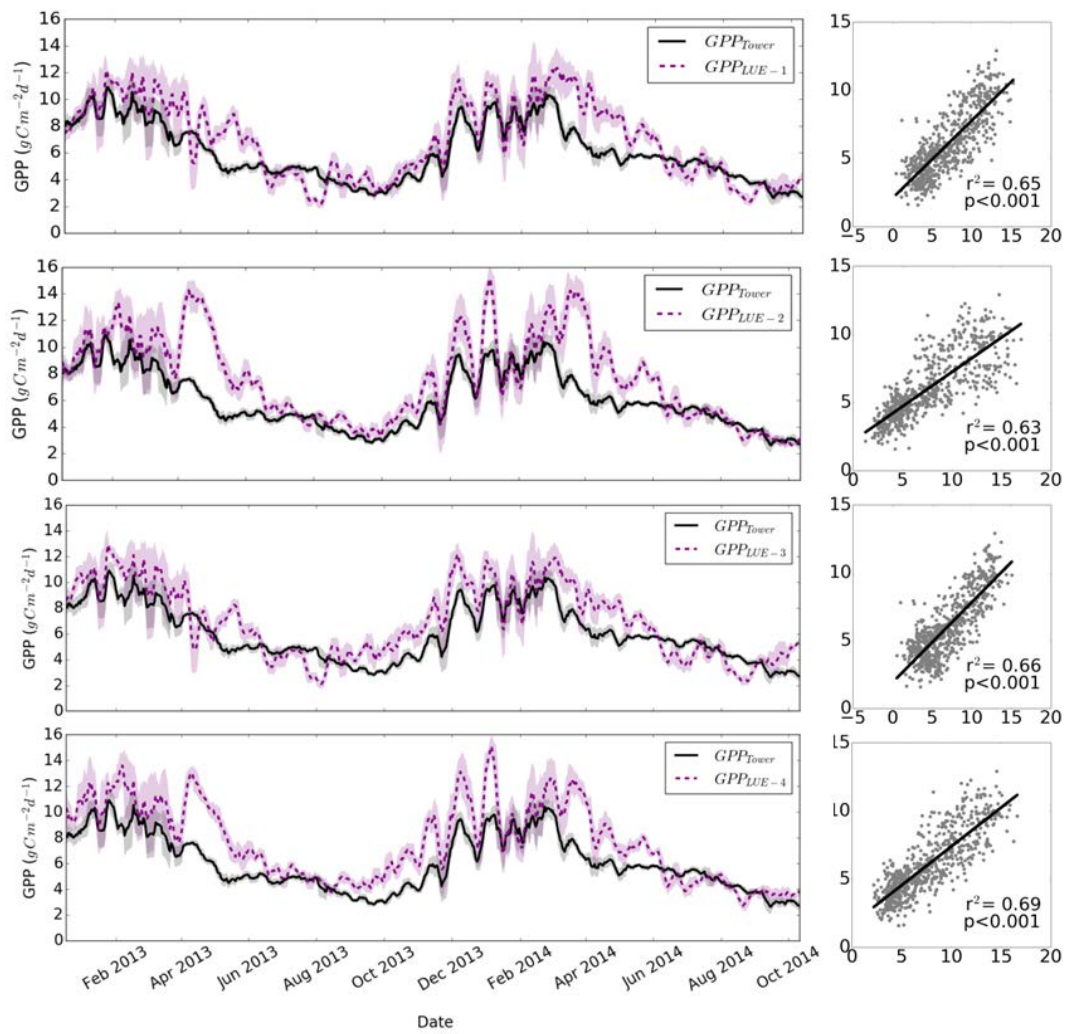


Figure 10: Ecosystem flux tower estimated GPP with model predicted GPP for the Howard Springs OzFlux site. Models shown are a) light use efficiency (LUE-1), b) LUE with evaporative fraction (EF, LUE-2), c) LUE with MODIS enhanced vegetation index (EVI, LUE-3), d) and LUE with EF and EVI (LUE-4).