

1 **Supplemental Material**

2 **S1. Watershed and soil attributes**

3 **S1.1 Extent of wetlands and lakes**

4 Estimates of lake and wetland cover were extracted from the Province of British
5 Columbia Terrestrial Ecosystem Mapping (TEM) (Green, 2014; Gonzalez Arriola et al., 2015).
6 The estimate of wetland cover is derived by combining the cover of nine ecosystem classes
7 typically considered to have wet (hygric to subhydryc) to very wet (hydric) soils, including
8 blanket bogs, bog woodlands, basin bogs, fens and swamps (Banner et al., 1993, MacKenzie and
9 Moran, 2004). This metric omits the widespread bog forests of Calvert and Hecate Islands,
10 which have very moist (subhygric) to wet soil moisture regimes (Banner et al., 1993) and are
11 transitional between upland and wetland ecosystems. The TEM dataset has polygons containing
12 up to three ecosystem classes, with no information on the location of classes within polygons.
13 Where TEM a polygon was intersected by watershed boundaries, we assumed a homogenous
14 distribution of ecosystem classes within the polygon. After summing the cover of wetlands in
15 each watershed we calculated the percentage of land (watershed area less lakes) covered by
16 wetlands.

17 **S1.2 Soil sampling and depth predictions**

18 Soil data were collected at a total of 353 field sites. Of these sites, 322 were located at
19 fixed distances along transects established using a conditioned latin hypercube sampling design
20 (Minasny and McBratney, 2006). The transect method was adopted because access on this
21 remote island is restricted, and it was not possible to visit all of the points identified in the
22 original hypercube procedure. The effect was to have small clusters of points that were well -
23 distributed and representative of the study area. At all sites, the thickness of organic horizons,

24 thickness of mineral horizons, and total soil depth to bedrock were recorded, along with
25 observations needed for categorization according to the Canadian System of Soil Classification
26 (Soil Classification Working Group, 1998) and the British Columbia terrain classification
27 (Howes and Kenk, 1997). For some sites, total depth exceeded the reach of sampling tools, so
28 recorded thicknesses were likely conservative. Data were also collected at an additional 31 sites
29 that were located in previously established ecosystem inventory plots with the same soil
30 attributes (Giesbrecht et al., 2015). In addition to field-sampled points, 40 sites with exposed
31 bedrock (0cm soil depth) were located using aerial photography.

32 Total organic horizon thickness, total mineral horizon thickness, and total soil depth were
33 combined with a suite of topographic, vegetation, and remote sensing data for each sampling
34 point, and the resulting dataset was used to train a random forest model (randomForest package
35 in R; Liaw and Wiener, 2002) which predicted soil depth values and soil/terrain types for all
36 points on the landscape. Depth predictions represent a modification of the procedure used by
37 Scarpone et al. (2016) for depth predictions in interior British Columbia.

38 **S2. Hydrology- Rating curve calculations of stream discharge and error analysis**

39 **S2.1 Stage Measurements**

40 Stations were installed in the spring and early fall of 2014 as part of a telemetry network
41 allowing for near real time download of data. At each station, an OTT PLS – L (OTT 2016)
42 pressure transducer (0 - 4 m range SDI-12) was installed. Each sensor was connected to a
43 CR1000 (Campbell Scientific, 2015) data logger. Stage measurements were recorded every five
44 minutes with a five second sampling interval and mean, max, min and standard deviation of
45 stream stage recorded over each five minute period. Each watershed also had stand-alone
46 Odyssey Capacitance Water Level recorder (Data Flow Systems PTY Ltd 2016) installed in

47 proximity to the pressure transducer to act as a back-up in case of sensor or data logger
48 malfunction.

49 **S2.2 Discharge Measurements**

50 Stream discharge was measured using multiple methods. Low and moderate flows,
51 generally below $0.5 \text{ m}^3 \text{ s}^{-1}$, were measured using the velocity area method midsection discharge
52 equation (ISO, 1992; ISO, 1997). The flow velocities were measured with the Swoffer 2100
53 propeller type mechanical current meter (Swoffer Instruments Inc., Seattle, USA) or the Sontek
54 Flowtracker acoustic doppler velocimeter (SonTek, San Diego, USA). Flow velocities were
55 averaged by the Swoffer over a five second measurement interval and by the Flowtracker over a
56 30 second measurement interval for each location. A suitable river cross-section site was defined
57 by: a) general flow direction perpendicular to the cross-section line, b) uniform stream bed
58 conditions, and c) constrained flow conditions with no back eddies and low turbulence.
59 At some watersheds, multiple velocity-area sites were used depending on conditions at time of
60 measurement.

61 At flows greater than $0.5 \text{ m}^3 \text{ s}^{-1}$, salt dilution was the primary method to measure
62 discharge, specifically salt in solution (“salt solution”) as described by Moore (2005). Discharge
63 was calculated using the following formula:

$$64 \quad Q = \frac{V}{\sum RC_t \cdot t_{\text{int}}} \quad (4)$$

65 where V represents the volume of salt solution (m^3), RC_t the relative concentration of salt
66 solution (mL mL^{-1}) and t_{int} is the time interval of measurement. RC_t is obtained using a relative
67 concentration, related to electrical conductivity (EC):

$$68 \quad RC_t = (EC_t - EC_0) \cdot CF \quad (5)$$

69 where EC_t is the temperature corrected EC measured at time t ($\mu\text{S cm}^{-1}$), EC_0 is the baseline
70 conductivity of the stream ($\mu\text{S cm}^{-1}$) defined as the five minute average prior to the salt wave,
71 and CF is the calibration factor. The end of the salt wave was defined as the point in which the
72 five minute EC average equaled EC_0 . In some instances the post-five minute average would not
73 return to EC_0 due to changes in background chemistry not associated with the salt dump. When
74 this occurred, EC_0 was determined by linear interpolation for baseline EC, pre and post
75 measurement.

76 The CF is defined as the relationship between additions of primary solution (made up of
77 salt solution and stream water) to a known volume of secondary solution (stream water only),
78 with the resulting slope of the line corresponding to the CF value. The primary solution was
79 typically made up of 10 mL salt solution (used in discharge measurement) added to 1000 mL of
80 stream water. Then, 2 or 5 mL increments of the primary solution was pipetted into 3000 mL of
81 the secondary solution, and corresponding changes in EC were recorded. Linear regression was
82 performed to determine slope of the line.

83 Due to difficulties associated with being on location to measure high discharge, a “salt
84 dilution system” was designed using the salt solution method described above. The system was
85 entirely automated and located within an extensive telemetry network enabling remote activation
86 off-site or through pre-programmed stream stages where discharge measurements had not been
87 previously measured.

88 A volume of salt solution, stored in two, 200 L barrels on site, allowed for up to thirty
89 measurements between refills. Recharging of the salt solution reservoir was done manually and
90 the CF completed following the refill and prior to the next refill (the reservoir was designed to
91 ensure that at least 5 L of solution remained after the final discharge measurement), for a

92 minimum of two CF's between refills. When the water level reached a predefined stage, a signal
93 was sent to release a pre-determined volume of salt solution from a reservoir connected to the
94 salt solution storage barrels. To increase the accuracy of this volume, the salt solution was first
95 pumped into a stainless steel cylinder with a pressure transducer at the bottom to measure water
96 depth, and in turn volume. The solution was then transferred to a dumping mechanism located
97 above the stream designed for near instantaneous release. Upon initiation of the salt solution
98 dump sequence, a second command was sent to a downstream data logger to activate two Global
99 Water-WQ Cond sensors (Global Water instrumentation, Inc., College Station, USA) to measure
100 EC_t at one second intervals, and therefore capture the passing salt wave. Once the dump
101 sequence was completed, the EC_t data were transmitted via the telemetry network to a server
102 accessed via the internet. The volume of salt depended on estimated discharge measurements,
103 with maximum EC measurements targeted to be no more than 40 uS above background, well
104 below the most sensitive toxicity threshold of 400 mg L⁻¹ (Moore 2004a, 2004b).

105 **S2.3 Error and uncertainty analysis**

106 **S2.3.1 Discharge measurement error analysis**

107 Errors associated with manual direct discharge measurements were estimated using
108 statistical techniques and on-site observations. For the velocity-area method, discharge
109 uncertainty was calculated using the Interpolated Variance Estimator (IVE) (Cohn et al., 2013).
110 For the salt dilution method, a statistical and site specific uncertainty estimation method was
111 developed.

112 **S2.3.2 Uncertainty analysis for the velocity-area measurements**

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114 As described in Cohn et al. (2013), the IVE was used to estimate uncertainty in velocity
115 area discharge measurements. It is based on the assumption that depth and velocity vary

116 gradually across a channel cross-section and that depth and velocity vary linearly between
 117 adjacent stations. The difference between the assumed and the measured value is used to
 118 calculate measurement uncertainty. In addition, uncertainties associated with calibration and
 119 systemic errors in the width, depth, and velocity were assumed to be 1% for the Sontek
 120 Flowtracker (the accuracy of the device calibration; Sontek/YSI, 2007) and 5% for the Swoffer
 121 current meter, due to increased potential uncertainty from the shorter time interval used to
 122 determine average velocity. Total uncertainty was estimated based on the above uncertainties
 123 and the number of measurement stations (see Cohn et al. 2013).

124 **S2.3.3 Salt dilution discharge uncertainty**

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 126 The discharge uncertainty for salt dilution measurements was estimated using the
 127 sensor resolution, calibration errors, salt volume errors, and salt mixing errors. Uncertainty (u_Q),
 128 associated with discharge calculated from a conductivity sensor is based on the following:

$$129 \quad u_Q = u_v + \frac{\sum_{i=1}^m ((u_{EC,i} + u_{CF}) C_i)}{\sum_{i=1}^m C_i} \quad (6)$$

130
 131 Where u_v is the relative uncertainty due to salt volume error (%), $u_{EC,i}$ is the relative uncertainty
 132 in EC measurement i due to the resolution of the sensor (%), u_{CF} is the relative uncertainty in CF
 133 (%), C_i is the calculated salt concentration at measurement i ($g\ m^{-3}$), and m is the total number of
 134 EC measurements.

135 Error associated with determining the volume of salt (u_v) was estimated by:

$$136 \quad u_v = \frac{\Delta v}{v} \cdot 100 \quad (7)$$

137 where V is the volume of salt solution released to the stream (L), and ΔV is the estimated error in
 138 salt solution volume (L). The error in solution volume was estimated based on the resolution (1
 139 mm) of the pressure transducer inside the stainless steel cylinder salt dump reservoir. With an

142 uncertainty of 0.5 mm in solution height inside the cylinder and a cylinder diameter of 304 mm,
143 the uncertainty in solution volume for each release was 36.3 mL. Because the cylinder was never
144 completely emptied, two level measurements were made to calculate water, thus total maximum
145 error in solution volume (ΔV) was 72.6 mL.

146 Electrical conductivity measurement uncertainty (u_{EC}), dependent on the resolution of
147 the conductivity sensor (Res) is described below:

$$u_{EC} = \frac{0.5 \cdot Res}{EC} \cdot 100 \quad (8)$$

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150 Uncertainty related to u_{CF} was a function of the errors associated with the measurement
151 of salt concentration of the primary and secondary solution, a combination of volumetric error of
152 the primary solution (± 0.3 mm, volumetric flask precision), the secondary solution (± 3.0 mm
153 volumetric flask precision plus rain splash and field conditions) and each primary solution dose
154 (0.006 mL, based on precision of the pipette) added in 2 or 5 mL increments. Uncertainty of the
155 CF was derived from the maximum variation in slope, a product of the salt concentration error
156 ranges. The calibration regression curve was plotted using three data points for each conductivity
157 measurement: the assumed salt concentration, the assumed salt concentration plus maximum
158 error, and the assumed salt concentration minus maximum error (Figure S2.1). Next, the
159 maximum variation of slope was calculated using the standard deviation of slope (σ_s):

$$\sigma_s = \sqrt{\frac{\left(\frac{1}{n-2}\right) \sum_{i=1}^n (y_i - \hat{y}_i)^2}{\sum_{i=1}^n (x_i - \bar{x})^2}} \quad (9)$$

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161 where n is the number of data points, y_i is the assumed salt concentration (\pm error) of
162 measurement i (mL mL^{-1}), \hat{y}_i is the modelled salt concentration (mL mL^{-1}), x_i is the measured
163 electrical conductivity of measurement i ($\mu\text{S cm}^{-1}$), and \bar{x} is the mean average electrical
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165 conductivity ($\mu\text{S cm}^{-1}$). Finally, the CF relative uncertainty (u_{CF}) was defined as two times the
166 standard deviation of slope divided by the CF:

$$167 \quad u_{\text{CF}} = (2 \cdot \sigma_s) / \text{CF} \quad (10)$$

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169 If the EC sensors showed different EC readings and confirmed the salt was not
170 completely mixed at the measurement site, additional uncertainty was added to the discharge
171 measurement. To measure the degree of salt mixing at the measurement site, discharges
172 calculated from both conductivity sensor measurements were compared, while taking their
173 uncertainties into account:

$$174 \quad M = \frac{(Q_2 - \varepsilon_{Q_2}) - (Q_1 + \varepsilon_{Q_1})}{(Q_1 + \varepsilon_{Q_1})} \cdot 100 \quad (11)$$

175 where M is the relative uncertainty due to improper mixing (%), Q1 is the lower discharge value
176 ($\text{m}^3 \text{s}^{-1}$), Q2 is the higher discharge value ($\text{m}^3 \text{s}^{-1}$), ε_{Q_1} is the absolute uncertainty of the lower
177 discharge value, derived from u_Q (Equation 6) and ε_{Q_2} is the absolute uncertainty of the higher
178 discharge value. If $M \leq 0$, the salt was assumed to be properly mixed. Any positive outcome of
179 M implies incomplete mixing and is added to the total uncertainty of the discharge measurement.
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181 **S2.4 Rating curve development and uncertainty**

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183 Discharge is related to stage through the formula:

$$184 \quad Q = a(h - h_0)^b \quad (12)$$

185 where Q is discharge ($\text{m}^3 \text{s}^{-1}$), h is stage level (m), h_0 is the water level at zero flow (m) and a and
186 b are coefficients specific to the gauging station of a river. The values for h_0 , a, and b are
187 obtained by the curve fitting results of simultaneous stage and discharge measurements. For this
188 work, stage-discharge curves were created using a non-linear least-squares fitting Python model
189 (lmfit; LMFIT Development Team, 2015). This model approximates the variables (a, b, and h_0)
190 by minimizing the residuals scaled by data uncertainties:

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$$[Q_i^{\text{meas}} - Q_i^{\text{model}}(v)]/\varepsilon_i \quad (13)$$

192 where Q_i^{meas} is the measured discharge ($\text{m}^3 \text{s}^{-1}$), Q_i^{model} is the fitted discharge ($\text{m}^3 \text{s}^{-1}$), v the set
193 of variables in the model (a , b and h_0) to be optimized, and ε_i the uncertainty in the discharge
194 measurement. This was a two step process where the curve was first fit taking into account
195 uncertainties related to Q and then fit again taking into account uncertainties in h .

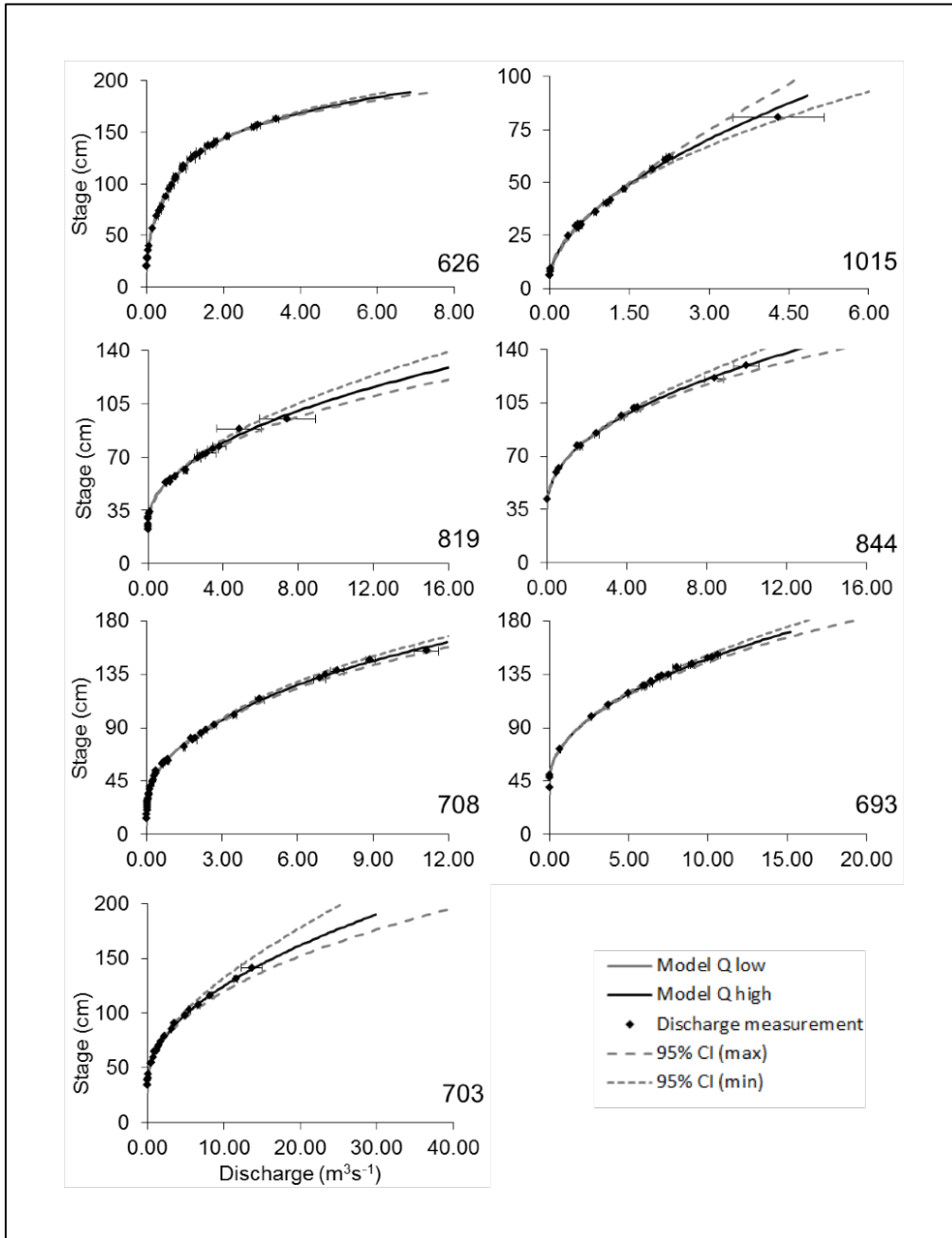
196 As described above, uncertainty for individual discharge measurements were accounted
197 for in the curve fitting process, with measurements of greater uncertainty having less influence
198 on position of the curve. To account for uncertainty in the stage discharge relation, 95%
199 confidence intervals were created per Herschy (1994) and applied to the final discharge times-
200 series as an estimate of discharge.

201 **S2.5 Results of stream discharge measurement and calculations**

202 A total of 168 total measurements, including 92 measures made using the automated
203 system, were used to develop rating curves for each watershed (Figure S2.1; Floyd et al., 2016).
204 Watershed 703 had the highest total discharge over the study period, which was more than the
205 combined total from watersheds 626, 819, 844 and 1015. Total discharge calculated from the
206 95% confidence intervals from the rating curves were $\pm 6.5\%$ of the mean of all watersheds, with
207 a range between $\pm 2.93\%$ (708) and $\pm 9.98\%$ (819) (Table S2.3). In general, discharge data from
208 watershed 708 had the lowest uncertainty, due to it having the most discharge measurements and
209 the best developed rating curve. Watershed 819 had the highest uncertainty largely due to the
210 limited number of high flow discharge measurements on the rating curve (max measured was 4.5
211 $\text{m}^3 \text{s}^{-1}$) and variation in stage during the discharge measurements at high flow. Four of the seven
212 watersheds had total discharge measurements less than $\pm 5.0\%$ of the estimated measurements

213 from the rating curve, and none were > 10% for the entire project study period, however for
214 water year 2015/2016, 819 had a total discharge uncertainty of ±13.0%.

215 **Figure S2.1.** Stage discharge rating curves for seven focal watersheds. Confidence intervals
216 (95%) are calculated based on Herschy (1994). Error bars represent uncertainty from individual
217 measurements.



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222 **Table S2.3.** Uncertainty (%) in total discharge, by water year and over the entire study period,
 223 based on rating curve confidence intervals (95%). Values are plus or minus the modelled output.
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<i>Watershed</i>	<i>2014-15</i>	<i>2015-16</i>	<i>2014-2016</i>
626	5.57	5.54	5.55
693	3.35	2.97	3.19
703	10.14	9.37	9.83
708	2.93	2.93	2.93
819	7.49	13.01	9.98
844	4.98	4.47	4.78
1015	9.01	8.58	8.84

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S3. Generating model estimates of DOC flux using rloadest

Table S3.1: The number of samples and specific regression model used by rloadest for calculating stream loads. Estimated bias of each model shows relatively low overall bias for each model, with 844 clearly showing the highest bias.

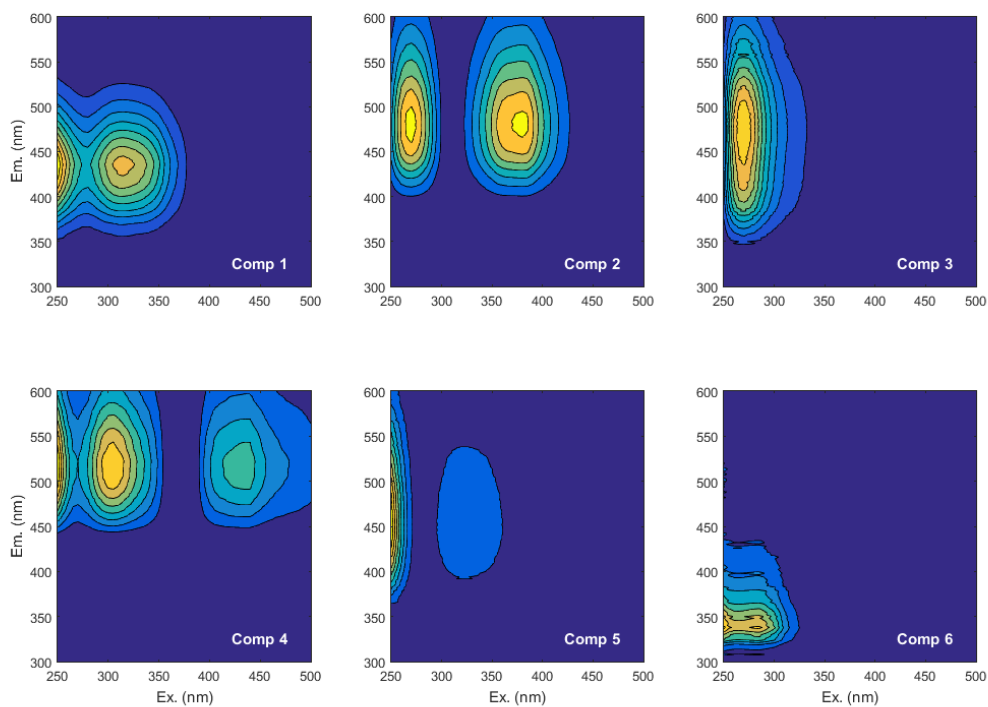
Watershed	n	Model #	Regression model	Estimated % bias
626	23	7	$a_0 + a_1 \ln Q + a_2 \sin(2\pi dtime) + a_3 \cos(2\pi dtime) + a_4 dtime$	2.026
1015	24	7	$a_0 + a_1 \ln Q + a_2 \sin(2\pi dtime) + a_3 \cos(2\pi dtime) + a_4 dtime$	-2.502
819	23	7	$a_0 + a_1 \ln Q + a_2 \sin(2\pi dtime) + a_3 \cos(2\pi dtime) + a_4 dtime$	2.011
844	20	3	$a_0 + a_1 \ln Q + a_2 dtime$	-11.49
708	24	6	$a_0 + a_1 \ln Q + a_2 \ln Q^2 + a_3 \sin(2\pi dtime) + a_4 \cos(2\pi dtime)$	-0.206
693	23	6	$a_0 + a_1 \ln Q + a_2 \ln Q^2 + a_3 \sin(2\pi dtime) + a_4 \cos(2\pi dtime)$	0.092

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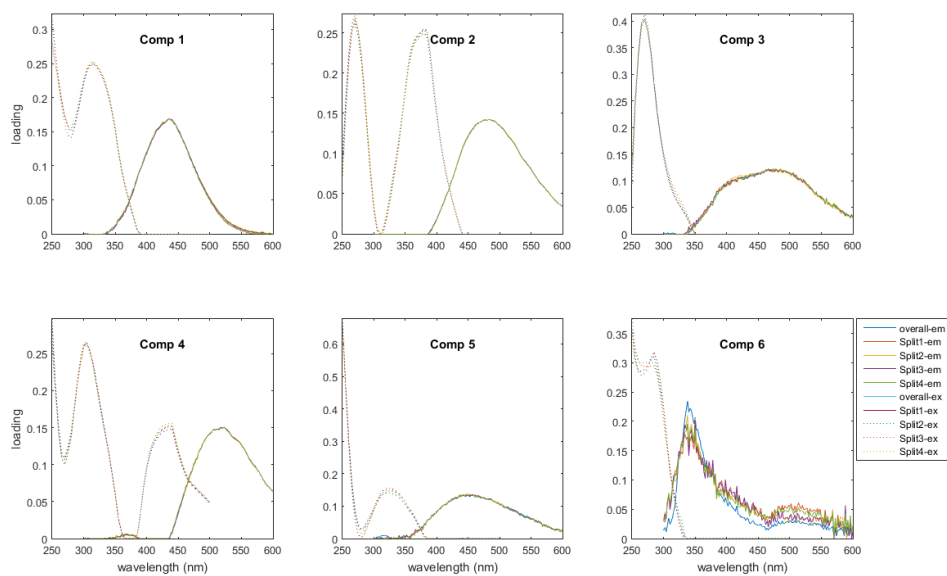
S4. PARAFAC Modeling of DOM composition

Figure S4.2: Fingerprint map showing the six fluorescence components determined by PARAFAC analysis.

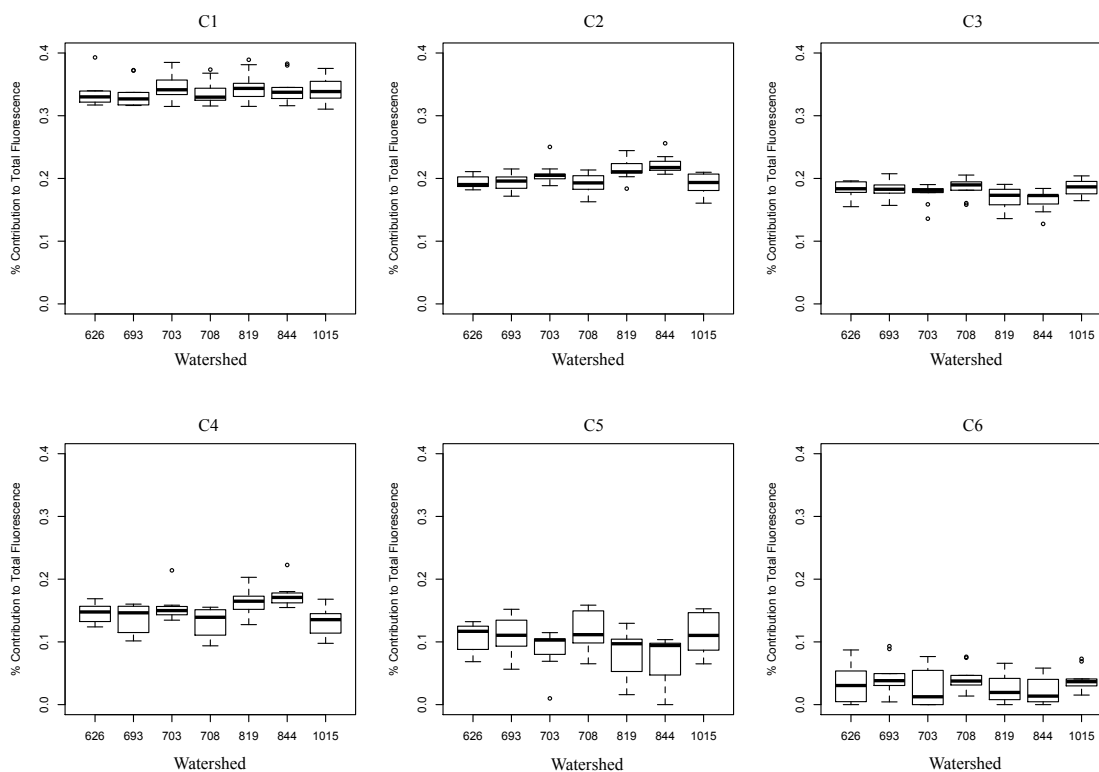


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Figure S4.3: Split half validation plots for the six fluorescence components determined by PARAFAC analysis.



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 261 **Figure S4.4:** Box plots showing the percent contribution to total fluorescence from each of the six components determined by PARAFAC analysis for each of the seven watersheds used in this
 262 study.
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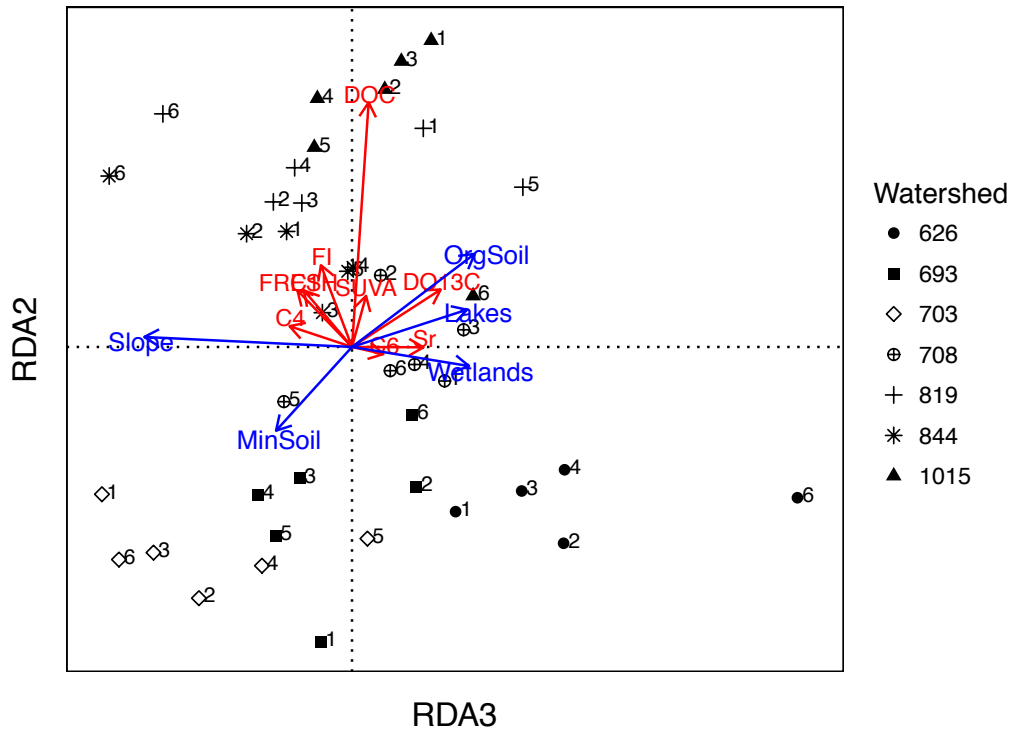
Table S4.1: Locations of maximum fluorescence values and the corresponding excitation and emission wavelengths for each of the six peaks (components) determined with PARAFAC modelling.

Component	Excitation (nm)	Excitation F_{\max}	Emission (nm)	Emission F_{\max}
1	315	0.2502	436	0.1688
2	270	0.2607	484	0.1422
	380	0.2539		
3	270	0.4125	478	0.1212
4	305	0.2648	522	0.1504
	435	0.1512		
5	325	0.1408	442	0.1321
6	285	0.3108	338	0.2350

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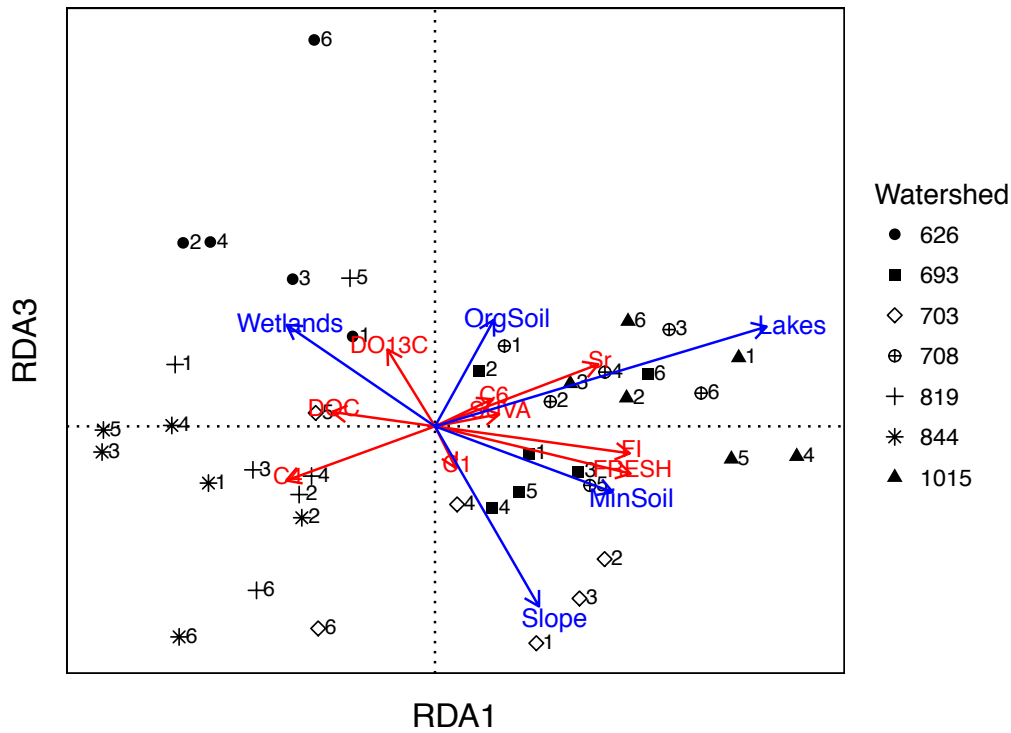
S5. Redundancy analysis: Relationships between watershed characteristics and DOC exports

275 **Figure S5.1:** Partial-RDA Axis 1 versus Axis 3. RDA was performed under type 2 scaling.



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Figure S5.2: Partial-RDA Axis 2 versus Axis 3. RDA was performed under type 2 scaling.



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Table S5.3: Relative eigenvalues and the statistical significance of each axes in the partial-RDA.

Axis	Eigen -value	F marginal	F forward	P- marginal	P- forward	% total variance in Y	% total variance explained by all axis
1	1.420	18.717	11.047	0.0001	0.0001	15.78	47.3
2	0.902	11.887	9.158	0.0001	0.0001	10.02	30.1
3	0.654	8.622	8.531	0.0002	0.0002	7.27	21.8
4	0.013	0.175	0.175	1.0000	1.0000	0.15	0.4
5	0.011	0.143	0.143	0.9965	0.9965	0.12	0.4

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Table S5.4: Results of permutation test on the marginal effects of terms given under the reduced RDA model.

	df	Variance	F	Pr (>F)
Lakes	1	1.093	6.4789	0.001
Slope	1	0.5722	3.392	0.005
Wetlands	1	0.1207	0.7153	0.651
MinSoil	1	0.8403	4.9807	0.001
OrgSoil	1	0.6937	4.1118	0.001
Residual	34	5.7359		

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Table S5.5: Biplot scores for partial-RDA axes using type 2 scaling.

	Axis1	Axis2	Axis3	Axis4	Axis5
Lakes	0.8471	0.1028	0.4853	-0.1871	0.0349
Slope	0.2658	0.0275	-0.8769	-0.0410	0.3825
Wetlands	-0.3789	-0.0527	0.4940	0.4033	-0.6664
MinSoil	0.4540	-0.2311	-0.3205	0.1128	0.7905
OrgSoil	0.1503	0.2569	0.5178	0.3138	0.7341

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