

Trend analysis of the airborne fraction and sink rate of anthropogenically released CO₂

Author response, Review 2

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1 Introduction

We thank the Referee for the constructive comments on the first revision of our paper. Our replies are given below. For each item, we reproduce (a slightly paraphrased version of) the comments of the Referee, followed by our response in which we indicate how and where the paper has changed. All quoted page and line numbers (“PX, LY”) refer to the newly revised version of the paper, with the changes tracked.

2 Referee report

2.1 Comment 1

First, a state-space regression using the full-year time-series need to be adressed using a Cook’s distance to see how far the slope of the fit will be affected by the data sampling.

10 2.2 Response to Comment 1

We have carried out the analysis as suggested by the Referee. The analysis for detecting potential influential data points has been conducted by (1) calculating Cook’s distance on the basis of sequentially leaving one observation out from the sample, and (2) estimating the slope parameter β on the same basis, by sequentially excluding the t -th observation from the full sample, for $t = 1959, 1960, \dots, 2016$. We may conclude from this two-fold analysis that none of the observations are especially influential: indeed, while Cook’s distance for the observation at $t = 1974$ is relatively much larger when compared to all $t \neq 1974$, it is still small in absolute terms. Similarly, the estimates of β obtained from leaving out the t ’th observation are very stable, also for $t = 1974$, and are in all instances well inside the 95% confidence bands of the full sample estimate.

The details of these investigations are included at the end of this Response, in Figures 1–4. For completeness, we also have included this graphical output in Sect. 2.1 of the Supplementary Material file. The conclusion from these analyses (as indicated above) are mentioned in the Discussion section of the main paper (P14, L26).

2.2.1 Changes made to the paper in response

- 5 We have included the two analyses as indicated by (1) and (2) above: Cook’s distance measures and slope parameter β estimates in Sect. 2.1 of the Supplementary Material file. We discuss the results of these analyses (along the lines as given above) in the Discussion section of the main paper (P14, L26).

2.3 Comment 2

10 *Then, futher discussion are needed to compare trends in air-borne fraction of CO2 and in carbon sink to know/best estimates of year-to-year variability (and infered/assumed decadal variability). I mean: while your model detect a significant changes in sink rate, can we detect it in the real world given the amplitude of the year-to-decadal variability ? (please refer to the published scientific literature where possible)*

In a situation where it doesn't, futher comparison with Gloor et al findings seems necessary.

2.4 Response to Comment 2

- 15 We have extended our discussions of the estimated trends in the airborne fraction of CO2 and in the carbon sink (P14 and P15, cf. our comments below).

Our point of departure is precisely the fact that it is rather challenging to determine whether a trend is present due to the relatively large year-to-year variability.

- 20 We ask the questions whether a trend is present, whether it is deterministic (linear) or stochastic (random walk) and what the degree of measurement noise is. Our model thus resolves the high degree of year-to-year variability and allows to distinguish non-stationary processes (trend-stationary or difference-stationary) from stationary processes.

We have adopted the local linear trend model, since this basic time series model can encompass and resolve these different processes. As an additional benefit, even when the year-to-year variability in the airborne fraction and in the carbon sink originate from different processes, we have a common modeling structure.

- 25 Because year-to-year variability is high and a stochastic trend with its own source of randomness over and above the stationary measurement noise may cloud the picture further, it is desirable to use as much data as possible to detect a latent trend. It is another advantage of our model, in equation (15), that it allows to accommodate multiple data sources for the same object of interest, here the sink rate that is alternatively measured by (1) data generated from ocean and land sink models, and (2) from emission and atmospheric concentration data. Our reported estimates of the slope parameter β are thus directly supported from
30 two different ways to compute the sink rate.

In the case of the carbon sink rate and a single common trend for the two alternative measurements, equation (15) reduces very closely to a standard linear trend regression estimate, since the maximum likelihood estimate of the variance in the stochastic trend component is almost zero. In this case, the slope parameter β is directly estimated from the year-to-year variation in the two different time series. Hence this result is close to the one from a standard trend regression, albeit with support from two different time series.

We believe that the reported results in our paper support the point, put forth in Gloor et al., that the behavior of the airborne fraction and the sink rate are NOT in a one-to-one correspondence. (Specifically, the point made in Gloor et al. is that findings of an increasing airborne does not necessarily imply that the sink rate is declining.) We now emphasize this more in the Discussion section (P14, L11-13 and P14, L33 – P15, L3). Note, however, that our findings also support those made by Le Quere et al., namely that the sink rate does, in fact, appear to be decreasing.

2.4.1 Changes made to the paper in response

The Discussion section (P14, L11-13 and P14, L33 – P15, L3) has been updated as noted above.

2.5 Comment 3

Finally, regarding the model forecast: how does your model compare to a simple persistence fit (based on a first-order regression processes)?

I would like to stress that further discussion could be usefull in regards of the model forecast: Does your model give an idea of a possible emergence of the climate change signal from the year-to-year variability ? This would help to liase this work with the published literature on climate-carbon cycle feedbacks.

2.6 Response to Comment 3

In the forecasting exercise, we now include the forecasts from a first-order autoregressive process (AR1).

The model results of the paper imply that the sink rate is linearly decreasing in time; the forecasting exercise illustrates how the sink rate will develop in the future under the assumption of the model. For instance, if the model is correct, in approximately 15 years, the sink rate will have declined below 2% (P10, L16). This has important implications for our understanding of the carbon-cycle: it indicates that the ability of the sinks to soak up CO₂ is decreasing, in relative terms. However, our main point is not that the sink rate will necessarily be declining with the same linear rate in the future. Our main point is that the sink rate *has been decreasing over the time period considered in the paper*. The purpose of the forecasting exercise conducted in the paper is mainly for diagnostic purposes: Does the forecasts from the model look reasonable? How can we expect the future sink rate to develop, if the model continues to be a good representation of the underlying physical processes? As such, the forecasts should not be seen as a bona fide prediction, but only as an indication of what we can expect of the sink rate, as long as it is approximately linear in concentrations (an assumption which seems to hold in the time period considered in the paper, but which might be violated in the future, cf. Appendix A in the main paper).

2.6.1 Changes made to the paper in response

Forecasts from an AR1 model is included in Fig. 3 (P12); some comments on this are included on P11 (L4-8).

A discussion of the forecasts and their limitations has been included in the main paper (P11, L9-15).

3 Additional changes

- 5 1. The description of the terms from Global Carbon Budget has been revised (P3).

References

Figure 1. Cook's distance of each observation from the state-space model of the airborne fraction.

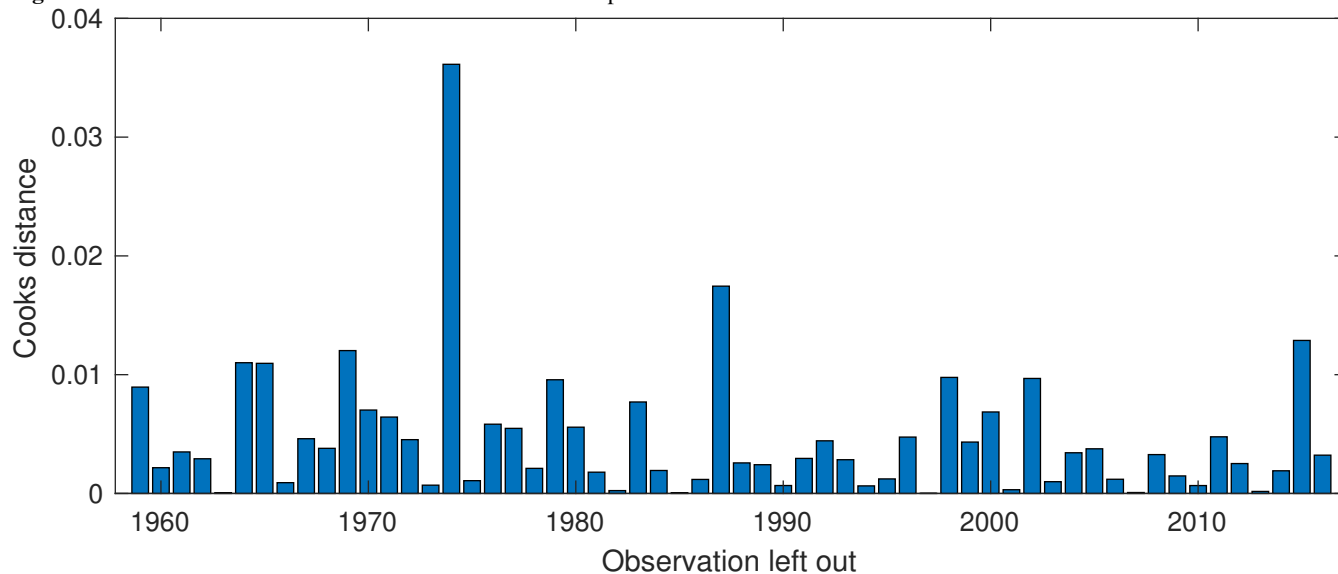


Figure 2. Estimates of slope parameter β from the state-space model of the airborne fraction after leaving out one observation. Dashed lines are 95% confidence bands for the full sample estimate.

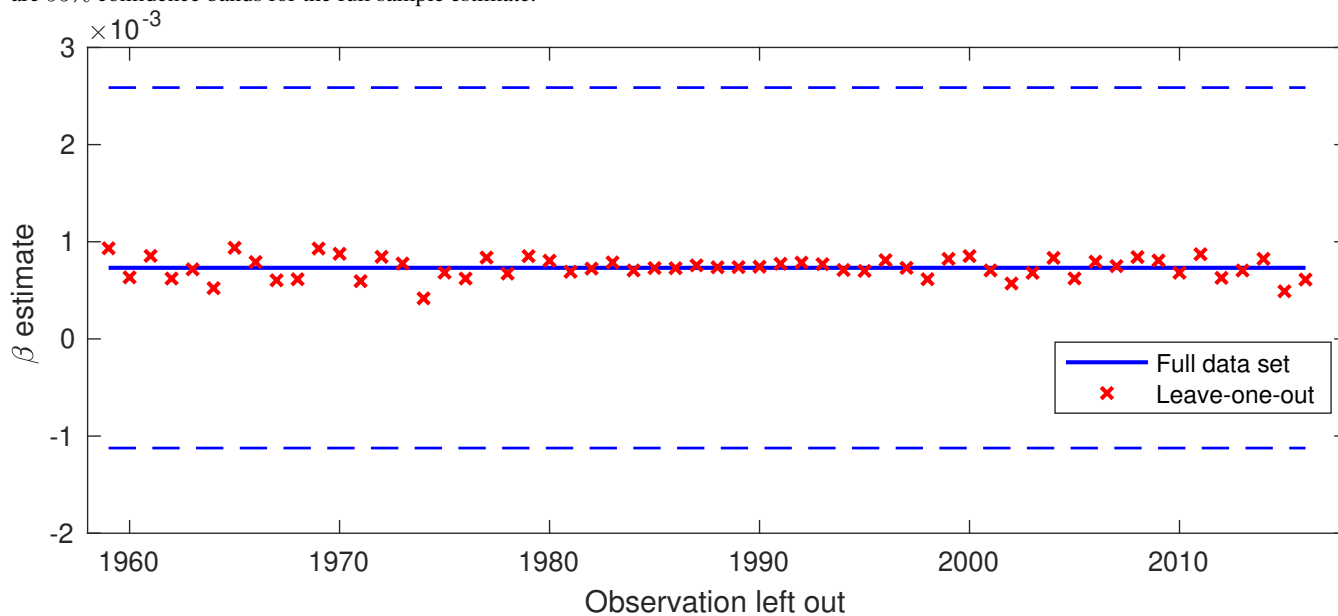


Figure 3. Cook's distance of each observation from the state-space model of the sink rate.

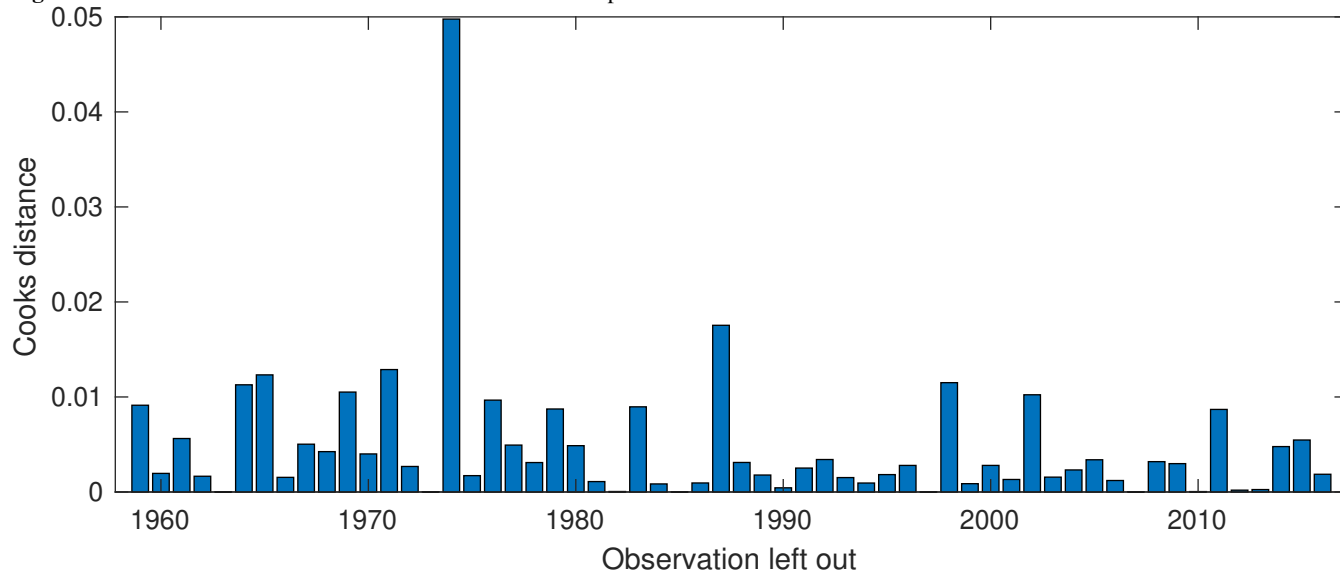
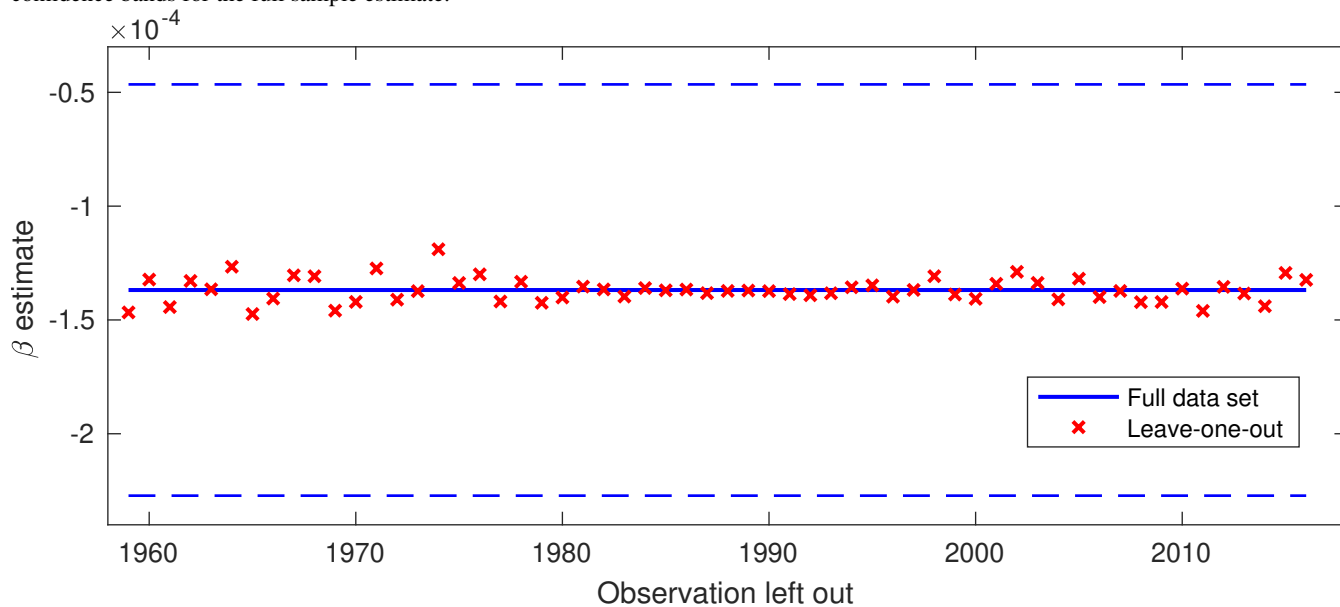


Figure 4. Estimates of slope parameter β from the state-space model of the sink rate after leaving out one observation. Dashed lines are 95% confidence bands for the full sample estimate.



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Abstract. Is the fraction of anthropogenically released CO₂ that remains in the atmosphere (the airborne fraction) increasing? Is the rate at which the ocean and land sinks take up CO₂ from the atmosphere decreasing? We analyze these questions by means of a statistical dynamic multivariate model, from which we estimate the unobserved trend processes together with the parameters that govern them. We show how the concept of a global carbon budget can be used to obtain two separate data series measuring the same physical object of interest, such as the airborne fraction. Incorporating these additional data into the dynamic multivariate model increases the number of available observations, thus improving the reliability of trend and parameter estimates. We find no statistical evidence of an increasing airborne fraction but we do find statistical evidence of a decreasing sink rate. We infer that the efficiency of the sinks in absorbing CO₂ from the atmosphere is decreasing at approximately 0.54% per year.

10 *Copyright statement.* TEXT

1 Introduction

A part of the anthropogenically released CO₂ emitted to the atmosphere flows to the oceans (the ocean sink) and the terrestrial biosphere (the land sink). Approximately 45% of released CO₂ stays in the atmosphere (the airborne fraction), while the two sinks take up approximately 24% and 31% of the CO₂, respectively. (These percentages are calculated over the period 1959 to 2016 using the data described below, see e.g. Raupach et al., 2014, for similar estimates.) A key question is whether the airborne fraction is increasing or if it remains constant at around 45%. An increasing airborne fraction implies that the share of anthropogenically released CO₂ that ultimately remains in the atmosphere increases, and projections of future atmospheric CO₂ levels need to take this into account (Gloor et al., 2010). Closely related is the question whether the sinks will continue taking up CO₂ at the same rate (the sink rate) or if this rate is decreasing. A decreasing sink rate implies that the efficiency with which ocean and land sinks are absorbing CO₂ from the atmosphere is decreasing. Thus, analyzing the behavior of the sink

rate can help predict the future uptake of CO₂ through the ocean and the land sink. The answers to the questions posed above are important for our understanding of the global carbon cycle and are relevant for policy makers and the public in general.

A series of papers argue that the airborne fraction of anthropogenically released CO₂ (mainly through fossil fuel emissions, cement production, and land-use change) is increasing (Canadell et al., 2007a; Le Quéré et al., 2009; Raupach et al., 2008; 5 Rayner et al., 2015). Similarly, in Raupach et al. (2014) it is argued that, although the statistical evidence of an increasing airborne fraction is relatively weak, the evidence of a decreasing CO₂ sink rate is clearer. However, the methods in these studies have been criticized in, for example, Knorr (2009), Gloor et al. (2010), and Ballantyne et al. (2015). Indeed, by considering a longer data set and incorporating uncertainties into the data, Knorr (2009) found that the conclusion of an increasing airborne fraction was not warranted. Similarly, Ballantyne et al. (2015) argues that errors in the data can lead to erroneous conclusions 10 regarding possible trends in the airborne fraction and in the sink rate.

In this paper, we address these statistical issues within the framework of a *state-space system*. It allows us to conduct statistical inference by taking explicit account of stochastic and deterministic trends in the data, transient shocks to the data (coming from, e.g., volcanic eruptions or strong El Niño events), and (potential) measurement errors. It also allows for the simultaneous incorporation of multiple data sets for the same object, which can improve the estimation of trends and increase reliability of 15 parameter estimates. We find strong evidence for purely deterministic trends when we incorporate multiple measurements for the airborne fraction and the sink rate. These deterministic trends have a statistically significantly negative slope in the case of the sink rate and an insignificant slope in the case of the airborne fraction. These findings corroborate earlier findings in the literature, especially Raupach et al. (2014), but address the statistical concerns raised by Knorr (2009) and Ballantyne et al. (2015), among others. Finally, by analyzing the ocean and land sink rates separately, we find no evidence of a decreasing ocean 20 sink rate but we do find evidence that the land sink rate is decreasing.

The paper is organized as follows. In Sect. 2 we state the fundamental equations of the global carbon budget, the definitions of the airborne fraction of anthropogenically released CO₂, and the CO₂ sink rate, which will motivate the specification of the state-space system. Sect. 3 introduces the state-space system used in the paper. In Sect. 4 we conduct a trend analysis of the airborne fraction within the proposed statistical framework. In Sect. 5 we carry out the corresponding analysis of the CO₂ 25 sink rate, and in Sect. 6 of the land and ocean sink rates separately. Sect. 7 discusses the results and Sect. 8 concludes. A Supplementary Material file is available online.

2 The global carbon budget

The so-called *global carbon budget* is defined as

$$E_t^{ANT} = G_t + S_t^O + S_t^L, \quad (1)$$

30 where E_t^{ANT} is anthropogenically released CO₂ into the atmosphere, G_t is growth of atmospheric CO₂ concentration, S_t^O is the flux of CO₂ from the atmosphere to the oceans (the ocean sink), and S_t^L is the flux of CO₂ from the atmosphere to the terrestrial biosphere (the land sink). In words, Eq. (1) states that emissions of CO₂ should equal the fluxes of CO₂ to the

atmosphere, the ocean sink, and the land sink. We use the data set provided by The Global Carbon Project (Le Quéré et al., 2018).¹ All data are measured-given in gigatonnes of carbon (GtC) and are recorded at a yearly frequency, beginning in 1959 and ending in 2016, resulting in 58 observations for each quantity in (1).

While the carbon budget is in principle always balanced for the physical quantities, in the sense that Eq. (1) always holds, this might not be the case when inserting actual data for emissions and sinks, due to measurement errors in the data. For this reason, Le Quéré et al. (2018) introduce a residual term into the budget Eq. (1) to capture measurement error. It is denoted B_t^{IM} for *budget imbalance*. Therefore, when considering actual data, the carbon budget is defined as

$$E_t^{ANT} = G_t + S_t^O + S_t^L + B_t^{IM}. \quad (2)$$

The sample mean of the budget imbalance over the observation period is not significantly different from zero and shows no sign of a trend (Le Quéré et al., 2018). These facts are important in the developments below, since they motivate treating B_t^{IM} as part of an error term.

The growth rate in atmospheric CO₂ data, G_t , is from Dlugokencky and Tans (2018), while the the ocean sink data, S_t^O and, are obtained from an ensemble of global biochemistry models, and the land sink data, S_t^L , are averages over several independent model-based estimates, constructed as explained in Le Quéré et al. (2018) estimated as the multi-model mean of several dynamic global vegetation models. See Le Quéré et al. (2018) for further information on the data. The anthropogenic emissions of CO₂ can be decomposed in two parts:

$$E_t^{ANT} = E_t^{FF} + E_t^{LUC},$$

where E_t^{FF} are emissions from fossil fuel burning, cement production, and gas flaring, while E_t^{LUC} are emissions from land-use change. Fossil fuel emissions, E_t^{FF} , are from Boden et al. (2018), while land-use change emissions, E_t^{LUC} , are averages over the model-based estimates of of the results of the two bookkeeping models of Hansis et al. (2015) and Houghton and Nassikas (2017), updated as in Le Quéré et al. (2018). The time series of concentrations (above preindustrial levels) of CO₂ in the atmosphere is constructed as

$$C_t = 2.127 \cdot ([CO_2]_{1959} - [CO_2]_{1750}) + \sum_{\tau=1}^t G_{\tau},$$

where $[CO_2]_{1750} = 279$ ppmv (parts per million volume) and $[CO_2]_{1959} = 315.39$ ppmv are the concentrations of CO₂ in the atmosphere in 1750 and 1959, respectively; see Raupach et al. (2014). The number 2.127 is the conversion factor from ppmv to GtC. In words, the atmospheric concentration C_t above pre-industrial levels is given by the initial value in 1959 plus the cumulative sum of the growth in atmospheric CO₂ concentrations G_t , which result from the budget equation (1).

We follow Raupach (2013) and Raupach et al. (2014) and define the airborne fraction as

$$AF_t = \frac{G_t}{E_t^{ANT}}$$

¹The data are available at <http://www.globalcarbonproject.org/> and were downloaded on June 1st, 2018.

and the CO₂ sink rate as

$$k_{S,t} = \frac{S_t^O + S_t^L}{C_t}, \quad (3)$$

which is the flux of CO₂ from the atmosphere to the sinks (ocean plus land), ~~normalized~~ normalised by the amount of CO₂ (above preindustrial levels) currently in the atmosphere. We can also consider the individual components of the sink rate for

5 ocean and land, which are given by

$$k_{O,t} = \frac{S_t^O}{C_t}, \quad k_{L,t} = \frac{S_t^L}{C_t}, \quad (4)$$

respectively, with $k_{S,t} = k_{O,t} + k_{L,t}$.

The airborne fraction and the sink rate are fundamentally different quantities. The airborne fraction $AF_t = G_t/E_t^{ANT}$ is the ratio of the growth of atmospheric CO₂ in period t to the amount of CO₂ emitted in period t . It is thus a measure of the fraction
10 of emitted CO₂ that stays in the atmosphere. In contrast, the sink rate $k_{S,t} = (S_t^O + S_t^L)/C_t$ is the ratio of the CO₂ flux in the sinks in period t to the total amount of CO₂ in the atmosphere (above pre-industrial levels). By writing $S_t^O + S_t^L = k_{S,t}C_t$, we can interpret the sink rate $k_{S,t}$ as the “efficiency”, with which CO₂ flows from the atmosphere to the sinks, i.e. as the amount of CO₂ going into the sinks for an extra unit of CO₂ added to the atmosphere (Gloor et al., 2010; Raupach, 2013). We discuss the relationship between the airborne fraction and the sink rate further in Sect. 7.

15 3 Trend model specification

In this section, we consider several models for the data generating process behind observations of the objects of interest defined in Sect. 2. Common to all models is that they can be cast in a state-space system of the form:

$$\begin{aligned} y_t &= Ax_t + \xi_t, \\ x_{t+1} &= Bx_t + \kappa_t, \end{aligned} \quad t = 1, \dots, n, \quad (5)$$

where y_t is a vector of observations at time $t = 1, \dots, n$ with time series length n , and the system matrices A and B have
20 appropriate dimensions. The vector x_t is usually referred to as the state vector, which can include deterministic and stochastic trends, and the error terms ξ_t and κ_t are both independent and identically distributed (iid) random vectors of appropriate dimension and with mean zero. For example, when we need to model the airborne fraction alone, we have $y_t = AF_t$ and the state-space system represents a univariate dynamic model for the airborne fraction. When modelling the ocean and land sink rates jointly, we have $y_t = (k_{O,t}, k_{L,t})'$, and the state-space system is a bivariate dynamic model. For given matrices A and
25 B , and under the assumption of mutually and serially uncorrelated Gaussian errors ξ_t and κ_t (with their respective variance matrices Σ_ξ and Σ_κ), the state-space system is a linear Gaussian model. In such regular cases, an analytic formulation for the likelihood function is available and relies on the prediction error decomposition. Hence the parameters (variances and possibly covariances in Σ_ξ and Σ_κ) can be estimated by the maximum likelihood method. It requires the numerical optimization of the log-likelihood function that is evaluated via the Kalman filter. The resulting algorithm is initialized with specific starting

values; we use a diffuse initialization as outlined in Chapter 5 of Durbin and Koopman (2012). The smooth estimate of the state process x_t can also be obtained by means of the Kalman filter together with a smoothing algorithm. The extracted state is effectively the conditional mean $\mathbb{E}(x_t|y_1, \dots, y_n; A, B, \Sigma_\xi, \Sigma_\kappa)$, for $t = 1, \dots, n$. Details of the state-space approach are given by Durbin and Koopman (2012), where both signal extraction and maximum likelihood estimation are discussed.

- 5 Our baseline model is the local linear trend (LLT) model. For a univariate time series y_t , we treat the underlying trend T_t as a stochastic process given by

$$T_{t+1} = T_t + \beta + \eta_t, \quad (6)$$

where $\beta \in \mathbb{R}$ is a fixed and unknown coefficient and η_t is an iid Gaussian random variable with mean zero and variance σ_η^2 . The solution to the difference equation (6) is given as

$$10 \quad T_{t+1} = T_1 + t\beta + \sum_{i=0}^{t-1} \eta_{t-i}, \quad t = 1, 2, \dots, n-1,$$

where T_1 can be treated as a fixed unknown coefficient (intercept or constant) or as a random variable. The solution shows that the trend component is made up of the starting value T_1 , a deterministic linear term with slope β , and a random walk component $\sum_{i=0}^{t-1} \eta_{t-i}$. Thus, T_t can be interpreted as a long-term trend in the time series and β as the slope of the deterministic part of the trend. We also considered a time-varying slope, β_t , but found no evidence supporting this generalization in either the airborne

- 15 fraction or the sink rate. The observation equation for y_t is given by

$$y_t = T_t + \epsilon_t, \quad (7)$$

where T_t is given by (6) and ϵ_t captures deviations of the observed time series from the unobserved trend component. The deviations ϵ_t can be viewed as (i) actual (transient) disturbances of the physical systems arising from, for example, volcanic eruptions and El Niño events, and/or (ii) measurement errors arising from the way the data are collected. The random variable

- 20 ϵ_t is assumed to be iid Gaussian with mean zero and variance σ_ϵ^2 .

The local linear trend model can be cast in the state-space system (5) where vectors and matrices are defined as

$$x_t = \begin{pmatrix} T_t \\ \beta \end{pmatrix}, \quad A = \begin{bmatrix} 1 & 0 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}, \quad \xi_t = \epsilon_t, \quad \kappa_t = \begin{pmatrix} \eta_t \\ 0 \end{pmatrix},$$

for $t = 1, \dots, n$. The state vector x_t consists of the two variables of interest: stochastic trend variable T_t and deterministic slope variable β . The state-space methods as discussed above can treat such mixed compositions of the state vector. We have

25 illustrated how the state-space system can be used for a univariate time series. In the next sections, we also consider trend analyses based on multivariate time series models.

4 Trend analysis of the airborne fraction

It follows immediately from Eq. (2) that we can measure the airborne fraction AF_t in two alternative ways:

$$AF_t^{(1)} = \frac{G_t^{ATM}}{E_t^{ANT}}, \quad AF_t^{(2)} = \frac{E_t^{ANT} - S_t^O - S_t^L}{E_t^{ANT}} = AF_t^{(1)} + \xi_t, \quad (8)$$

where $\xi_t = B_t^{IM}/E_t^{ANT}$, since $E_t^{ANT} - S_t^O - S_t^L = G_t + B_t^{IM}$. Although the two quantities in (8) measure the same underlying object (the airborne fraction AF_t), they differ in practice, because of a non-zero budget imbalance, i.e. $\xi_t \neq 0$. Our statistical analysis implies that ξ_t is a well-behaved zero-mean and covariance stationary error process.

We consider our baseline local linear trend model of Sect. 3 for each of the objects, that is,

$$y_t = AF_t^{(i)} = T_t^{(i)} + \epsilon_t^{(i)},$$

for $i = 1, 2$, where the trend $T_t^{(i)}$ is specified in (6) and with error $\epsilon_t^{(i)}$. Table 1 reports the output of the estimation, using the state-space system and the Kalman filter. The first part of Table 1 presents estimates of the standard deviations of the observation error term $\epsilon_t^{(i)}$ and the trend error term $\eta_t^{(i)}$, as well as the estimate of the slope parameter β , including the estimated standard error (s.e.) of $\hat{\beta}$ and the resulting t -statistic, $t\text{-stat} = \hat{\beta} / \text{s.e.}(\hat{\beta})$. Based on these estimation results, we can formally test hypotheses of the type

$$H_0 : \beta = 0 \quad \text{against} \quad H_1 : \beta \neq 0, \quad (9)$$

or, more relevantly,

$$H_0 : \beta = 0 \quad \text{against} \quad H_1 : \beta > 0. \quad (10)$$

By using the normal approximation to the t -distribution and for a 95% confidence level, the critical value for the test (9) is 1.96, and for (10) it is 1.645. In case of the airborne fraction, we are interested in testing (10). It is evident from Table 1 that we cannot reject H_0 in this case (p -values 0.2711 and 0.4042, respectively). In other words, although the estimate $\hat{\beta}$ is positive, we cannot conclude, statistically at 95% confidence, that the airborne fraction is increasing over time.

Table 1 also contains diagnostic statistics for the standardized prediction residual u_t based on

$$y_t - \mathbb{E}(y_t | y_1, \dots, y_{t-1}; A, B, \Sigma_\xi, \Sigma_\kappa),$$

for $t = 1, \dots, n$, and where Σ_ξ and Σ_κ are replaced by their respective maximum likelihood estimates. Under the assumption that the local linear trend model is correctly specified for the time series y_t , the residuals u_t are Gaussian iid; see Durbin and Koopman (2012), p. 38. To verify these properties of u_t empirically, we consider two residual diagnostic statistics: the normality test statistic N of Jarque and Bera (1987) and the serial correlation test statistic DW of Durbin and Watson (1971). As a goodness-of-fit statistic, we consider the R_d^2 which is a relative measure of model fit against a random walk model. The statistic is defined in a similar way as the standard regression fit measure R^2 , we have

$$R_d^2 = 1 - \frac{\sum_{t=2}^n u_t^2}{\sum_{t=2}^n [(y_t - y_{t-1}) - m]^2}, \quad m = (n-1)^{-1} \sum_{t=2}^n (y_t - y_{t-1}).$$

The reported diagnostic statistics and goodness-of-fit in Table 1 are satisfactory for the time series $AF_t^{(1)}$ and $AF_t^{(2)}$. We may conclude from these results that the local linear trend model (6)-(7) provides an adequate description of the dynamic features in the time series. Since the $AF_t^{(2)}$ is well-described within our state-space framework, the extra error term $\xi_t = B_t^{IM} / E_t^{ANT}$ in $AF_t^{(2)}$, as introduced by the budget imbalance term in Eq. (8), is well-behaved. Hence the assumptions underlying the state-space system appear to be valid.

Table 1. Univariate analysis of the airborne fraction

	Parameter estimates					Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t -stat($\hat{\beta}$)	N	R_d^2	DW
$AF_t^{(1)}$	0.1357	0.0101	0.00109	0.00179	0.60934	0.274	0.442	1.829
$AF_t^{(2)}$	0.1353	0.0122	0.00049	0.00203	0.24246	2.324	0.489	1.991

We report parameter estimates for the standard deviations σ_ϵ and σ_η , and slope coefficient β together with its standard error (s.e.) and t -statistic (t -stat). We further report the normality (N) test, the goodness-of-fit statistic R_D^2 and the Durbin-Watson (DW) test statistic for serial correlation; all computed for the standardized prediction errors u_t which are obtained from the Kalman filter. The normality test N is the χ^2 distributed, with 2 degrees of freedom, statistic of Jarque and Bera (1987) with its 95% critical value of 5.99; the statistic relies on the sample estimates of skewness and kurtosis of u_t . The goodness-of-fit statistic R_d^2 is defined as $1 - ESS/DSS$ where $ESS = \sum_{t=2}^n u_t^2$ and $DSS = \sum_{t=2}^n [(y_t - y_{t-1}) - m]^2$ with $m = (n - 2)^{-1} \sum_{t=2}^n (y_t - y_{t-1})$. The Durbin-Watson DW test statistic is developed by Durbin and Watson (1971), where also its critical values are tabulated. If $DW = 2$ the sequence u_t is serially uncorrelated; if $DW < 2$ there is evidence that the errors u_t are positively autocorrelated; if $DW > 2$ there is evidence that the errors u_t are negatively autocorrelated.

The state-space system allows both measures for the airborne fraction, $AF_t^{(1)}$ and $AF_t^{(2)}$, to be included in a single model with the purpose to improve the quality of the trend estimation and inference. We begin with an “uninformed” system using two different trend components, $T_t^{(1)}$ and $T_t^{(2)}$, both specified as (6), for the two time series. We have

$$y_t = \begin{bmatrix} AF_t^{(1)} \\ AF_t^{(2)} \end{bmatrix} = \begin{bmatrix} G_t^{ATM} / E_t^{ANT} \\ 1 - (S_t^{OCEAN} + S_t^{LAND}) / E_t^{ANT} \end{bmatrix} = \begin{bmatrix} T_t^{(1)} \\ T_t^{(2)} \end{bmatrix} + \begin{bmatrix} \epsilon_t^{(1)} \\ \epsilon_t^{(2)} \end{bmatrix}, \quad (11)$$

where the error terms $\epsilon_t^{(i)}$, for $i = 1, 2$, are correlated and their correlation coefficient can be estimated by the method of maximum likelihood together with the other parameters. The estimation results for this model are presented in Panel A of Table 2. The main difference to Table 1 is the inclusion of the estimated correlation matrix for $(\epsilon_t^{(1)}, \epsilon_t^{(2)})$. The diagnostic test statistics are reasonable. In comparison with the univariate analysis, the goodness-of-fit values for R_d^2 are slightly higher for the multivariate model. Hence we trust the model to be a good representation of the data. Furthermore, the slope is estimated to be positive in both cases (that is $\hat{\beta} > 0$). However, when testing the null hypothesis given in (10), we cannot reject the hypothesis that the slopes are zero (p -values 0.3753 and 0.4895, respectively).

Table 2. Multivariate analysis of the airborne fraction

Parameter estimates						Correlation matrix (ϵ)		Diagnostics		
Panel A: Two individual trends as in Eq. (11).										
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t -stat($\hat{\beta}$)	$AF^{(1)}$	$AF^{(2)}$	N	R_d^2	DW
$AF^{(1)}$	0.1268	0.0333	0.00146	0.00459	0.31797	1.0000	0.7612	0.603	0.484	2.0152
$AF^{(2)}$	0.1307	0.0274	0.00010	0.00383	0.02629	0.7612	1.0000	1.469	0.525	2.0853
Panel B: One common trend as in Eq. (12).										
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t -stat($\hat{\beta}$)	$AF^{(1)}$	$AF^{(2)}$	N	R_d^2	DW
$AF^{(1)}$	0.1370	7.2e-09	0.00073	0.00095	0.77258	1.0000	0.5518	0.245	0.470	1.8722
$AF^{(2)}$	0.1375	–	–	–	–	0.5518	1.0000	2.573	0.516	1.9820

We report parameter estimates for the standard deviations $\sigma_\epsilon^{(i)}$ and $\sigma_\eta^{(i)}$, for $i = 1, 2$, correlation matrix for ϵ_t , and slope coefficient β together with its standard error (s.e.) and t -statistic (t -stat). We further report the normality (N) test, the goodness-of-fit statistic R_D^2 and the Durbin-Watson (DW) test statistic for serial correlation; for details see Table 1. In Panel B, the trend coefficients (σ_η and β) for $AF^{(2)}$ are the same as for $AF^{(1)}$ given the construction of model (12).

Since the two quantities in (8) are measuring the same object, the airborne fraction, we now force the state-space system to recognize that these data are driven by the same underlying common trend, T_t^A , but with possibly different error terms $\epsilon_t^{(1)}$ and $\epsilon_t^{(2)}$. In other words, we consider

$$y_t = \begin{bmatrix} AF_t^{(1)} \\ AF_t^{(2)} \end{bmatrix} = \begin{bmatrix} G_t^{ATM}/E_t^{ANT} \\ 1 - (S_t^{OCEAN} + S_t^{LAND})/E_t^{ANT} \end{bmatrix} = \begin{bmatrix} T_t^A \\ T_t^A \end{bmatrix} + \begin{bmatrix} \epsilon_t^{(1)} \\ \epsilon_t^{(2)} \end{bmatrix}. \quad (12)$$

- 5 The output of the estimation of this system is shown in Panel B of Table 2; the estimated common trend and the data are plotted in Fig. 1. A slight deterioration of the diagnostic statistics is to be expected when introducing a common trend into the system, but the diagnostic statistics are still such that we can accept (12) as a plausible model. For the estimate of the slope $\hat{\beta}$, we find a larger t -statistic in absolute value than in the uninformed model, indicating that the restriction to the common trend increases the precision of the estimates. An explanation of this finding is that the informed system has used twice as many observations
- 10 for estimating the trend compared to the uninformed system. The hypothesis test (10) reveals that the estimate of the slope parameter, although again positive, is still not statistically different from zero (p -value 0.2199).

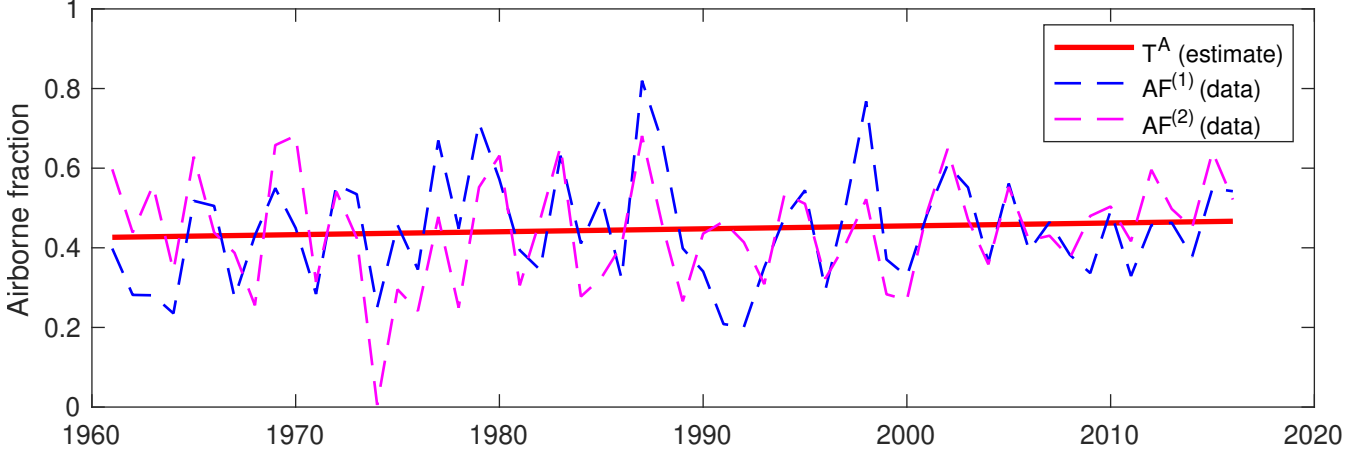
5 Trend analysis of the CO₂ sink rate

In this section, we analyse the CO₂ sink rate in the same way as the airborne fraction above. Analogously we can define two alternative versions of the sink rate:

$$15 \quad k_{S,t}^{(1)} = \frac{S_t^O + S_t^L}{C_t}, \quad k_{S,t}^{(2)} = \frac{E_t^{ANT} - G_t}{C_t} = k_{S,t}^{(1)} + \xi_t, \quad (13)$$

where now $\xi_t = B_t^{IM}/C_t$ and where we have used Eq. (2). As was the case for the airborne fraction, these two quantities are measuring the same underlying object (the sink rate, $k_{S,t}$) but differ in practice because of a non-zero budget imbalance, i.e. $\xi_t \neq 0$.

Figure 1. Estimated trend T_t^A of the airborne fraction from Model (12).



The basic (univariate) local linear trend model for each of these objects is then given by

$$y_t = k_{S,t}^{(i)} = T_t^{(i)} + \epsilon_t^{(i)},$$

for $i = 1, 2$, where $T_t^{(i)}$ is specified as in (6). When the model is cast in the state-space system, the parameters can be estimated for each of the data series individually. The estimation results are presented in Table 3. The diagnostic statistics are satisfactory, and we conclude again that the error term $\xi_t = B_t^{IM}/C_t$ is well-behaved, in the sense that the assumptions underlying the state-space system appear to be valid, also for the alternative sink rate data, $k_{S,t}^{(2)}$. Even though the estimates of the slopes are negative, we cannot reject the null hypothesis of $\beta = 0$ (p -values 0.2233 and 0.0761, respectively). We still consider a one-sided test as in (10) but now the relevant alternative hypothesis is $H_1 : \beta < 0$.

Table 3. Univariate analysis of the CO₂ sink rate

	Parameter estimates					Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e. ($\hat{\beta}$)	t -stat ($\hat{\beta}$)	N	R_d^2	DW
$k_S^{(1)}$	0.0066	8.8077e-04	-0.00010	0.00013	-0.76117	4.880	0.464	1.968
$k_S^{(2)}$	0.0063	6.3982e-04	-0.00015	0.00010	-1.43179	0.967	0.442	1.875

We report parameter estimates for the standard deviations σ_ϵ and σ_η , and slope coefficient β together with its standard error (s.e.) and t -statistic (t -stat). We further report the normality (N) test, the goodness-of-fit statistic R_D^2 and the Durbin-Watson (DW) test statistic for serial correlation; all computed for the standardized prediction errors u_t which are obtained from the Kalman filter; for details see Table 1.

Analogously to the airborne fraction above, these data can be put in a joint “uninformed” system with two different trend components, and we have

$$y_t = \begin{bmatrix} k_{S,t}^{(1)} \\ k_{S,t}^{(2)} \end{bmatrix} = \begin{bmatrix} (S_t^O + S_t^L)/C_t \\ (E_t^{ANT} - G_t)/C_t \end{bmatrix} = \begin{bmatrix} T_t^{(1)} \\ T_t^{(2)} \end{bmatrix} + \begin{bmatrix} \epsilon_t^{(1)} \\ \epsilon_t^{(2)} \end{bmatrix}, \quad (14)$$

which can be compared with model (11). The estimation results for this model are reported in Panel A of Table 4. Although
5 the slope estimates are negative, they are not significant (p -values 0.3106 and 0.1947, respectively).

Table 4. Multivariate analysis of the CO₂ sink rate

		Parameter estimates					Correlation matrix (ϵ)		Diagnostics		
Panel A: Two individual trends as in Eq. (14).											
		$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t -stat($\hat{\beta}$)	$AF^{(1)}$	$AF^{(2)}$	N	R_d^2	DW
$k_S^{(1)}$		0.0064	0.0015	-0.00010	0.00020	-0.49406	1.0000	0.7733	3.348	0.511	2.0233
$k_S^{(2)}$		0.0060	0.0014	-0.00017	0.00020	-0.86071	0.7733	1.0000	1.365	0.488	2.0185
Panel B: One common trend as in Eq. (15).											
		$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t -stat($\hat{\beta}$)	$k_S^{(1)}$	$k_S^{(2)}$	N	R_d^2	DW
$k_S^{(1)}$		0.0068	4.1762e-09	-0.00014	0.00005	-2.99145	1.0000	0.5621	4.012	0.499	2.0276
$k_S^{(2)}$		0.0065	–	–	–	–	0.5621	1.0000	0.090	0.474	1.7967

We report parameter estimates for the standard deviations $\sigma_\epsilon^{(i)}$ and $\sigma_\eta^{(i)}$, for $i = 1, 2$, correlation matrix for ϵ_t , and slope coefficient β together with its standard error (s.e.) and t -statistic (t -stat). We further report the normality (N) test, the goodness-of-fit statistic R_D^2 and the Durbin-Watson (DW) test statistic for serial correlation; for details see Table 1. In Panel B, the trend coefficients (σ_η and β) for $k_S^{(2)}$ are the same as for $k_S^{(1)}$ given the construction of
model (15).

Finally, we consider the state-space system that imposes a common trend for both time series, T_t^S , that is

$$y_t = \begin{bmatrix} k_{S,t}^{(1)} \\ k_{S,t}^{(2)} \end{bmatrix} = \begin{bmatrix} (S_t^O + S_t^L)/C_t \\ (E_t^{ANT} - G_t)/C_t \end{bmatrix} = \begin{bmatrix} T_t^S \\ T_t^S \end{bmatrix} + \begin{bmatrix} \epsilon_t^{(1)} \\ \epsilon_t^{(2)} \end{bmatrix}, \quad (15)$$

which can be compared with model (12). The estimation results are presented in Panel B of Table 4. Similar to the analysis
10 of the airborne fraction in the previous section, the diagnostic statistics are somewhat worse for the less flexible system with a common trend. However, the diagnostics are still satisfactory while the goodness-of-fit statistics have improved overall. The estimate of the slope is

$$\hat{\beta} = -0.00014,$$

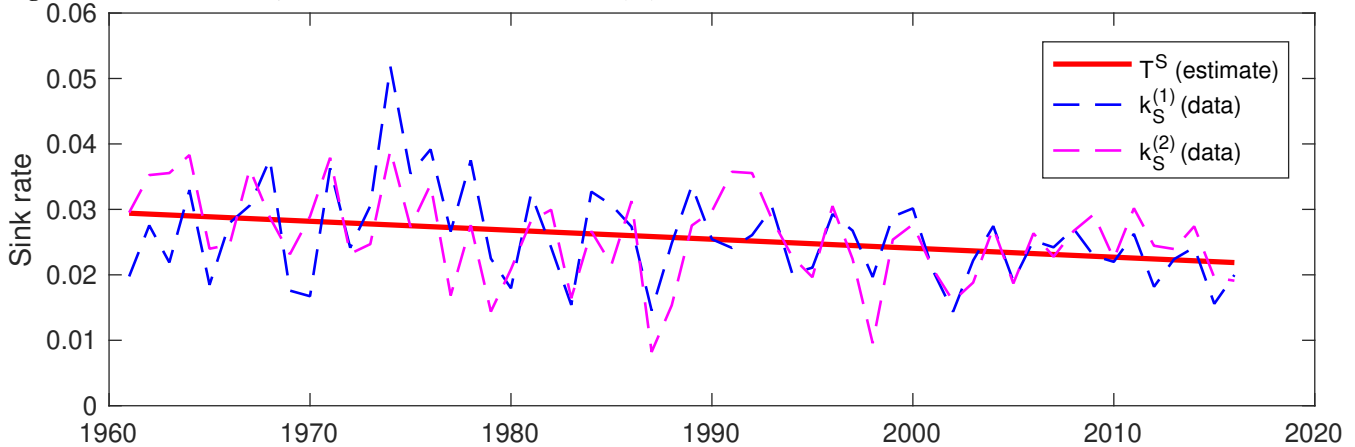
and this estimate is statistically significant: we reject the hypothesis $H_0 : \beta = 0$ in favor of $H_1 : \beta < 0$ at a 95% confidence
15 level (p -value 0.0014). The mean of the sink rate (calculated using either data set $k_S^{(1)}$ or $k_S^{(2)}$) is 0.0258. It follows that we

estimate the sink rate to be decreasing with approximately $0.00014/0.0258 = 0.54\%$ every year. The estimated trend and the data are plotted in Fig. 2.

The state-space system is also well-suited for forecasting; see Durbin and Koopman (2012). Using model (15), we forecast the sink rate 25 years ahead in time. The output is presented in Fig. 3. [For reference, the forecasts coming from an autoregressive model of order one \(AR1\) are also presented.](#) The downward trend in the forecasts [from the state-space model](#) is the result of the negative estimate of β . Under current conditions, the forecast implies that in approximately 15 years, the sink rate will have declined to below 2%. [Conversely, the autoregressive model produces forecasts that converge to the mean of the original data series.](#)

[It is important to recognise that the validity of these forecasts are conditional on the assumption that the sink rate, \$k_S\$, is linear in concentrations. As seen from the analysis above, cf. also Fig. 2, this assumption has been approximately satisfied over the time period considered in this paper, but whether it will continue to be accurate is an open question. \(Cf. Appendix A for a discussion of the possible future behaviour of the sink rate.\) The model-based forecasts of Fig. 3 should be seen in this light: these forecasts are obtained under the assumption that the sink rate will continue to be approximately linear in concentrations. Whether this assumption is reasonable is an interesting question beyond the scope of the present study.](#)

Figure 2. Estimated trend T_t^S of the CO₂ sink rate from Model (15).



15 6 Trend analysis of the ocean and land sink rates

We may conclude from the analysis in the previous section that the combined (land plus ocean) sink rate appears to be decreasing. To investigate this finding in more detail, we study two alternative models, which consider the two sink variables

Figure 3. Forecasting the CO₂ sink rate based on Model (15).

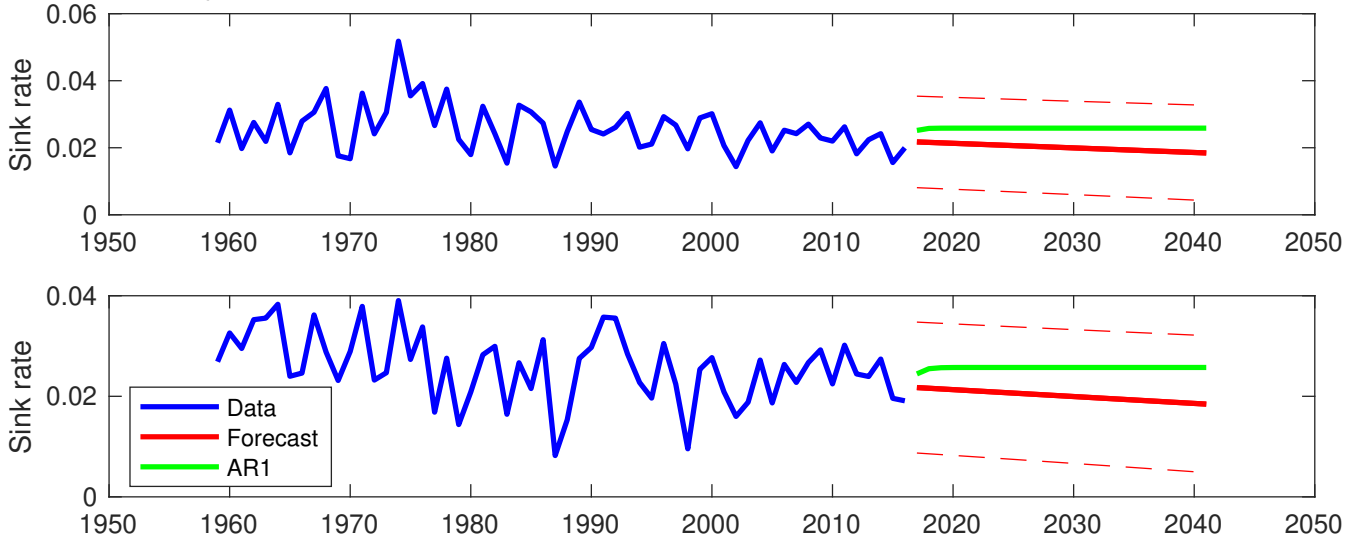


Figure 3. The blue solid line represents the data, while the red solid line represents the point forecasts from the Kalman filter with the unknown parameters estimated by maximum likelihood. The dashed red lines are 95% confidence bands (± 1.96 standard deviation) for the forecasts. The green line represents the forecasts from an autoregressive model of order one.

separately. The first model specifies local linear trends for ocean and land sink rates, i.e.,

$$y_t = \begin{bmatrix} k_{O,t} \\ k_{L,t} \end{bmatrix} = \begin{bmatrix} S_t^O / C_t \\ S_t^L / C_t \end{bmatrix} = \begin{bmatrix} T_t^O \\ T_t^L \end{bmatrix} + \begin{bmatrix} \epsilon_t^{(1)} \\ \epsilon_t^{(2)} \end{bmatrix}, \quad (16)$$

where the time series $k_{O,t}$ and $k_{L,t}$ are defined in (4) while the trend variables T_t^O and T_t^L are specified as in (6). To inform the state-space system of the structure of the carbon budget, we also consider the model equations

$$5 \quad y_t = \begin{bmatrix} k_{O,t} \\ k_{L,t} \\ k_{S,t} \end{bmatrix} = \begin{bmatrix} S_t^O / C_t \\ S_t^L / C_t \\ (E_t^{ANT} - G_t) / C_t \end{bmatrix} = \begin{bmatrix} T_t^O \\ T_t^L \\ T_t^O + T_t^L \end{bmatrix} + \begin{bmatrix} \epsilon_t^{(1)} \\ \epsilon_t^{(2)} \\ \epsilon_t^{(3)} \end{bmatrix}. \quad (17)$$

This trivariate model equation can be cast in the state-space system (5) as well. The model specification has two independent trend processes of the form (6) for land and ocean sinks. Since $k_{S,t} = k_{O,t} + k_{L,t}$, the time series $k_{S,t}$ of combined ocean and land sinks must feature the sum of the two trend processes for the individual sinks as its trend process.

The estimation results for these two model specifications are presented in Table 5. The residual diagnostic statistics N and DW are satisfactory, but we are particularly interested in the estimates of the slope parameters. It seems that most of the decrease in the sink rate can be attributed to the land sink. The slope estimates of the trend driving the ocean sink rate are very close to zero and not statistically significant (p -values 0.5227 and 0.5168, respectively). On the other hand, the slope estimates of the trend driving the land sink rate are negative for both specifications. In the first model (16), we can reject the hypothesis

that the slope of the trend driving the land sink rate is zero, in favor of the one-sided alternative $H_1 : \beta < 0$ at a 95% confidence level (p -value of 0.0420). For the more informed model specification (17), the estimation results are reported in Panel B of Table 5. Here we can reject H_0 at a 90% confidence level (p -value of 0.0882). Further, the results show that the estimate of the slope parameter from the land sink rate is equal to the estimate of the slope parameter from the combined sink rate as in Sect. 5, that is, $\hat{\beta} = -0.00014$. In other words, it appears that the decrease in the combined sink rate studied in the previous section is entirely explained by the decrease in the land sink rate.

Table 5. Analysis of ocean and land sink rates

Panel A: Two trends, two observation series as in Eq. (16).											
	Parameter estimates					Correlation matrix (ϵ)			Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t -stat($\hat{\beta}$)	$k_{O,t}$	$k_{L,t}$		N	R_d^2	DW
$k_{O,t}$	0.0001	0.00081	0.00001	0.00011	0.057	1.00	-1.00		4.839	0.0343	1.847
$k_{L,t}$	0.0067	0.00015	-0.00010	0.00006	-1.728	-1.00	1.00		5.332	0.513	1.908
Panel B: Two trends, three observation series as in Eq. (17).											
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t -stat($\hat{\beta}$)	$k_{O,t}$	$k_{L,t}$	$k_{S,t}$	N	R_d^2	DW
	$k_{O,t}$	0.0001	0.00081	0.00000	0.0001	0.0422	1.00	-0.122	-0.884	4.839	0.0343
$k_{L,t}$	0.0068	0.00068	-0.00014	0.0001	-1.352	-0.122	1.00	0.572	4.054	0.494	1.989
$k_{S,t}$	0.0065	-	-	-	-	-0.884	0.572	1.00	1.114	0.477	1.801

We report parameter estimates for standard deviations $\sigma_\epsilon^{(i)}$ and $\sigma_\eta^{(i)}$, for $i = 1, 2, 3$, correlation matrix for ϵ_t , and slope coefficient β together with its standard error (s.e.) and t -statistic (t -stat). We further report the normality (N) test, the goodness-of-fit statistic R_D^2 and the Durbin-Watson (DW) test statistic for serial correlation; for details see Table 1. In Panel B, we have two trends and two sets of trend coefficients (σ_η and β) for $k_{O,t}$ and $k_{L,t}$, the trend for $k_{S,t}$ is a combination of the two, given the construction of model (17).

7 Discussion

Previous studies of the airborne fraction and the CO₂ sink rate have focused on detecting a single linear and deterministic trend in the data of the form $a_0 + a_1 t$, where a_0, a_1 are constants (Canadell et al., 2007a; Le Quéré et al., 2009; Knorr, 2009; Raupach et al., 2008, 2014). However, possible statistical difficulties in such analyses have been pointed out in Knorr (2009). For instance, a linear regression analysis of two or more non-stationary variables can yield invalid inference (Granger and Newbold, 1974). The approach of this paper is to consider the data in a state-space system. In this way, non-stationary components are explicitly modelled as unobserved trend components and inference is valid (e.g., Durbin and Koopman, 2012). Furthermore, the trend specification of the state-space system allows for both deterministic and stochastic trend components.

In some of the “un-informed” models, cf. Table 1, Panel A of Table 2, and Panel A of Table 4, we estimate $\hat{\sigma}_{Slp} > 0$ and, thus, in these cases, we find evidence of the trend component varying in time. However, in our “informed” models with a single trend object for two alternative time series, the extracted trends are practically deterministic, that is, the estimates of σ_{Slp} in Panel B of Tables 2 and 4 are near zero, cf. also Fig. 1 and 2. In conclusion, there is evidence that a simple deterministic trend

fits both the airborne fraction and the sink rate data well, although this only becomes evident when incorporating two data sets for each of these objects.

Several studies have highlighted the need for accounting for noise in measurements of climate-related data (Knorr, 2009; Ballantyne et al., 2015). The state-space approach explicitly incorporates such noise in the framework as well. Ballantyne et al. (2015) argue that errors in E_t^{ANT} might be autocorrelated. As shown in Tables 1 through 5, the diagnostic statistics do not indicate that autocorrelated errors pose a serious problem in our specifications. Nevertheless, the state-space framework can incorporate autocorrelated errors in the measurement equation.

Why do we find statistical evidence of a decreasing CO₂ sink rate but no evidence of an increasing airborne fraction when these two quantities are closely linked and the data entering the analyses are the same? It was noted in Gloor et al. (2010) that the airborne fraction and the sink rate are actually not as closely linked as they may seem *prima facie*. In particular, an increasing airborne fraction does not necessarily imply a decreasing sink rate (Gloor et al., 2010, Section 8) and vice versa (Gloor et al., 2010, Section 8). The findings of this paper supports this claim by providing statistical evidence for a constant airborne fraction but at the same time a decreasing sink rate. Secondly, the concept of an airborne fraction is that of a long-term quantity: the airborne fraction should represent the amount of anthropogenically released CO₂ that *eventually* stays in the atmosphere, *after* other fluxes have been taken into account. However, the ratio of the concurrent fluxes, i.e., G_t/E_t^{ANT} , is likely a very noisy measurement of this object. Also, as we saw above, it is reasonable to consider sink fluxes, and therefore indirectly G_t , as dependent on the *level* of CO₂ in the atmosphere (i.e., $C_t = \sum G_t$), which is not captured by the concurrent ratio G_t/E_t^{ANT} . When studying the airborne fraction, it would perhaps be more reasonable to study an object taking this cumulative nature into account, e.g. $\sum G_t / \sum E_t^{ANT} = C_t / \sum E_t^{ANT}$ (in fact, such specifications were often considered in earlier parts of the literature, e.g. Keeling, 1973; Bacastow and Keeling, 1979; Oeschger and Heimann, 1983; Enting and Pearman, 1986). However, cumulative statistics of this type would present other difficulties. The dominance of the long-term history may mask sudden changes, for example. In contrast, the sink rate S_t/C_t , as a flow-to-stock ratio, is immediately compatible with the underlying theory, at least as long as the linear approximation of the relationship between S_t and C_t , such as was made in e.g. Gloor et al. (2010) and Rayner et al. (2015), is adequate.

What are possible physical ~~reasons~~ explanations for the apparent decrease in the sink rate? Raupach (2013) argues that a necessary condition for a constant sink rate is that the so-called “LinExp” assumption holds, i.e., that the sink fluxes S_t^O and S_t^L are linear in concentrations C_t (“Lin”) and that emissions (E_t^{ANT}) grow exponentially (“Exp”). Constancy of the airborne fraction rests on a similar “LinExp” argument. Since we find no statistical evidence that the airborne fraction, AF_t , and the ocean sink rate, $k_{O,t}$, are non-constant in time, it is unlikely that the “Exp” assumption is grossly violated over the observation period considered in this paper. In contrast, it was found above that the efficiency of the land sink, $k_{L,t}$, is decreasing. A plausible explanation of these findings is that the “Lin” assumption no longer holds for the land sink, for instance because the terrestrial sink could be slowly saturating (Canadell et al., 2007b). In Appendix A we give a formal argument for how this could lead to the findings documented above. In particular, we show that the findings of this paper can be explained by the land sink’s response to high atmospheric CO₂ concentrations: it is plausible that due to a rising level of CO₂ concentration, non-linear effects in the terrestrial CO₂ carbon cycle have become noticeable. If this is indeed the case, it has obvious consequences

for our understanding of the carbon cycle and should be a cause for substantial concern (Gloor et al., 2010, p. 7740). However, although this explanation of our findings is consistent with the data, we can not conclude that it is the only possible explanation. Further research into the underlying reasons for the decreasing sink rate would be very valuable and are left for future work.

It is possible that the analyses conducted above are influenced by external natural events such as ENSO, volcanic eruptions, and the like (Frölicher et al., 2013). The state-space system used in this paper can explicitly account for such effects through the additive error terms ϵ_t , cf. Eq. (5). To verify that the approach is indeed robust to such external and transitory events, we have also conducted our analyses using 5-year average data. The findings from the estimated state-space system for these time series of averages confirm those reported above: In the joint estimation, we find no statistical evidence of a trend in the airborne fraction (p -value of 0.3214), and we do find statistical evidence of a decreasing trend in the sink rate (p -value of 0.00064). We conclude that the findings of this paper are not likely to be driven by external natural events such as ENSO and volcanic eruptions. We also considered 2-, 3-, and 4-year averages with similar results. We present details of this analysis in the Supplementary Material file [\(Sect. 3\)](#). To further check the robustness of the results, we examined whether there are any of the observations in the data set which are particularly influential. Statistically influential observations could be due to outliers, caused for instance by external natural events, such as the ones mentioned above. Using a statistic called Cook's distance (Cook, 1977, 1979; Atkinson et al., 1997), which is a measure of how influential a given observation is on the analysis, we did not find evidence of any one observation being particularly influential. Similarly, we tried estimating the slope parameter β after deleting the t 'th observation for each time point t in the sample, i.e., for $t = 1959, 1960, \dots, 2016$; the estimates of the slope parameter found in this way were very stable, which is further evidence of the robustness of the analyses to potential outliers and external events. Details can be found in the Supplementary Material file (Sect. 2.1).

This paper considers data recorded at a yearly frequency, while many of the previous studies of the airborne fraction and the sink rate use monthly data. The advantage of using monthly data is obvious: more observations. However, there are also some disadvantages. For instance, while the CO_2 concentration C_t (and therefore also the growth rate G_t) are recorded every month, these data contain a strong seasonal component induced by the photosynthesis/respiration cycle of terrestrial vegetation. This seasonality needs to be accounted for in some way; for instance, Raupach et al. (2014) smooth the data using a 15-month running mean. In contrast, some of the other data are recorded only yearly; for instance, emissions data available to us, E_t^{ANT} . In this case, Raupach et al. (2014) use linear interpolation to get monthly estimates of emissions. Such transformations of the data, i.e., smoothing or interpolation, might introduce new and complicated errors, possibly invalidating the analyses. For these reasons, we prefer to work with yearly data.

8 Conclusions

We have argued that the state-space system can be a useful approach to analyze possible trends in the airborne fraction of anthropogenically released CO_2 and in the CO_2 sink rate. We have shown that deterministic and stochastic trend processes can be explicitly and jointly incorporated as unobserved components, allowing for valid inference, even when the observed time

series are non-stationary. The state-space framework also allows for the incorporation of multiple data sets for the same object, which increases reliability of the resulting estimates.

We estimate a positive, yet statistically insignificant, slope in the data for the airborne fraction. Using two alternative time series for the sink rate and imposing a common trend, we obtain a significantly negative deterministic trend. Our analyses support the conclusions as set out by Raupach et al. (2014): the rate at which the combined (ocean plus land) sink takes up CO₂ from the atmosphere seems to be decreasing. The best estimate resulting from our state-space system is that the CO₂ sink rate, and therefore the efficiency with which the combined land and ocean sink is absorbing carbon from the atmosphere, is decreasing by 0.54% per year. We do not find evidence of this rate itself changing over time.

Finally, there is tentative evidence that the decrease in the sink rate is mainly driven by a weakening uptake in the land sink. This could be the result of non-linearities in the response of the terrestrial carbon sink to the level of atmospheric concentrations of CO₂. That is, although the land sink is itself increasing and thus continuing to take up a large part of anthropogenically emitted CO₂, as also noted recently by e.g. Rayner et al. (2015), Keenan et al. (2016), and Fernández-Martínez et al. (2019), the *rate* of this uptake appears to be decreasing. The statistical evidence for this is not strong, however, and we suggest that additional research must be conducted to further investigate this question.

Author contributions. All authors contributed equally to the paper.

Competing interests. No competing interests are present.

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Appendix A: Linear approximation of the relation of land sink and concentrations

In this appendix, we argue that the levels of atmospheric concentrations of CO₂ may have risen to a point where a linear expansion of the logarithmic Bacastow and Keeling (1973) formula, describing the flux of CO₂ into the land sink, is no longer sufficient. Consequently, the “Lin” assumption of Raupach (2013) might be violated for the land sink, implying that second-
5 order effects may be driving the negative slope of the sink rate that we document in this paper.

From Eq. (4) we obtain the relation

$$S_t^L = k_{L,t} \cdot C_t,$$

which implies that the flux of CO₂ to the land sink is linear in C_t , where $k_{L,t}$ would then be treated as a constant. On the other hand, a decreasing $k_{L,t}$ implies that the efficiency with which the land sink absorbs CO₂ is decreasing, i.e., that the flux of
10 CO₂ to the land sink is non-linear in C_t and this non-linearity is such that the efficiency is decreasing. These statements are consistent with simulation results from climate cycle models (Friedlingstein et al., 2006). Here we illustrate mathematically how such non-linearities can arise.

The precise relationship between S_t^L and C_t still alludes us but Bacastow and Keeling (1973), p. 94, suggest that (in our notation):

$$15 \quad S_t^L \approx \alpha \log(1 + C_t/C^0),$$

where α is a constant and $C^0 = 591.30$ GtC is the amount of CO₂ in the atmosphere in pre-industrial times. Using this function, we can write a second-order Taylor expansion

$$S_t^L \approx \alpha \log(1 + C_t/C^0) \approx \alpha \frac{C_t}{C^0} - \frac{1}{2} \alpha \left(\frac{C_t}{C^0} \right)^2.$$

Thus, if C^0 is large compared to C_t , this implies [that the squared term in the above equation is small and thus](#) that a linear
20 specification between S_t^L and C_t is reasonable. However, once C_t becomes large compared to C^0 , this shows that the estimated sink rate will be found to be decreasing. To see this, use the Taylor expansion to write

$$S_t^L \approx k_{L,t} C_t,$$

where

$$k_{L,t} = \frac{\alpha}{C^0} - \frac{1}{2} \frac{\alpha}{C^0} \frac{C_t}{C^0}$$

25 is decreasing in C_t . In our data, we have $C_{1959} \approx 80$ GtC and $C_{2016} \approx 267$ GtC, resulting in $C_{1959}/C^0 \approx 14\%$ and $C_{2016}/C^0 \approx 45\%$. In other words, the linear approximation to the Bacastow and Keeling model of the land sink flux might have been reasonable in the past, since $C_{1959}/C^0 \approx 14\%$, but is likely misspecified in the present, since $C_{2016}/C^0 \approx 45\%$. That is, if this model is accurate, then a decreasing (land) sink rate indicates that we have entered a regime of atmospheric CO₂ concentrations, where the linear approximation breaks down and higher order terms should be taken into account.

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Supplementary Material: Trend analysis of the airborne fraction and sink rate of anthropogenically released CO₂

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Abstract. This document accompanies the paper “Trend analysis of the airborne fraction and sink rate of anthropogenically released CO₂” (Bennedsen et al., 2018): We expand on the analyses of the main paper and supply additional results.

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1 Introduction

- 5 Section 2 provides some additional information of the univariate analyses of the main paper. In particular, Section 2.1 contains an analysis of potential statistically influential observations in the data set. Section 3 analyses data that have been averaged, so as to minimise possible influences from transitory events such as ENSO and volcanic eruptions.

2 Additional results from univariate analyses

In the main paper, we analyse the univariate data series in Tables 1 and 3 (airborne fraction and sink rate, respectively).

- 10 However, to save space, we did not provide any graphical information on the estimated trends. These are given here, in Figure 1 (airborne fraction) and Figure 2 (sink rate). The figures can be compared to the ones from the multivariate analyses, see Figures 1 and 2 in the main paper. The main take-away from these figures is that in the univariate analyses, the underlying trends are found to be time-varying. This is contrast to the multivariate analyses, where the trends are better described by a trend that does not vary in time.

- 15 Figure 3 plots the trend estimates of the individual sink rates, i.e., of of the ocean sink rate (k_O) and land sink rate (k_L), cf. Equation (5) in the main paper.

Figure 1. Univariate estimation of time-varying trend for AF.

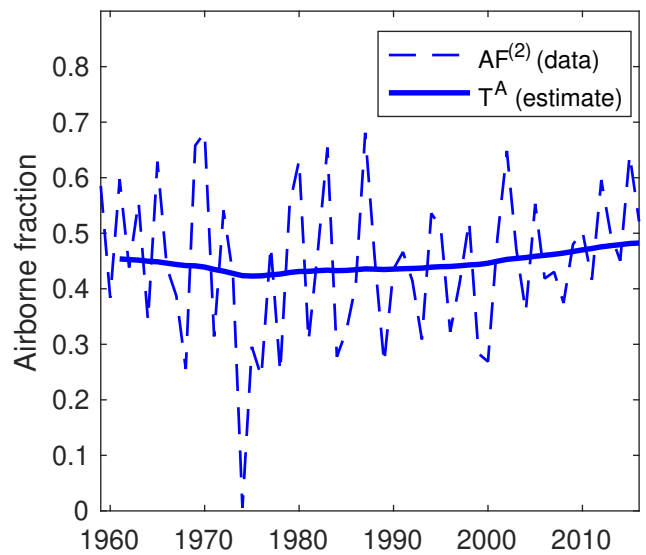
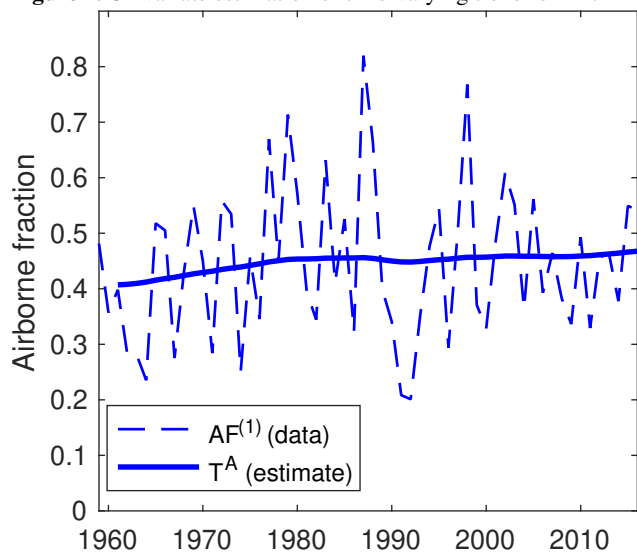


Figure 2. Univariate estimation of time-varying trend for sink rate, k_S .

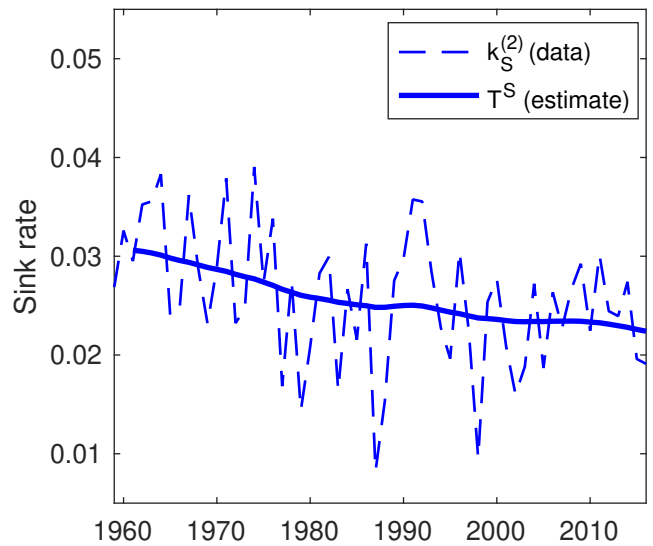
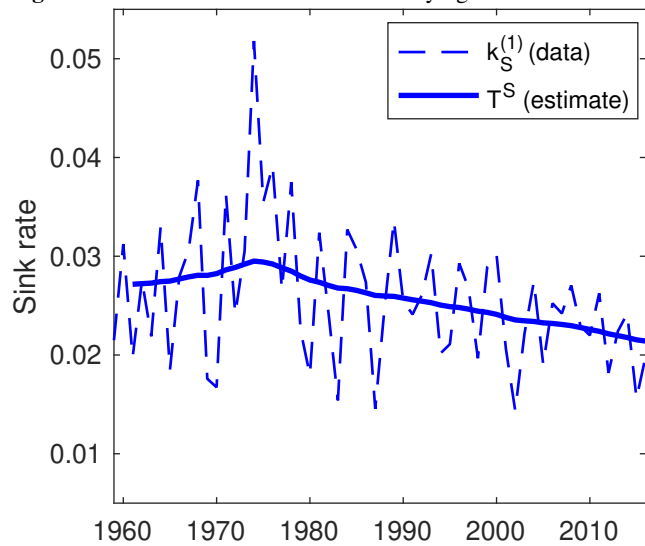
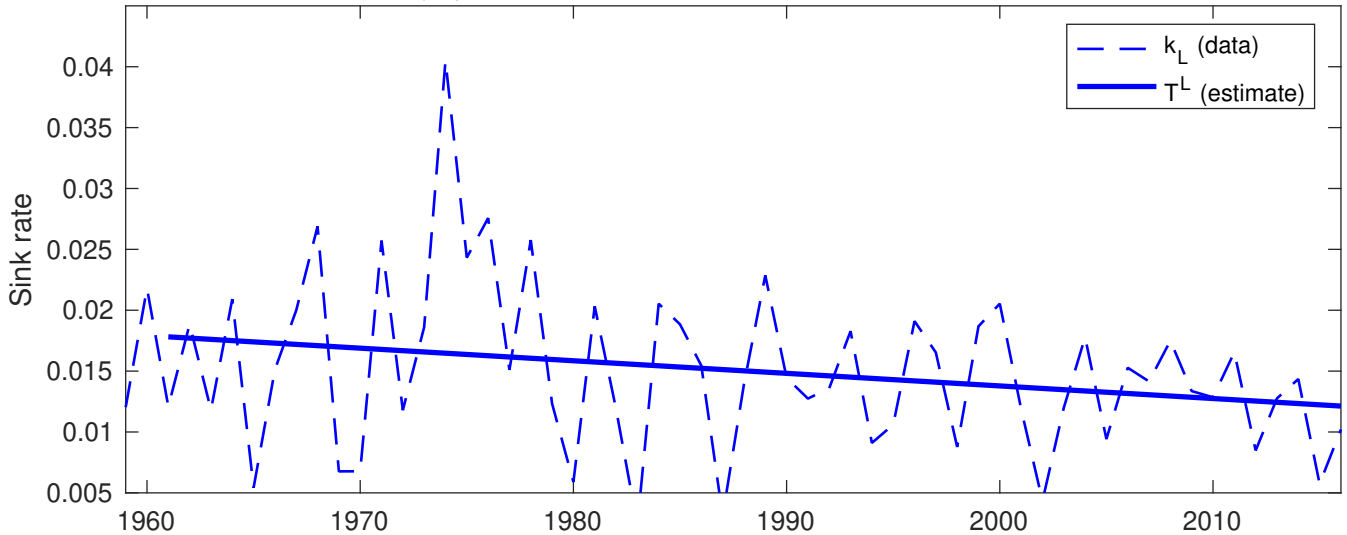


Figure 3. Univariate estimation of time-varying trend for land sink.



2.1 Influential data point analysis

To investigate the robustness of the statistical findings of the main paper, we here examine whether there are observations that are particularly influential on the analyses. We consider two related approaches. First, we calculate Cook’s distance (Cook, 1977, 1979; Atkinson et al., 1997) for each $t = 1959, 1960, \dots, 2016$, which is a measure of how influential a particular data point is. Second, we estimate the slope parameter β after deleting the t ’th observation from the sample (treating it as a “missing value” in the state-space system) for $t = 1959, 1960, \dots, 2016$. That is, for each year in the sample, we obtain an estimate $\beta_{\setminus t}$ for each $t = 1959, 1960, \dots, 2016$, by treating the t ’th observation as missing and then estimating the slope parameter using the maximum likelihood approach considered in the main paper.

Figures 4 and 5 present these analyses for the airborne fraction, while Figures 6 and 7 present the analogous results for the sink rate. From these figures, it is clear that one observation, namely the one at $t = 1974$, stands out: it has by far the largest Cook’s distance for both the airborne fraction and the sink rate data (Figures 4 and 6, respectively). It also results in the most extreme slope parameter estimates (Figures 5 and 7, respectively). However, even this observation at $t = 1974$ seems to have only a minor influence on the analysis: indeed, the estimate of $\beta_{\setminus 1974}$ is well within the confidence bands (dashed lines) of the full sample estimate for both the airborne fraction data (Figure 5) and for the sink rate data (Figure 7). Similarly, while the Cook’s distance for this data point is high relative to the other points, it is far below conventional rule-of-thumb thresholds such as 0.50 or 1.00, which are often used in applied analyses.

Figure 4. Cook's distance of each observation from the state-space model of the airborne fraction.

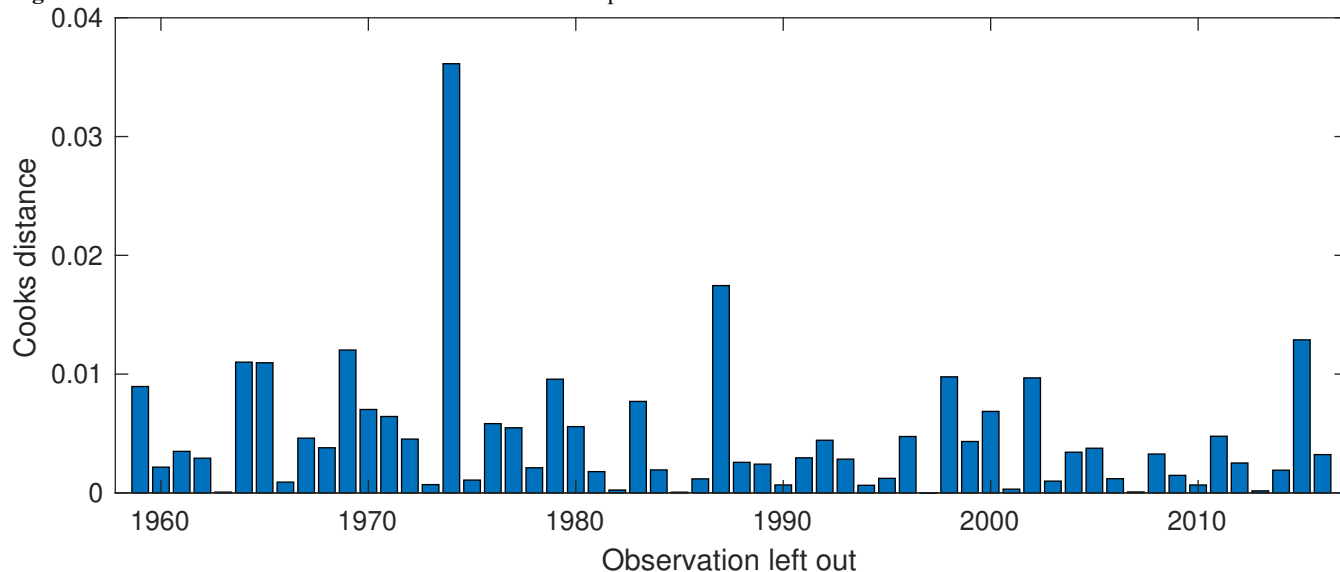


Figure 5. Estimates of slope parameter β from the state-space model of the airborne fraction after leaving out one observation. Dashed lines are 95% confidence bands for the full sample estimate.

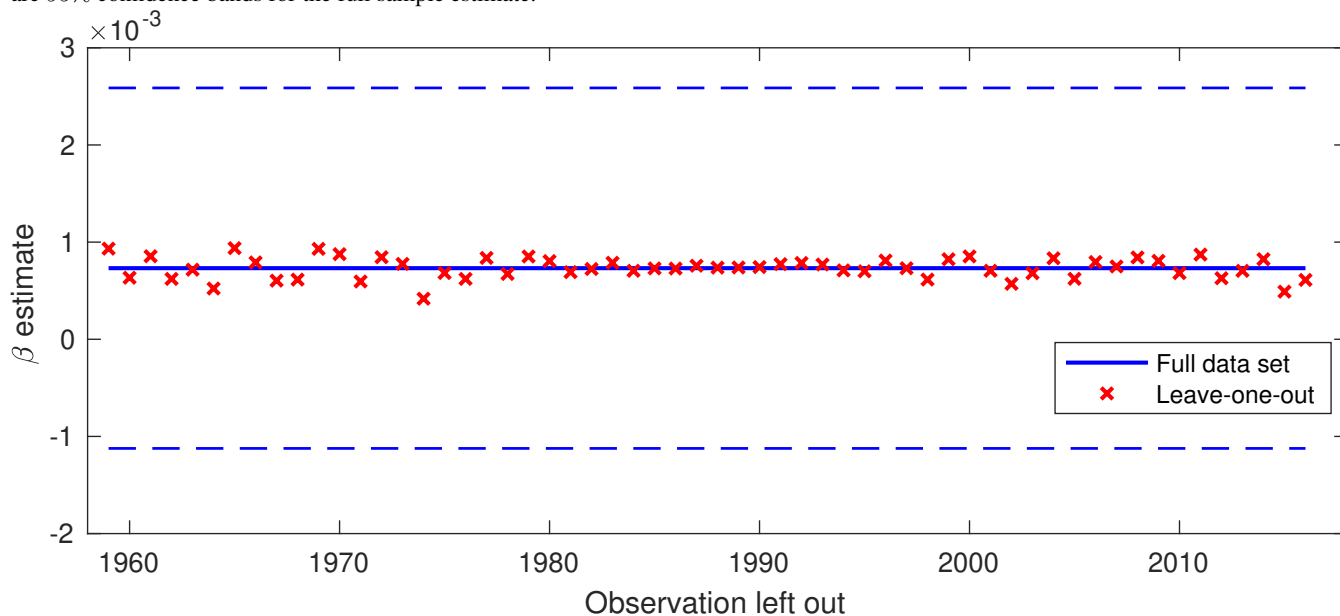


Figure 6. Cook's distance of each observation from the state-space model of the sink rate.

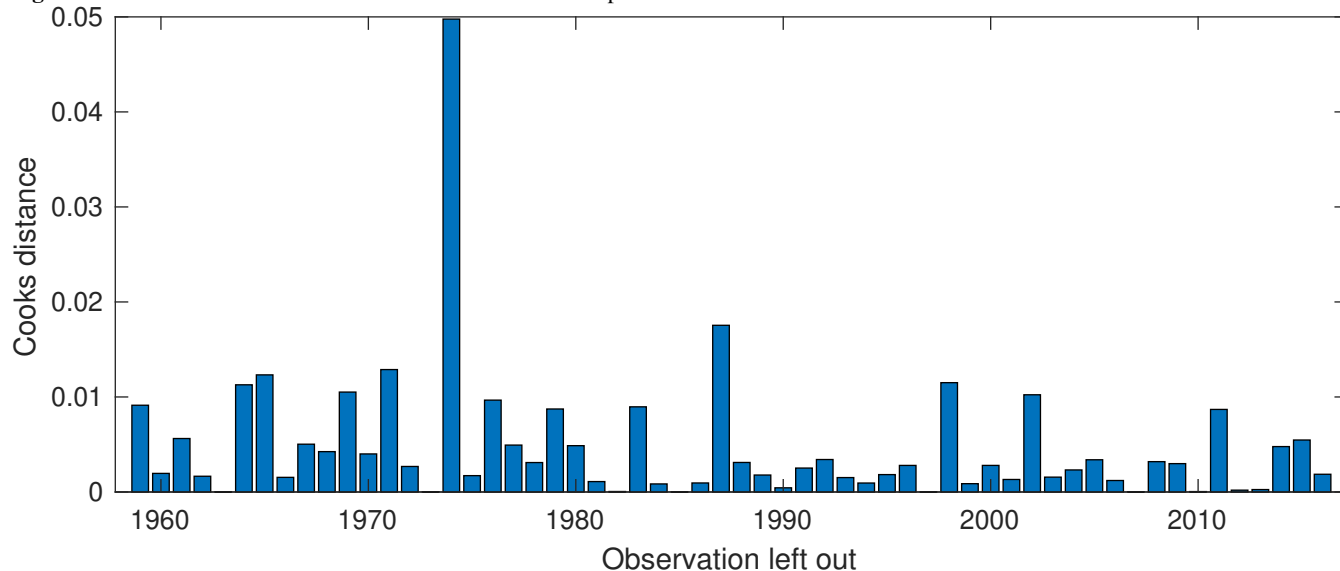
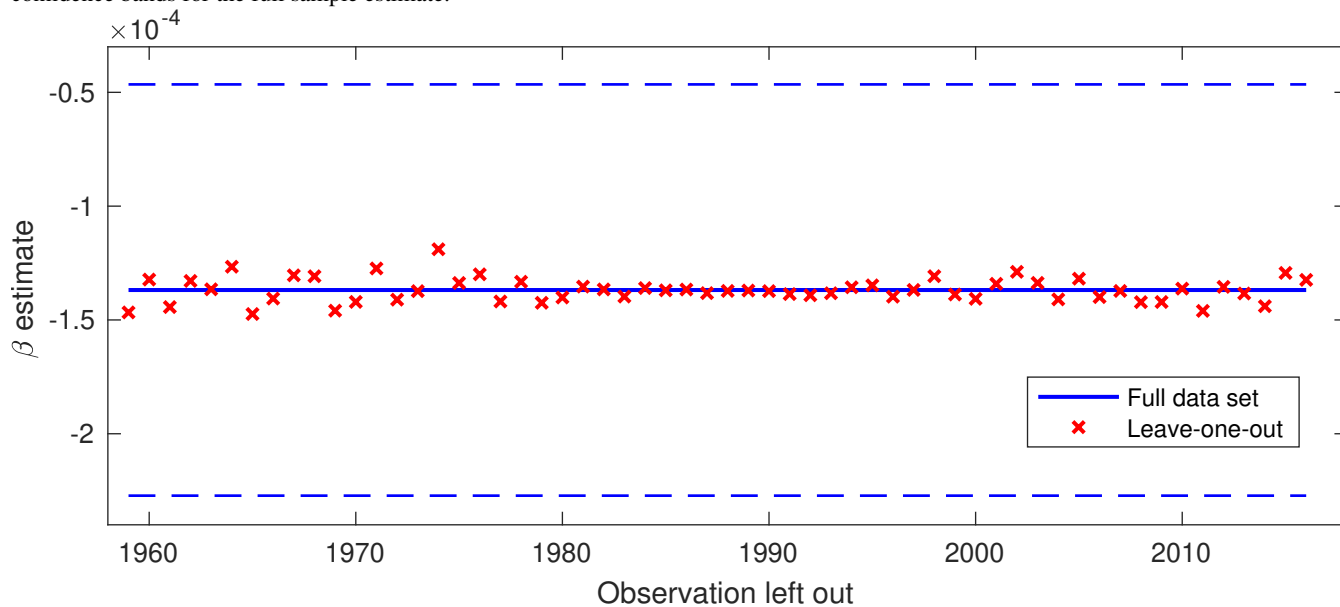


Figure 7. Estimates of slope parameter β from the state-space model of the sink rate after leaving out one observation. Dashed lines are 95% confidence bands for the full sample estimate.



3 Analysis with 5-year averages

To remove possible influences of transitory events (e.g., ENSO and/or volcanic eruptions) on our analyses, we here re-do the analysis from the main paper, now with data averaged over 5 year periods.¹ We also averaged the data over 2, 3, and 4 years and found similar results to what we report below. For brevity, the results from using 2-4 year averages are not presented. They are available upon request.

We consider two ways of averaging the data: (i) Running averages, which results in overlapping “windows” of data, and (ii) non-overlapping averages. The former is considered in Section 3.1 and the latter in Section 3.2.

3.1 Running averages

Recall that the data of the original paper runs from $t = 1959$ to $t = 2016$, resulting in 58 observations. We now study the data after they have been averaged over a 5-year period using a running window. That is, if the original data are x_t , we consider the averaged data

$$\tilde{x}_t^{(m)} = \frac{1}{m} \sum_{i=1}^m x_{t-i+1}, \quad t = 1958 + m, 1959 + m, \dots, 2016,$$

where $m \geq 1$ is the number of observations used in constructing the averages. For instance, if $m = 5$, we get the 5-year averages

$$\tilde{x}_t^{(5)} = \frac{1}{5} \sum_{i=1}^5 x_{t-i+1}, \quad t = 1963, 1968, \dots, 2016,$$

resulting in $58 - 4 = 54$ observations.

As remarked in the Discussion section of the main paper, such averaging can, unfortunately, make the error structure of the data quite complicated. We illustrate how this can happen with a toy example: Suppose that the original data are “signal plus noise”:

$$x_t = x_t^* + \xi_t,$$

where x_t^* is the true (unobserved) value for the underlying data and ξ_t is an iid measurement error term. Let $m \geq 2$ and consider the averaged data

$$\tilde{x}_t^{(m)} = \frac{1}{m} \sum_{i=1}^m x_{t-i+1} = \tilde{x}_t^* + \tilde{\xi}_t,$$

where

$$\tilde{x}_t^* = \frac{1}{m} \sum_{i=1}^m x_{t-i+1}^*, \quad \tilde{\xi}_t = \frac{1}{m} \sum_{i=1}^m \xi_{t-i+1},$$

are the averaged signal and an error term, respectively. It is clear that the error term $\tilde{\xi}_t$ is now serially correlated, which can invalidate the analysis if the researcher does not take it into account.

¹We thank an anonymous referee for suggesting this.

With the above caveat in place, we analyse the 5-year averaged airborne fraction (AF) and sink rate (SR) data using a trend model specification, as explained in Section 3 of the main paper.² The results are shown in Tables 1 and 2 for the airborne fraction and Tables 3 and 4 for the sink rate. From the tables, we see that the diagnostics are quite bad, indicating that the proposed model is not able to fit the data well. In particular, we find evidence of positive serial correlation ($DW < 2$) in the prediction errors, as we would expect from the discussion of the error structure above.

We conclude that if one wants to analyse the running averages data, another approach than the one considered here is necessary. In particular, it is important to choose an approach that can take into account the error structure induced by the averaging. However, constructing such an alternative approach is outside the scope of this note. Instead, we propose to average the data using non-overlapping windows, thereby hopefully alleviating the serial correlation in the errors. The following section presents the results from this approach.

Table 1. Univariate analysis of the airborne fraction

	Parameter estimates					Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e. $(\hat{\beta})$	t -stat $(\hat{\beta})$	N	R_d^2	DW
$AF_t^{(1)}$	0	0.0447	0.00223	0.00584	0.38270	0.3387	-0.0616	1.6657
$AF_t^{(2)}$	0	0.0444	0.00055	0.00610	0.08987	1.0360	-0.0711	1.8195

Data: 5-year running average AF. See Table 1 in the main paper for the analogous analysis on the original data.

Table 2. Multivariate analysis of the airborne fraction

	Parameter estimates					Correlation matrix (ϵ)		Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e. $(\hat{\beta})$	t -stat $(\hat{\beta})$	$AF^{(1)}$	$AF^{(2)}$	N	R_d^2	DW
Panel A: Two individual trends as in Eq. (12) of the main paper.										
$AF^{(1)}$	0	0.0425	0.00223	0.00584	0.38270	1.0000	0.9999	0.3387	-0.0616	1.6657
$AF^{(2)}$	0	0.0444	0.00055	0.00610	0.08987	0.9999	1.0000	1.0360	-0.0711	1.8195
Panel B: One common trend as in Eq. (13) of the main paper.										
$AF^{(1)}$	0.0359	0.0393	0.00149	0.00540	0.27679	1.0000	-1.0000	3.6409	-0.6278	1.1458
$AF^{(2)}$	0.0459	–	–	–	–	-1.0000	1.0000	0.8089	-0.9646	0.9314

Data: 5-year running average AF. See Table 2 in the main paper for the analogous analysis on the original data.

²We perform the averaging directly on the global carbon budget data, i.e., on E_t^{ANT} , G_t , S_t^O , S_t^L , and C_t , and then construct the AF and SR data as explained in Section 2 of the main paper. We also experimented with first constructing the AF and SR data and then averaging these. The results of the two approaches were very similar so we only present the results of the former.

Table 3. Univariate analysis of the sink rate

	Parameter estimates					Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t-stat($\hat{\beta}$)	N	R_d^2	DW
$k_S^{(1)}$	0	0.0022	-0.00008	0.00030	-0.27290	4.3025	-0.0710	1.7625
$k_S^{(2)}$	0	0.0020	-0.00017	0.00027	-0.63234	0.0726	-0.0637	1.7127

Data: 5-year running average SR. See Table 3 in the main paper for the analogous analysis on the original data.

Table 4. Multivariate analysis of the sink rate

	Parameter estimates					Correlation matrix (ϵ)		Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t-stat($\hat{\beta}$)	$AF^{(1)}$	$AF^{(2)}$	N	R_d^2	DW
Panel A: Two individual trends as in Eq. (14) of the main paper.										
$k_S^{(1)}$	0	0.0022	-0.00008	0.00030	-0.27290	1.0000	1.0000	4.3025	-0.0710	1.7625
$k_S^{(2)}$	0	0.0020	-0.00017	0.00027	-0.63235	1.0000	1.0000	0.0726	-0.0637	1.7127
Panel B: One common trend as in Eq. (15) of the main paper.										
$k_S^{(1)}$	0.0024	0.0019	-0.00014	0.00026	-0.53638	1.0000	-1.0000	0.6056	-0.9981	0.8756
$k_S^{(2)}$	0.0015	–	–	–	–	-1.0000	1.0000	5.6559	-0.6044	1.1971

Data: 5-year running average SR. See Table 4 in the main paper for the analogous analysis on the original data.

3.2 Non-overlapping averages

We here consider averaged data, but where the averaging is done using non-overlapping windows. That is, if x_t is again the original data series, we define

$$5 \quad \hat{x}_t^{(m)} = \frac{1}{m} \sum_{i=1}^m x_{t-i+1}, \quad t = 1958 + m, 1958 + 2m, \dots, 2016,$$

i.e., we divide the data into bins (“windows”) of size m and then take the average in each bin.³

The advantage of this approach to averaging the data is, as discussed above, that we expect the errors to be more nicely behaved. In particular, we do not expect them to be as serially correlated in this case. The downside of the approach is of course that we will have fewer observations available for the subsequent statistical analysis. For instance, in the case of 5-year averages that we consider here, each averaged data series consists of only 12 observations.

The results are shown in Tables 5 and 6 for the airborne fraction and Tables 7 and 8 for the sink rate. From the tables, we see, as expected, that the diagnostics are better than what was seen in the case of overlapping averaging windows. Interestingly, the

³Because the original data set consists of 58 observations, it might not be possible in practice to have exactly m observations in each bin; in this case the first bin will have less observations allocated to it. For instance, in the case of 5-year averaging, the first bin will consist of 3 observations (representing the years 1959, 1960, and 1961) and the other bins will have 5 observations allocated to them (i.e., the second bin consists of the years 1962-1966, the third bin 1967-1971, etc.).

two main conclusions from the main paper hold also in the case of the averaged data: (i) We find no statistical evidence of an increasing airborne fraction (Tables 5 and 6) but we do find statistical evidence of a decreasing sink rate (Panel B of Table 6). (ii) The latter conclusion is only reached when *all* the data are combined into one model with a common trend, compare Panel A and Panel B of Table 6.

- 5 Figures 8 and 9 show the trend estimates of the airborne fraction and sink rate data, respectively, in the case of averaged data using non-overlapping windows.

Table 5. Univariate analysis of the airborne fraction

	Parameter estimates					Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t -stat($\hat{\beta}$)	N	R_d^2	DW
$AF_t^{(1)}$	0.0574	0.0067	0.00517	0.00523	0.98975	0.3594	0.3465	2.0985
$AF_t^{(2)}$	0.0481	0.0450	0.00083	0.01449	0.05721	0.1227	0.1018	2.0714

Data: 5-year non-overlapping average AF. See Table 1 in the main paper for the analogous analysis on the original data.

Table 6. Multivariate analysis of the airborne fraction

	Parameter estimates					Correlation matrix (ϵ)		Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t -stat($\hat{\beta}$)	$AF^{(1)}$	$AF^{(2)}$	N	R_d^2	DW
Panel A: Two individual trends as in Eq. (12) of the main paper.										
$AF^{(1)}$	0.0473	0.0335	0.00538	0.01087	0.49443	1.0000	0.9456	0.7162	0.4872	2.5460
$AF^{(2)}$	0.0394	0.0541	0.00122	0.01666	0.07344	0.9456	1.0000	0.3027	0.0821	2.3698
Panel B: One common trend as in Eq. (13) of the main paper.										
$AF^{(1)}$	0.0535	0	0.00361	0.00364	0.99164	1.0000	0.1975	0.4802	0.3698	2.2944
$AF^{(2)}$	0.0596	–	–	–	–	0.1975	1.0000	0.7454	0.5965	2.6334

Data: 5-year non-overlapping average AF. See Table 2 in the main paper for the analogous analysis on the original data.

Table 7. Univariate analysis of the sink rate

	Parameter estimates					Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t -stat($\hat{\beta}$)	N	R_d^2	DW
$k_S^{(1)}$	0.0023	0.0029	-0.00037	0.00091	-0.40483	0.1374	-0.0147	2.0028
$k_S^{(2)}$	0.0026	0.0011	-0.00073	0.00041	-1.78102	0.0770	0.2431	2.0450

Data: 5-year non-overlapping average SR. See Table 3 in the main paper for the analogous analysis on the original data.

Table 8. Multivariate analysis of the sink rate

Parameter estimates						Correlation matrix (ϵ)		Diagnostics		
Panel A: Two individual trends as in Eq. (14) of the main paper.										
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t -stat($\hat{\beta}$)	$AF^{(1)}$	$AF^{(2)}$	N	R_d^2	DW
$k_S^{(1)}$	0.0023	0.0029	-0.00052	0.00088	-0.58373	1.0000	1.0000	0.7418	-0.0204	2.0524
$k_S^{(2)}$	0.0025	0.0015	-0.00078	0.00049	-1.57493	1.0000	1.0000	0.0552	0.4228	2.2251
Panel B: One common trend as in Eq. (15) of the main paper.										
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t -stat($\hat{\beta}$)	$AF^{(1)}$	$AF^{(2)}$	N	R_d^2	DW
$k_S^{(1)}$	0.0032	0	-0.00068	0.00020	-3.41506	1.0000	0.3340	0.1292	0.6888	2.9392
$k_S^{(2)}$	0.0027	-	-	-	-	0.3340	1.0000	1.0816	0.1869	1.8314

Data: 5-year non-overlapping average SR. See Table 4 in the main paper for the analogous analysis on the original data.

Figure 8. Multivariate estimation of time-varying trend for AF. Data: 5-year averages (no overlap)

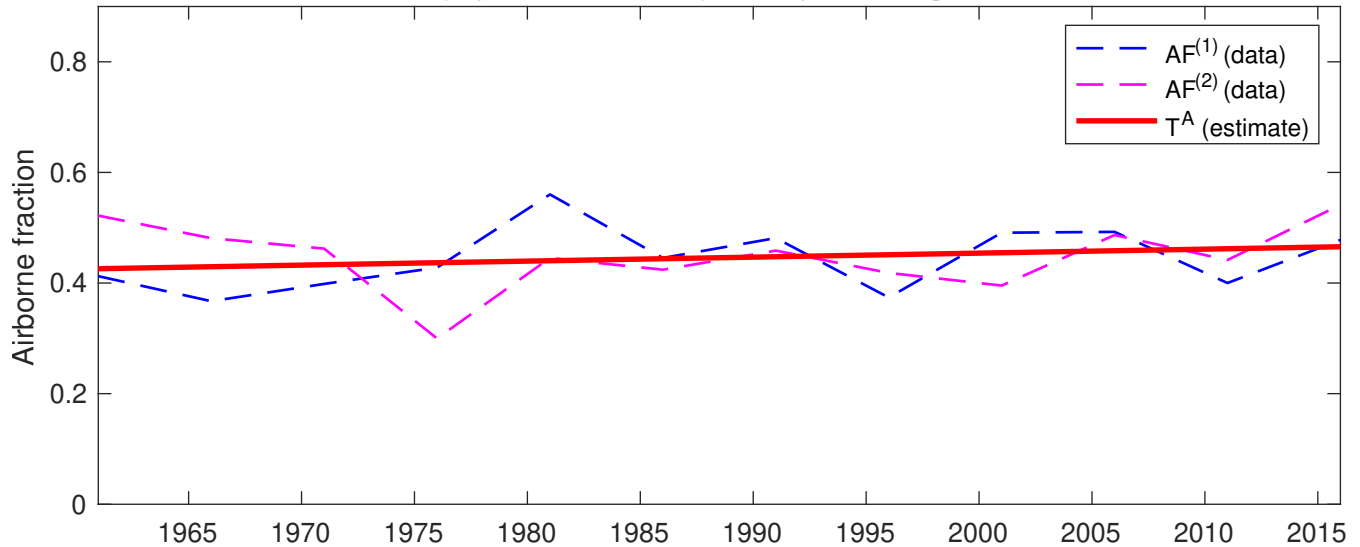
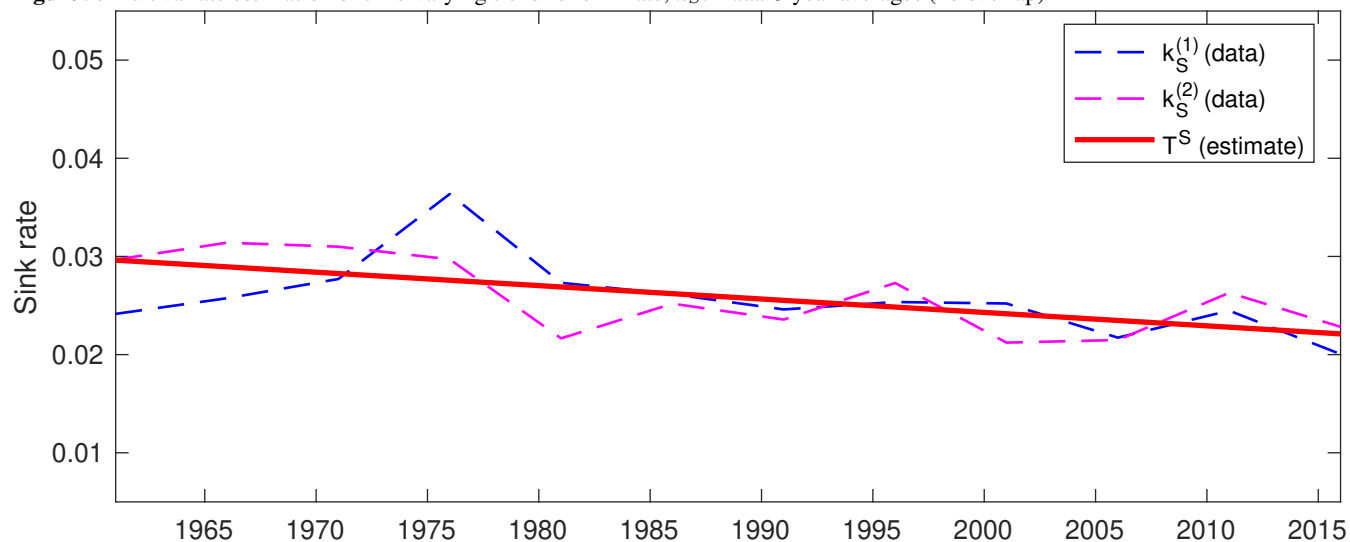


Figure 9. Multivariate estimation of time-varying trend for sink rate, k_S . Data: 5-year averages (no overlap)



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Supplementary Material: Trend analysis of the airborne fraction and sink rate of anthropogenically released CO₂

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Abstract. This document accompanies the paper “Trend analysis of the airborne fraction and sink rate of anthropogenically released CO₂” (Bennedsen et al., 2018): We expand on the analyses of the main paper and supply additional results.

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1 Introduction

- 5 Section 2 provides some additional information of the univariate analyses of the main paper. [Section 2.1 contains an analysis of potential statistically influential observations in the data set.](#) Section 3 analyses data that have been averaged, so as to minimise possible influences from transitory events such as ENSO and volcanic eruptions.

2 Additional results from univariate analyses

In the main paper, we analyse the univariate data series in Tables 1 and 3 (airborne fraction and sink rate, respectively).

- 10 However, to save space, we did not provide any graphical information on the estimated trends. These are given here, in Figure 1 (airborne fraction) and Figure 2 (sink rate). The figures can be compared to the ones from the multivariate analyses, see Figures 1 and 2 in the main paper. The main take-away from these figures is that in the univariate analyses, the underlying trends are found to be time-varying. This is contrast to the multivariate analyses, where the trends are better described by a trend that does not vary in time.

- 15 Figure 3 plots the trend estimates of the individual sink rates, i.e., of the ocean sink rate (k_O) and land sink rate (k_L), cf. Equation (5) in the main paper.

2.1 [Influential data point analysis](#)

Figure 1. Univariate estimation of time-varying trend for AF.

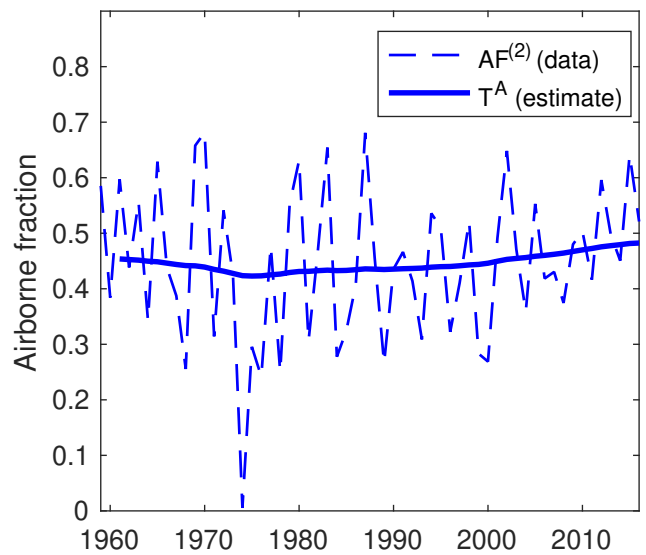
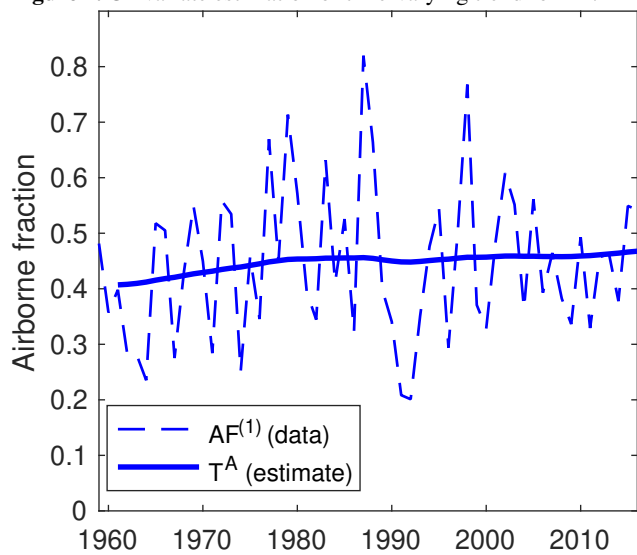


Figure 2. Univariate estimation of time-varying trend for sink rate, k_S .

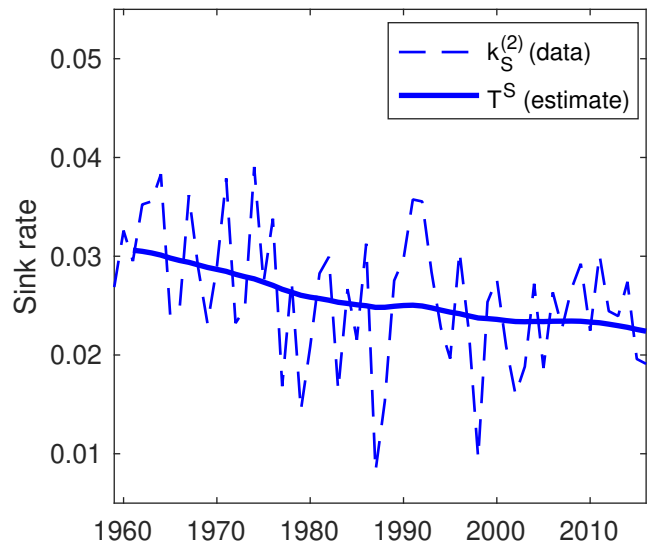
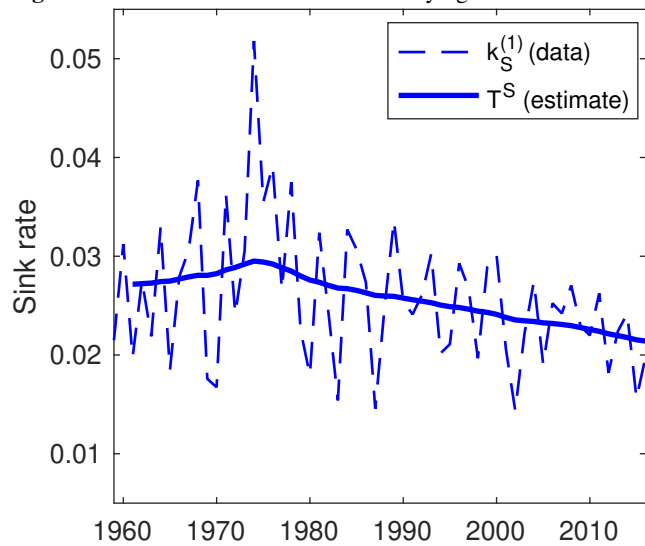
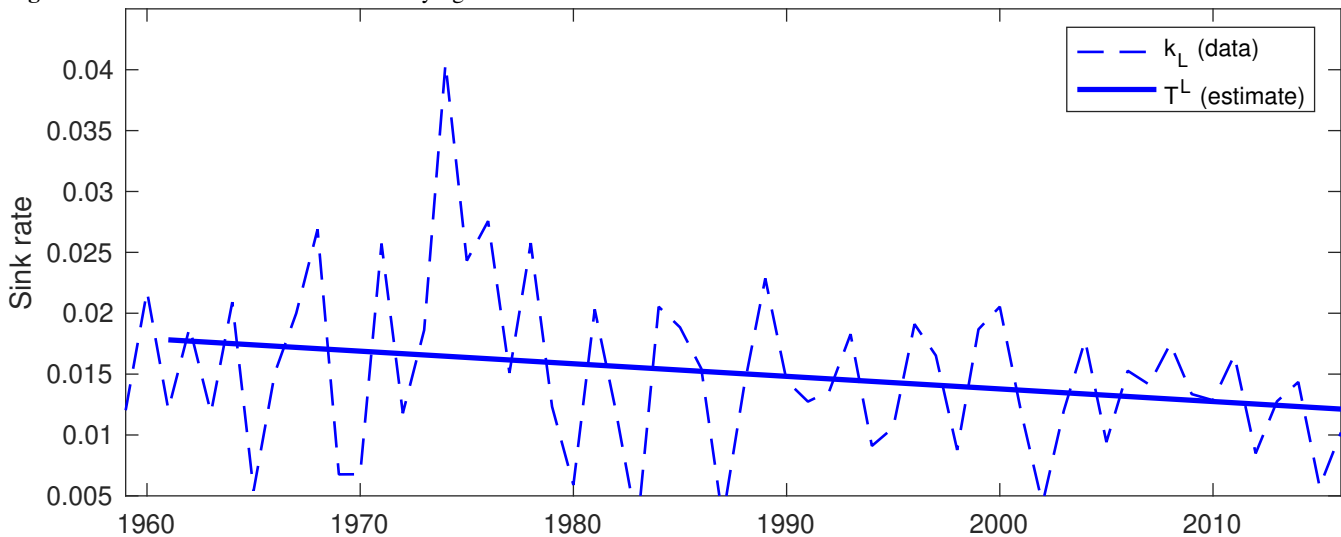


Figure 3. Univariate estimation of time-varying trend for land sink.



To investigate the robustness of the statistical findings of the main paper, we here examine whether there are observations that are particularly influential on the analyses. We consider two related approaches. First, we calculate Cook’s distance (Cook, 1977, 1979; Atkinson et al., 1997) for each $t = 1959, 1960, \dots, 2016$, which is a measure of how influential a particular data point is. Second, we estimate the slope parameter β after deleting the t ’th observation from the sample (treating it as a “missing value” in the state-space system) for $t = 1959, 1960, \dots, 2016$. That is, for each year in the sample, we obtain an estimate β_{λ_t} for each $t = 1959, 1960, \dots, 2016$, by treating the t ’th observation as missing and then estimating the slope parameter using the maximum likelihood approach considered in the main paper.

Figures 4 and 5 present these analyses for the airborne fraction, while Figures 6 and 7 present the analogous results for the sink rate. From these figures, it is clear that one observation, namely the one at $t = 1974$, stands out: it has by far the largest Cook’s distance for both the airborne fraction and the sink rate data (Figures 4 and 6, respectively). It also results in the most extreme slope parameter estimates (Figures 5 and 7, respectively). However, even this observation at $t = 1974$ seems to have only a minor influence on the analysis: indeed, the estimate of $\beta_{\lambda_{1974}}$ is well within the confidence bands (dashed lines) of the full sample estimate for both the airborne fraction data (Figure 5) and for the sink rate data (Figure 7). Similarly, while the Cook’s distance for this data point is high relative to the other points, it is far below conventional rule-of-thumb thresholds such as 0.50 or 1.00, which are often used in applied analyses.

Figure 4. Cook's distance of each observation from the state-space model of the airborne fraction.

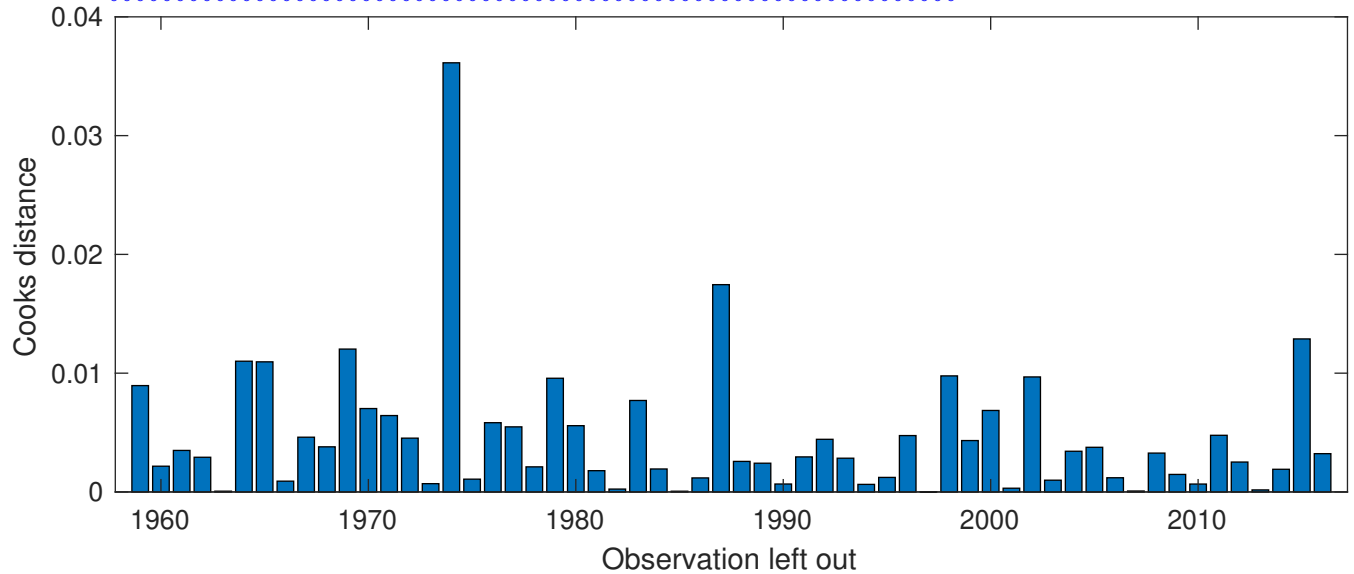


Figure 5. Estimates of slope parameter β from the state-space model of the airborne fraction after leaving out one observation. Dashed lines are 95% confidence bands for the full sample estimate.

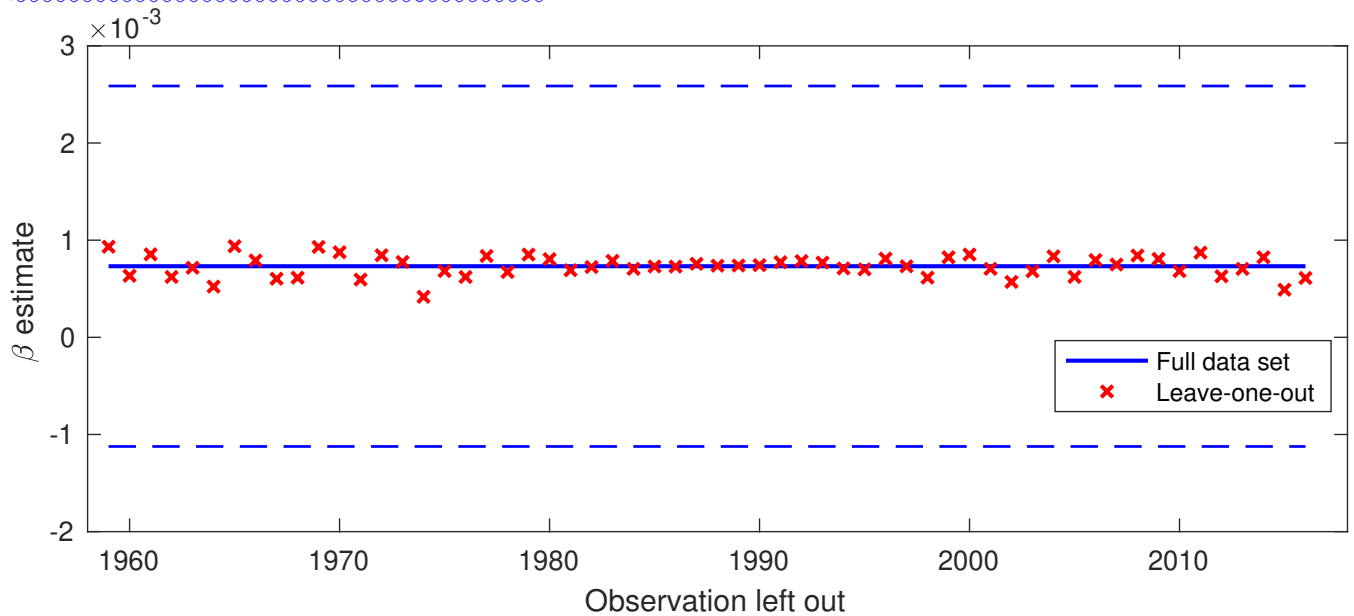


Figure 6. Cook's distance of each observation from the state-space model of the sink rate.

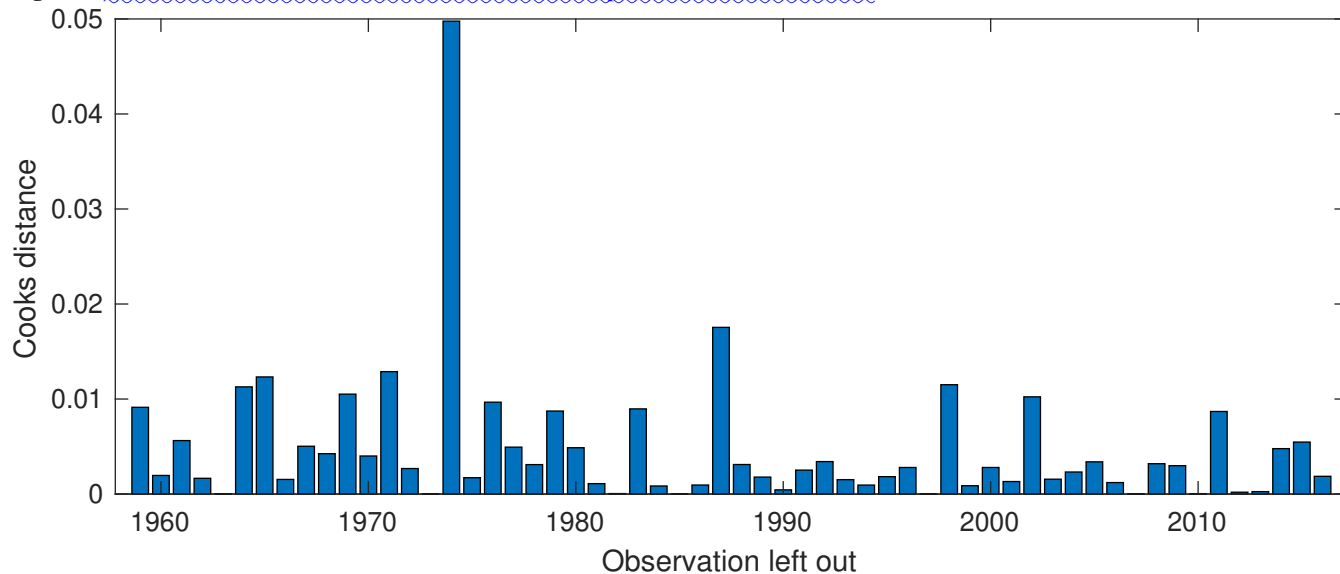
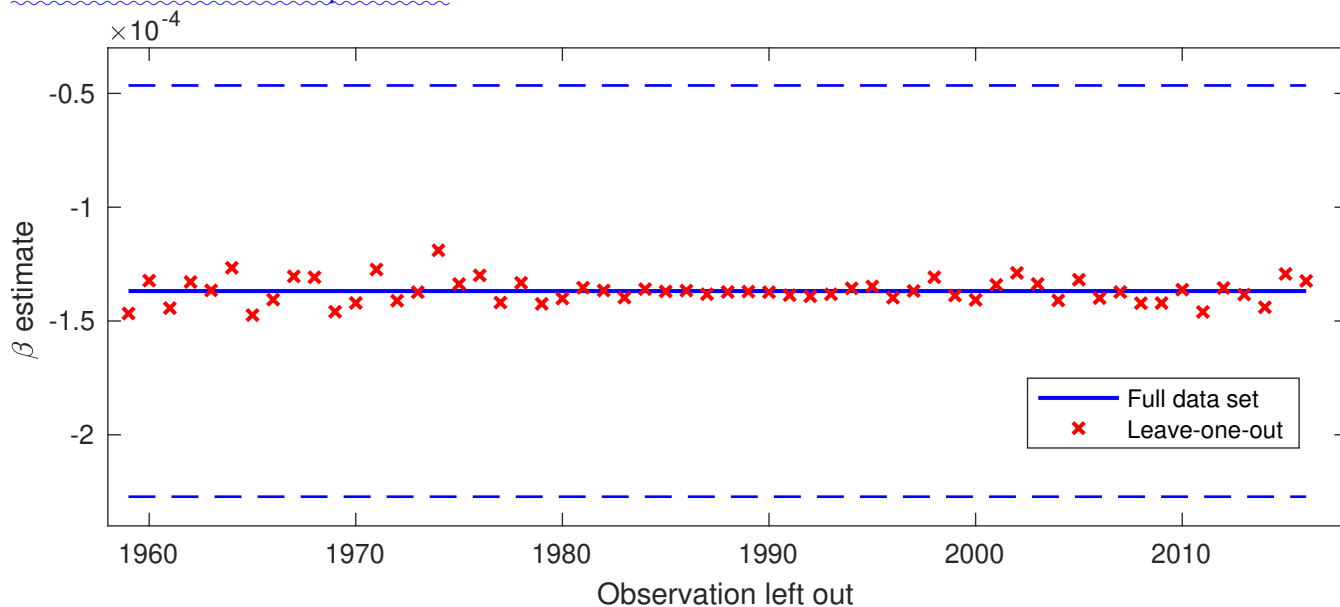


Figure 7. Estimates of slope parameter β from the state-space model of the sink rate after leaving out one observation. Dashed lines are 95% confidence bands for the full sample estimate.



3 Analysis with 5-year averages

To remove possible influences of transitory events (e.g., ENSO and/or volcanic eruptions) on our analyses, we here re-do the analysis from the main paper, now with data averaged over 5 year periods.¹ We also averaged the data over 2, 3, and 4 years and found similar results to what we report below. For brevity, the results from using 2-4 year averages are not presented. They are available upon request.

We consider two ways of averaging the data: (i) Running averages, which results in overlapping “windows” of data, and (ii) non-overlapping averages. The former is considered in Section 3.1 and the latter in Section 3.2.

3.1 Running averages

Recall that the data of the original paper runs from $t = 1959$ to $t = 2016$, resulting in 58 observations. We now study the data after they have been averaged over a 5-year period using a running window. That is, if the original data are x_t , we consider the averaged data

$$\tilde{x}_t^{(m)} = \frac{1}{m} \sum_{i=1}^m x_{t-i+1}, \quad t = 1958 + m, 1959 + m, \dots, 2016,$$

where $m \geq 1$ is the number of observations used in constructing the averages. For instance, if $m = 5$, we get the 5-year averages

$$\tilde{x}_t^{(5)} = \frac{1}{5} \sum_{i=1}^5 x_{t-i+1}, \quad t = 1963, 1968, \dots, 2016,$$

resulting in $58 - 4 = 54$ observations.

As remarked in the Discussion section of the main paper, such averaging can, unfortunately, make the error structure of the data quite complicated. We illustrate how this can happen with a toy example: Suppose that the original data are “signal plus noise”:

$$x_t = x_t^* + \xi_t,$$

where x_t^* is the true (unobserved) value for the underlying data and ξ_t is an iid measurement error term. Let $m \geq 2$ and consider the averaged data

$$\tilde{x}_t^{(m)} = \frac{1}{m} \sum_{i=1}^m x_{t-i+1} = \tilde{x}_t^* + \tilde{\xi}_t,$$

where

$$\tilde{x}_t^* = \frac{1}{m} \sum_{i=1}^m x_{t-i+1}^*, \quad \tilde{\xi}_t = \frac{1}{m} \sum_{i=1}^m \xi_{t-i+1},$$

are the averaged signal and an error term, respectively. It is clear that the error term $\tilde{\xi}_t$ is now serially correlated, which can invalidate the analysis if the researcher does not take it into account.

¹We thank an anonymous referee for suggesting this.

With the above caveat in place, we analyse the 5-year averaged airborne fraction (AF) and sink rate (SR) data using a trend model specification, as explained in Section 3 of the main paper.² The results are shown in Tables 1 and 2 for the airborne fraction and Tables 3 and 4 for the sink rate. From the tables, we see that the diagnostics are quite bad, indicating that the proposed model is not able to fit the data well. In particular, we find evidence of positive serial correlation ($DW < 2$) in the prediction errors, as we would expect from the discussion of the error structure above.

We conclude that if one wants to analyse the running averages data, another approach than the one considered here is necessary. In particular, it is important to choose an approach that can take into account the error structure induced by the averaging. However, constructing such an alternative approach is outside the scope of this note. Instead, we propose to average the data using non-overlapping windows, thereby hopefully alleviating the serial correlation in the errors. The following section presents the results from this approach.

Table 1. Univariate analysis of the airborne fraction

	Parameter estimates					Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t-stat($\hat{\beta}$)	N	R_d^2	DW
$AF_t^{(1)}$	0	0.0447	0.00223	0.00584	0.38270	0.3387	-0.0616	1.6657
$AF_t^{(2)}$	0	0.0444	0.00055	0.00610	0.08987	1.0360	-0.0711	1.8195

Data: 5-year running average AF. See Table 1 in the main paper for the analogous analysis on the original data.

Table 2. Multivariate analysis of the airborne fraction

	Parameter estimates					Correlation matrix (ϵ)		Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t-stat($\hat{\beta}$)	$AF^{(1)}$	$AF^{(2)}$	N	R_d^2	DW
Panel A: Two individual trends as in Eq. (12) of the main paper.										
$AF^{(1)}$	0	0.0425	0.00223	0.00584	0.38270	1.0000	0.9999	0.3387	-0.0616	1.6657
$AF^{(2)}$	0	0.0444	0.00055	0.00610	0.08987	0.9999	1.0000	1.0360	-0.0711	1.8195
Panel B: One common trend as in Eq. (13) of the main paper.										
$AF^{(1)}$	0.0359	0.0393	0.00149	0.00540	0.27679	1.0000	-1.0000	3.6409	-0.6278	1.1458
$AF^{(2)}$	0.0459	–	–	–	–	-1.0000	1.0000	0.8089	-0.9646	0.9314

Data: 5-year running average AF. See Table 2 in the main paper for the analogous analysis on the original data.

²We perform the averaging directly on the global carbon budget data, i.e., on E_t^{ANT} , G_t , S_t^O , S_t^L , and C_t , and then construct the AF and SR data as explained in Section 2 of the main paper. We also experimented with first constructing the AF and SR data and then averaging these. The results of the two approaches were very similar so we only present the results of the former.

Table 3. Univariate analysis of the sink rate

	Parameter estimates					Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t-stat($\hat{\beta}$)	N	R_d^2	DW
$k_S^{(1)}$	0	0.0022	-0.00008	0.00030	-0.27290	4.3025	-0.0710	1.7625
$k_S^{(2)}$	0	0.0020	-0.00017	0.00027	-0.63234	0.0726	-0.0637	1.7127

Data: 5-year running average SR. See Table 3 in the main paper for the analogous analysis on the original data.

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	Parameter estimates					Correlation matrix (ϵ)		Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t-stat($\hat{\beta}$)	$AF^{(1)}$	$AF^{(2)}$	N	R_d^2	DW
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$k_S^{(2)}$	0	0.0020	-0.00017	0.00027	-0.63235	1.0000	1.0000	0.0726	-0.0637	1.7127
Panel B: One common trend as in Eq. (15) of the main paper.										
$k_S^{(1)}$	0.0024	0.0019	-0.00014	0.00026	-0.53638	1.0000	-1.0000	0.6056	-0.9981	0.8756
$k_S^{(2)}$	0.0015	–	–	–	–	-1.0000	1.0000	5.6559	-0.6044	1.1971

Data: 5-year running average SR. See Table 4 in the main paper for the analogous analysis on the original data.

3.2 Non-overlapping averages

We here consider averaged data, but where the averaging is done using non-overlapping windows. That is, if x_t is again the original data series, we define

$$5 \quad \hat{x}_t^{(m)} = \frac{1}{m} \sum_{i=1}^m x_{t-i+1}, \quad t = 1958 + m, 1958 + 2m, \dots, 2016,$$

i.e., we divide the data into bins (“windows”) of size m and then take the average in each bin.³

The advantage of this approach to averaging the data is, as discussed above, that we expect the errors to be more nicely behaved. In particular, we do not expect them to be as serially correlated in this case. The downside of the approach is of course that we will have fewer observations available for the subsequent statistical analysis. For instance, in the case of 5-year averages that we consider here, each averaged data series consists of only 12 observations.

The results are shown in Tables 5 and 6 for the airborne fraction and Tables 7 and 8 for the sink rate. From the tables, we see, as expected, that the diagnostics are better than what was seen in the case of overlapping averaging windows. Interestingly, the

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- 5 Figures 8 and 9 show the trend estimates of the airborne fraction and sink rate data, respectively, in the case of averaged data using non-overlapping windows.

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	Parameter estimates					Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t -stat($\hat{\beta}$)	N	R_d^2	DW
$AF_t^{(1)}$	0.0574	0.0067	0.00517	0.00523	0.98975	0.3594	0.3465	2.0985
$AF_t^{(2)}$	0.0481	0.0450	0.00083	0.01449	0.05721	0.1227	0.1018	2.0714

Data: 5-year non-overlapping average AF. See Table 1 in the main paper for the analogous analysis on the original data.

Table 6. Multivariate analysis of the airborne fraction

	Parameter estimates					Correlation matrix (ϵ)		Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t -stat($\hat{\beta}$)	$AF^{(1)}$	$AF^{(2)}$	N	R_d^2	DW
Panel A: Two individual trends as in Eq. (12) of the main paper.										
$AF^{(1)}$	0.0473	0.0335	0.00538	0.01087	0.49443	1.0000	0.9456	0.7162	0.4872	2.5460
$AF^{(2)}$	0.0394	0.0541	0.00122	0.01666	0.07344	0.9456	1.0000	0.3027	0.0821	2.3698
Panel B: One common trend as in Eq. (13) of the main paper.										
$AF^{(1)}$	0.0535	0	0.00361	0.00364	0.99164	1.0000	0.1975	0.4802	0.3698	2.2944
$AF^{(2)}$	0.0596	–	–	–	–	0.1975	1.0000	0.7454	0.5965	2.6334

Data: 5-year non-overlapping average AF. See Table 2 in the main paper for the analogous analysis on the original data.

Table 7. Univariate analysis of the sink rate

	Parameter estimates					Diagnostics		
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t -stat($\hat{\beta}$)	N	R_d^2	DW
$k_S^{(1)}$	0.0023	0.0029	-0.00037	0.00091	-0.40483	0.1374	-0.0147	2.0028
$k_S^{(2)}$	0.0026	0.0011	-0.00073	0.00041	-1.78102	0.0770	0.2431	2.0450

Data: 5-year non-overlapping average SR. See Table 3 in the main paper for the analogous analysis on the original data.

Table 8. Multivariate analysis of the sink rate

	Parameter estimates					Correlation matrix (ϵ)		Diagnostics		
Panel A: Two individual trends as in Eq. (14) of the main paper.										
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t-stat($\hat{\beta}$)	$AF^{(1)}$	$AF^{(2)}$	N	R_d^2	DW
$k_S^{(1)}$	0.0023	0.0029	-0.00052	0.00088	-0.58373	1.0000	1.0000	0.7418	-0.0204	2.0524
$k_S^{(2)}$	0.0025	0.0015	-0.00078	0.00049	-1.57493	1.0000	1.0000	0.0552	0.4228	2.2251
Panel B: One common trend as in Eq. (15) of the main paper.										
	$\hat{\sigma}_\epsilon$	$\hat{\sigma}_\eta$	$\hat{\beta}$	s.e.($\hat{\beta}$)	t-stat($\hat{\beta}$)	$AF^{(1)}$	$AF^{(2)}$	N	R_d^2	DW
$k_S^{(1)}$	0.0032	0	-0.00068	0.00020	-3.41506	1.0000	0.3340	0.1292	0.6888	2.9392
$k_S^{(2)}$	0.0027	-	-	-	-	0.3340	1.0000	1.0816	0.1869	1.8314

Data: 5-year non-overlapping average SR. See Table 4 in the main paper for the analogous analysis on the original data.

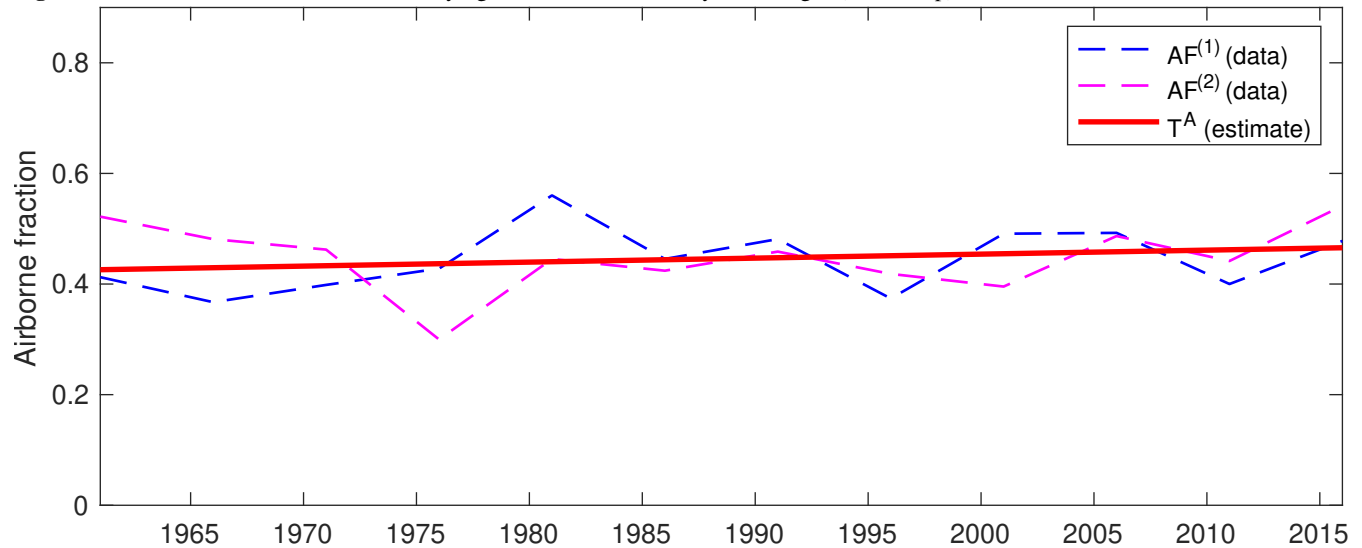
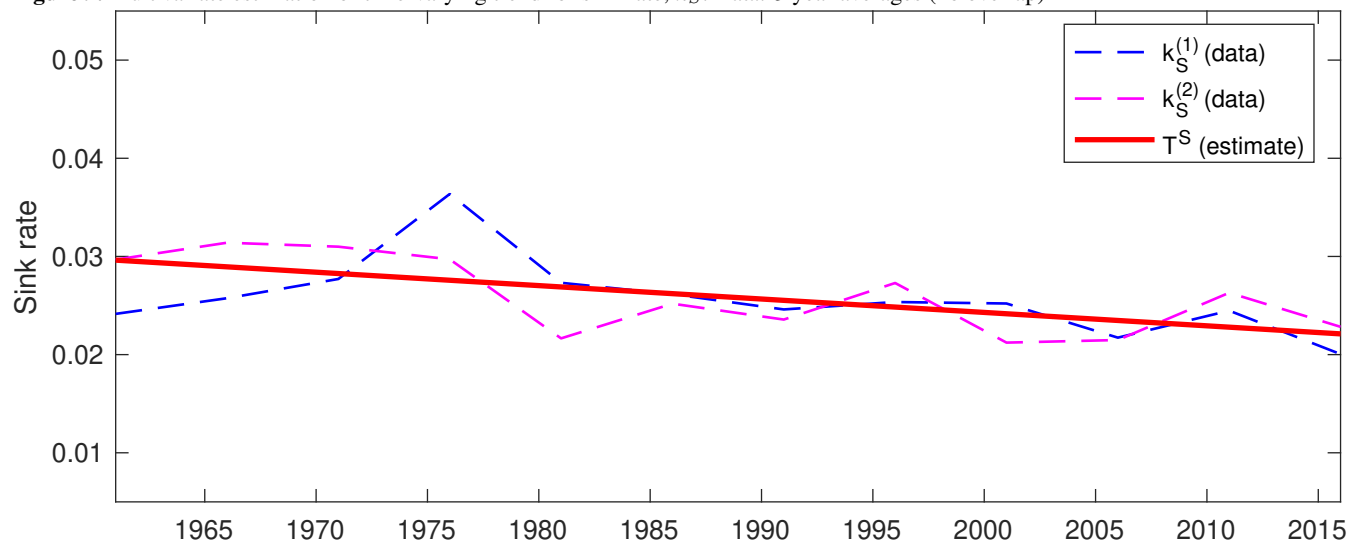
Figure 8. Multivariate estimation of time-varying trend for AF. Data: 5-year averages (no overlap)

Figure 9. Multivariate estimation of time-varying trend for sink rate, k_S . Data: 5-year averages (no overlap)



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- 5 Cook, R. D.: Detection of influential observations in linear regression, *Technometrics*, 19, 15–18, 1977.
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Trend analysis of the airborne fraction and sink rate of anthropogenically released CO₂

Author response, Review 2

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1 Introduction

We thank the Referee for the constructive comments on the first revision of our paper. Our replies are given below. For each item, we reproduce (a slightly paraphrased version of) the comments of the Referee, followed by our response in which we indicate how and where the paper has changed. All quoted page and line numbers (“PX, LY”) refer to the newly revised version of the paper, with the changes tracked.

2 Referee report

2.1 Comment 1

First, a state-space regression using the full-year time-series need to be adressed using a Cook’s distance to see how far the slope of the fit will be affected by the data sampling.

10 2.2 Response to Comment 1

We have carried out the analysis as suggested by the Referee. The analysis for detecting potential influential data points has been conducted by (1) calculating Cook’s distance on the basis of sequentially leaving one observation out from the sample, and (2) estimating the slope parameter β on the same basis, by sequentially excluding the t -th observation from the full sample, for $t = 1959, 1960, \dots, 2016$. We may conclude from this two-fold analysis that none of the observations are especially influential: indeed, while Cook’s distance for the observation at $t = 1974$ is relatively much larger when compared to all $t \neq 1974$, it is still small in absolute terms. Similarly, the estimates of β obtained from leaving out the t ’th observation are very stable, also for $t = 1974$, and are in all instances well inside the 95% confidence bands of the full sample estimate.

The details of these investigations are included at the end of this Response, in Figures 1–4. For completeness, we also have included this graphical output in Sect. 2.1 of the Supplementary Material file. The conclusion from these analyses (as indicated above) are mentioned in the Discussion section of the main paper (P14, L26).

2.2.1 Changes made to the paper in response

- 5 We have included the two analyses as indicated by (1) and (2) above: Cook’s distance measures and slope parameter β estimates in Sect. 2.1 of the Supplementary Material file. We discuss the results of these analyses (along the lines as given above) in the Discussion section of the main paper (P14, L26).

2.3 Comment 2

10 *Then, futher discussion are needed to compare trends in air-borne fraction of CO2 and in carbon sink to know/best estimates of year-to-year variability (and infered/assumed decadal variability). I mean: while your model detect a significant changes in sink rate, can we detect it in the real world given the amplitude of the year-to-decadal variability ? (please refer to the published scientific literature where possible)*

In a situation where it doesn't, futher comparison with Gloor et al findings seems necessary.

2.4 Response to Comment 2

- 15 We have extended our discussions of the estimated trends in the airborne fraction of CO2 and in the carbon sink (P14 and P15, cf. our comments below).

Our point of departure is precisely the fact that it is rather challenging to determine whether a trend is present due to the relatively large year-to-year variability.

- 20 We ask the questions whether a trend is present, whether it is deterministic (linear) or stochastic (random walk) and what the degree of measurement noise is. Our model thus resolves the high degree of year-to-year variability and allows to distinguish non-stationary processes (trend-stationary or difference-stationary) from stationary processes.

We have adopted the local linear trend model, since this basic time series model can encompass and resolve these different processes. As an additional benefit, even when the year-to-year variability in the airborne fraction and in the carbon sink originate from different processes, we have a common modeling structure.

- 25 Because year-to-year variability is high and a stochastic trend with its own source of randomness over and above the stationary measurement noise may cloud the picture further, it is desirable to use as much data as possible to detect a latent trend. It is another advantage of our model, in equation (15), that it allows to accommodate multiple data sources for the same object of interest, here the sink rate that is alternatively measured by (1) data generated from ocean and land sink models, and (2) from emission and atmospheric concentration data. Our reported estimates of the slope parameter β are thus directly supported from
30 two different ways to compute the sink rate.

In the case of the carbon sink rate and a single common trend for the two alternative measurements, equation (15) reduces very closely to a standard linear trend regression estimate, since the maximum likelihood estimate of the variance in the stochastic trend component is almost zero. In this case, the slope parameter β is directly estimated from the year-to-year variation in the two different time series. Hence this result is close to the one from a standard trend regression, albeit with support from two different time series.

We believe that the reported results in our paper support the point, put forth in Gloor et al., that the behavior of the airborne fraction and the sink rate are NOT in a one-to-one correspondence. (Specifically, the point made in Gloor et al. is that findings of an increasing airborne does not necessarily imply that the sink rate is declining.) We now emphasize this more in the Discussion section (P14, L11-13 and P14, L33 – P15, L3). Note, however, that our findings also support those made by Le Quere et al., namely that the sink rate does, in fact, appear to be decreasing.

2.4.1 Changes made to the paper in response

The Discussion section (P14, L11-13 and P14, L33 – P15, L3) has been updated as noted above.

2.5 Comment 3

Finally, regarding the model forecast: how does your model compare to a simple persistence fit (based on a first-order regression processes)?

I would like to stress that further discussion could be usefull in regards of the model forecast: Does your model give an idea of a possible emergence of the climate change signal from the year-to-year variability ? This would help to liase this work with the published literature on climate-carbon cycle feedbacks.

2.6 Response to Comment 3

In the forecasting exercise, we now include the forecasts from a first-order autoregressive process (AR1).

The model results of the paper imply that the sink rate is linearly decreasing in time; the forecasting exercise illustrates how the sink rate will develop in the future under the assumption of the model. For instance, if the model is correct, in approximately 15 years, the sink rate will have declined below 2% (P10, L16). This has important implications for our understanding of the carbon-cycle: it indicates that the ability of the sinks to soak up CO₂ is decreasing, in relative terms. However, our main point is not that the sink rate will necessarily be declining with the same linear rate in the future. Our main point is that the sink rate *has been decreasing over the time period considered in the paper*. The purpose of the forecasting exercise conducted in the paper is mainly for diagnostic purposes: Does the forecasts from the model look reasonable? How can we expect the future sink rate to develop, if the model continues to be a good representation of the underlying physical processes? As such, the forecasts should not be seen as a bona fide prediction, but only as an indication of what we can expect of the sink rate, as long as it is approximately linear in concentrations (an assumption which seems to hold in the time period considered in the paper, but which might be violated in the future, cf. Appendix A in the main paper).

2.6.1 Changes made to the paper in response

Forecasts from an AR1 model is included in Fig. 3 (P12); some comments on this are included on P11 (L4-8).

A discussion of the forecasts and their limitations has been included in the main paper (P11, L9-15).

3 Additional changes

- 5 1. The description of the terms from Global Carbon Budget has been revised (P3).

References

Figure 1. Cook's distance of each observation from the state-space model of the airborne fraction.

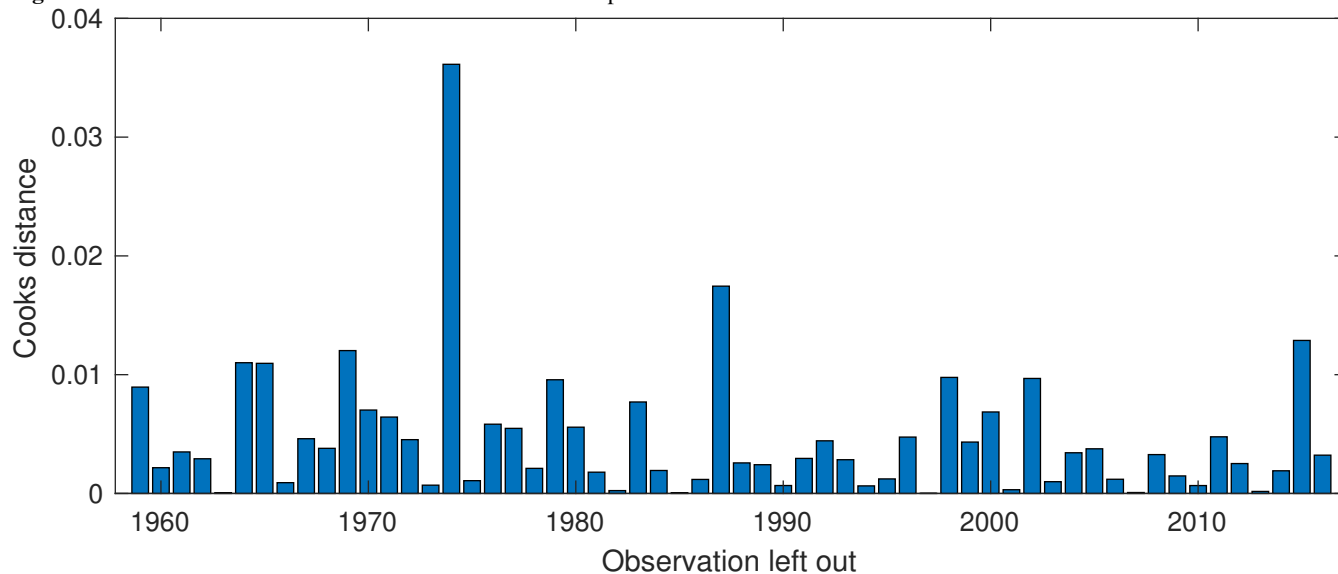


Figure 2. Estimates of slope parameter β from the state-space model of the airborne fraction after leaving out one observation. Dashed lines are 95% confidence bands for the full sample estimate.

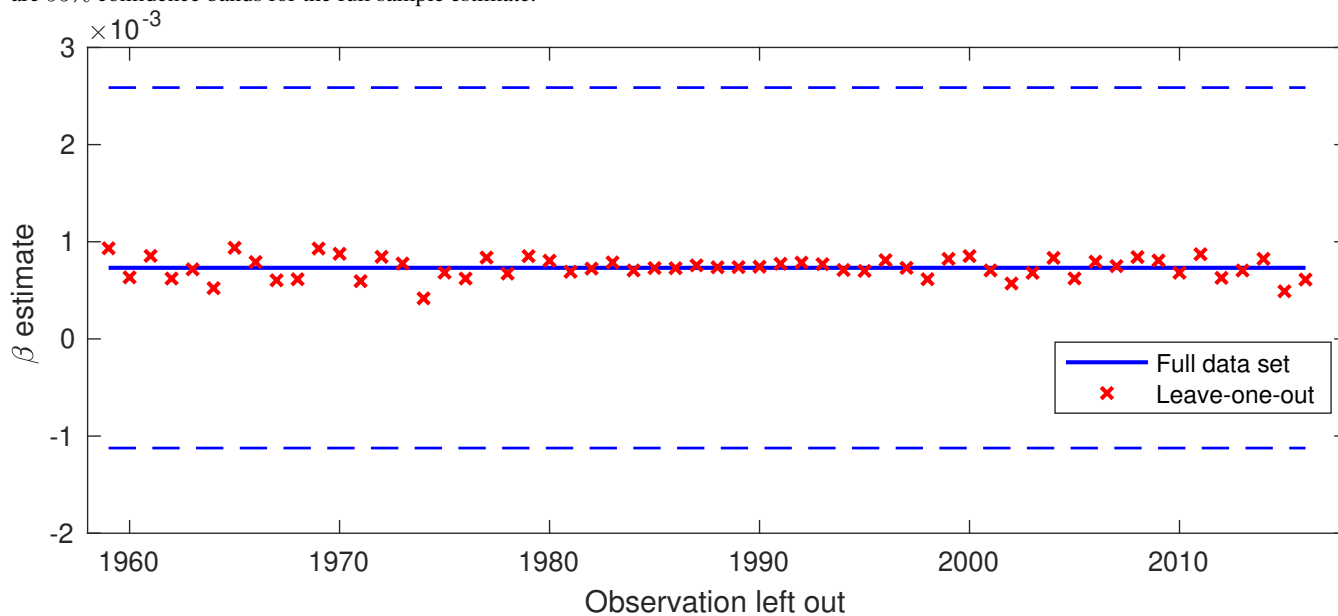


Figure 3. Cook's distance of each observation from the state-space model of the sink rate.

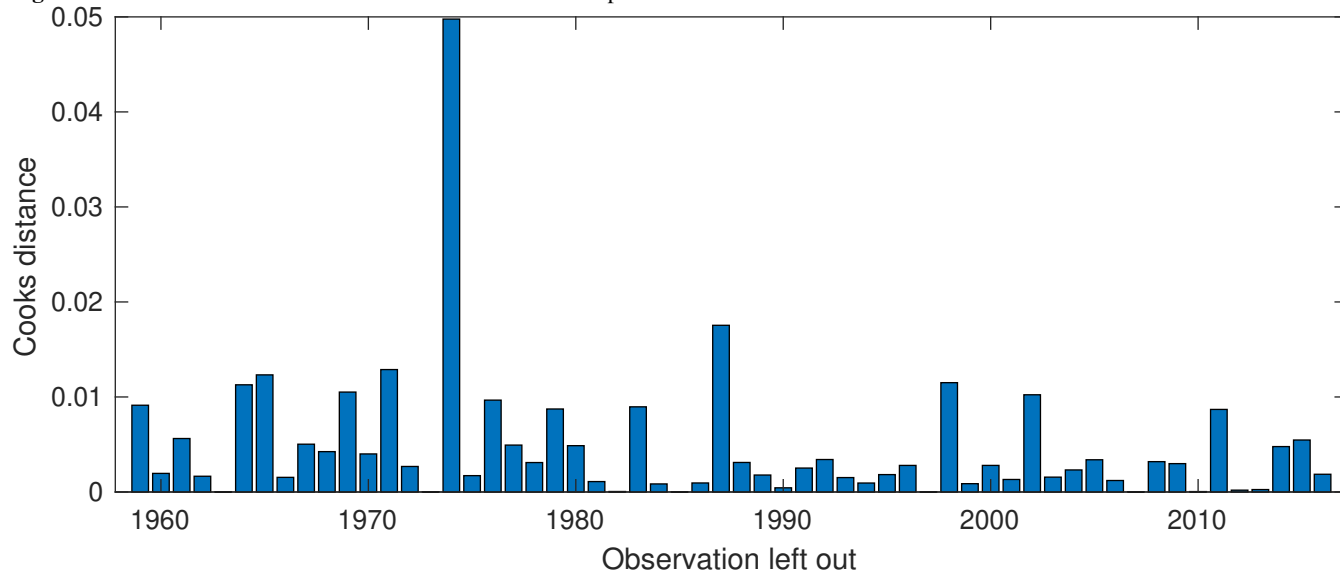


Figure 4. Estimates of slope parameter β from the state-space model of the sink rate after leaving out one observation. Dashed lines are 95% confidence bands for the full sample estimate.

